

DATA SET CATALOG # 115

060-5 Fluxgate Magnetometer
6 tapes

68-014A-14B

68-014A-14E

68-014A-14F

60 SECOND Avg.

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1. INTRODUCTION:

The documentation for this data set was originally on paper, kept in NSSDC's Data Set Catalogs (DSCs). The paper documentation in the Data Set Catalogs have been made into digital images, and then collected into a single PDF file for each Data Set Catalog. The inventory information in these DSCs is current as of July 1, 2004. This inventory information is now no longer maintained in the DSCs, but is now managed in the inventory part of the NSSDC information system. The information existing in the DSCs is now not needed for locating the data files, but we did not remove that inventory information.

The offline tape datasets have now been migrated from the original magnetic tape to Archival Information Packages (AIP's).

A prior restoration may have been done on data sets, if a requestor of this data set has questions; they should send an inquiry to the request office to see if additional information exists.

2. ERRATA/CHANGE LOG:

NOTE: Changes are made in a text box, and will show up that way when displayed on screen with a PDF reader.

When printing, special settings may be required to make the text box appear on the printed output.

Version	Date	Person	Page	Description of Change
01				
02				

3 LINKS TO RELEVANT INFORMATION IN THE ONLINE NSSDC INFORMATION SYSTEM:

<http://nssdc.gsfc.nasa.gov/nmc/>

[NOTE: This link will take you to the main page of the NSSDC Master Catalog. There you will be able to perform searches to find additional information]

4. CATALOG MATERIALS:

- a. Associated Documents To find associated documents you will need to know the document ID number and then click here.
<http://nssdcftp.gsfc.nasa.gov/miscellaneous/documents/>

- b. Core Catalog Materials

OGO 5

FLUXGATE MAGNETOMETER

68-014A-14B

THIS DATA SET HAS BEEN RESTORED. THERE WERE ORIGINALLY 14 7-TRACK, 800 BPI TAPES, WRITTEN IN BINARY WITH STANDARD LABELS. THERE IS ONE RESTORED TAPE, THE RESTORED TAPE IS UNLABELED. THE DR TAPE IS A 3480 CARTRIDGE AND THE DS TAPE IS A 9-TRACK, 6250 BPI. THE TAPES WERE CREATED ON AN IBM 360 COMPUTER. THE DR AND DS NUMBERS ALONG WITH THE CORRESPONDING D NUMBERS AND TIME SPANS ARE AS FOLLOWS:

DR#	DS#	DD#	FILES	TIME SPAN
DR02621	DS02621	D06008	1-5	03/05/68 - 03/17/68
		D06009	6-10	03/17/68 - 03/30/68
		D06165	11-15	03/30/68 - 04/12/68
		D06166	16-20	04/12/68 - 04/25/68
		D06373	21-25	05/13/68 - 05/26/68
		D06860	26-30	05/21/68 - 06/03/68
		D06372	31-35	05/26/68 - 06/12/68
		D06859	36-40	06/03/68 - 06/16/68
		D08047	41-45	06/17/68 - 06/30/68
		D08048	46-50	06/30/68 - 07/13/68
		D08045	51-55	07/13/68 - 07/26/68
		D08046	56-60	07/26/68 - 08/08/68
		D08829	61-65	08/06/68 - 08/17/68
		D08830	66-70	08/19/68 - 09/01/68

OGO 5

4.608 SECOND AVERAGE B FIELD

68-014A-14C

THIS DATA SET HAS BEEN RESTORED. ORIGINALLY THERE WERE FIVE 9-TRACK, 1600 BPI TAPES WRITTEN IN BINARY. THERE ARE TWO RESTORED TAPES. THE DR TAPES ARE 3480 CARTRIDGES AND THE DS TAPES ARE 9-TRACK, 6250 BPI. THE ORIGINAL TAPES WERE CREATED ON AN IBM 360 COMPUTER AND WERE RESTORED ON AN IBM 9021 COMPUTER. THE DR AND DS NUMBERS ALONG WITH THE CORRESPONDING D NUMBERS AND TIME SPANS ARE AS FOLLOWS:

DR#	DS#	D#	FILES	TIME SPAN
DR002632	DS002632	D029194	1-25	03/05/68 - 05/08/68
		D029195	26-50	05/08/68 - 07/12/68
DR002631	DS002631	D029196	1-25	07/12/68 - 09/14/68
		D029248	26-50	09/14/68 - 11/18/68
		D029249	51-70	11/18/68 - 01/10/69

OGO 5

FLUXGATE MAGNETOMETER

68-014A-14E

THIS DATA SET HAS BEEN RESTORED. THERE WERE ORIGINALLY 14 7-TRACK, 800 BPI TAPES, WRITTEN IN BINARY WITH STANDARD LABELS. THERE ARE 3 RESTORED TAPES. THE RESTORED TAPES ARE UN-LABELED. THE DR TAPES ARE 3480 CARTRIDGES AND THE DS TAPES ARE 9-TRACK, 6250 BPI. THE ORIGINAL TAPES WERE CREATED ON AN IBM 360 COMPUTER. THE DR AND DS NUMBERS ALONG WITH THE CORRESPONDING D NUMBERS AND TIME SPANS ARE AS FOLLOWS:

DR#	DS#	D#	FILES	TIME SPAN
DR002636	DS002636	D005575	1-5	03/05/68 - 03/17/68
		D004813	6-10	03/17/68 - 03/30/68
		D006163	11-15	03/30/68 - 04/12/68
		D006164	16-20	04/12/68 - 04/25/68
		D006371	21-25	05/13/68 - 05/26/68
DR002637	DS002637	D006861	1-5	05/21/68 - 06/03/68
		D006370	6-10	05/26/68 - 06/12/68
		D006862	11-15	06/03/68 - 06/16/68
		D008052	16-20	06/17/68 - 06/30/68
		D008051	21-25	06/30/68 - 07/13/68
DR002638	DS002638	D008049	1-5	07/13/68 - 07/26/68
		D008050	6-10	07/26/68 - 08/08/68
		D008833	11-15	08/06/68 - 08/19/68
		D008834	16-20	08/19/68 - 09/01/68

OGÓ 5

1-MIN. AVG. B-FIELD, GSM COORD.

68-014A-14F

This data set has been restored. There were originally 15 7-track, 800 BPI tapes, written in Binary with standard labels. There is one restored tape. The restored tape is unlabeled. The DR tape is a 3480 cartridge and the DS tape is 9-track, 6250 BPI. The tapes were created on an IBM 360 computer and were restored on an IBM 3081 computer. The DR and DS number along with the corresponding D numbers and time spans are as follows:

DR#	DS#	D#	FILES	TIME SPAN
DR002775	DS002775	D004814	1-5	03/05/68 - 03/17/68
		D006007	6-10	03/17/68 - 03/30/68
		D006161	11-15	03/30/68 - 04/12/68
		D006162	16-20	04/12/68 - 04/25/68
		D006369	21-25	05/13/68 - 05/26/68
		D006863	26-30	05/21/68 - 06/03/68
		D006368	31-35	05/26/68 - 06/09/68
		D006864	36-40	06/03/68 - 06/16/68
		D008055	41-45	06/17/68 - 06/30/68
		D008056	46-50	06/30/68 - 07/13/68
		D008053	51-55	07/13/68 - 07/26/68
		D008054	56-60	07/26/68 - 08/08/68
		D008835	61-65	08/06/68 - 08/19/68
		D008836	66-70	08/19/68 - 09/01/68
		D029053	71	03/05/68 - 05/05/70

68-014A-14B

OGO-5

FLUXGATE MAGNETOMETER

60 SECOND AVERAGES

This data set consists of 6, 800 BPI, Binary tapes produced on the IEM/360, where the 'D' tapes are 9 track and the 'C' tapes are 7 track.

These six tapes are known as the Spacecraft Coordinate tapes. They are blocked 128 logical records per physical record.

Each tape has 15 files on it, 5 main files and a header and trailer file for each main file.

<u>D#</u>	<u>C#</u>	<u>START</u>	<u>STOP</u>
D-06008	C-04928	3/05/68	3/17/68
D-06009	C-04929	3/17/68	3/30/68
D-06165	C-05114	3/30/68	4/12/68
D-06166	C-05115	4/12/68	4/25/68
D-06372	C-05198	5/26/68	6/12/68
D-06373	C-05199	5/13/68 4/25/68	5/26/68 5/8/68

ATTACHED LETTER SENT TO:

Mr. Bruno Aparicio

Mr. Michel Aubry

Mr. J. N. Barfield

Dr. J. R. Barrows

Dr. Jih-Kwin Chao

Dr. V. P. Golovkov

Mr. Paul Lane

Dr. J. Munch

Mr. Alfredo Navato

Dr. Chris T. Russell

Dr. V. A. Troitskaya

Dr. Johannes Wihjelm

Dr. Bruce Boller

Dr. Keith Ogilvie

Dr. Vithalbai L. Patel

Dr. Willard P. Olson

Dr. Lothar Rossberg

Dr. Ferdinand F. Cap

Mrs. Marcia M. Neugebauer

Dr. Harry I. West, Jr.

Dr. A. Nishida

Dr. James L. Burch

Dr. Raymond G. D'Arcy, Jr.

Dr. Frederick L. Scarf



NATIONAL AERONAUTICS AND SPACE ADMINISTRATION
GODDARD SPACE FLIGHT CENTER
GREENBELT, MARYLAND 20771

NATIONAL SPACE SCIENCE DATA CENTER
CODE 601

TELEPHONE
301-982-6095

March 28, 1973

Dear Colleague:

The National Space Science Data Center (NSSDC) has just received the attached letter from the Coleman group at UCLA informing us of a possible offset problem in some of the early OGO 5 magnetometer data. We are forwarding it to you in this manner so that you may be informed of possible problems relating to certain potential uses of the data.

NSSDC will transmit further information regarding these data as soon as it becomes available. We suggest that, at this stage of our understanding of the potential problem, if you plan to use the early OGO 5 data, you contact me at (301-982-5783) or Dr. Christopher T. Russell at UCLA (213-825-3188).

Sincerely,

Donald J. Hei, Jr.
Acquisition and Analysis Branch

DJ:fn

Attachment:
UCLA Letter

MEMO

To: Users of UCLA OGO-5 fluxgate magnetometer data
From: C.T. Russell
Subject: Absolute accuracy of data on NSSDC tapes
Date: March 21, 1973

The purpose of this memo is to interject a note of caution in the use of the UCLA OGO-5 fluxgate magnetometer data as an absolute instrument in very low fields. The fluxgate magnetometer flown by the UCLA group has a dynamic range of $\pm 64,000\gamma$ and a precision of $\pm 1/16\gamma$. This precision should not be confused with accuracy. The OGO-5 spacecraft has a set of magnetometers provided by GSFC which are designed for high accuracy. This set includes a rubidium vapor magnetometer with biasing coils and a fluxgate magnetometer with limited dynamic range. It was decided prelaunch to devote the major effort with magnetic cleanliness procedures on this set of magnetometers and intercalibrate the OGO-5 and GSFC data inflight. For this purpose, we were supplied with short stretches of GSFC data (5 minutes) once per orbit for orbits 1-52 and orbit 138 and above.

The initial data were consistent with an offset which changed moderately rapidly just after turn on but which asymptotically settled down by about orbit 25. The data above orbit 138 showed a rather constant offset but these offsets exhibited some temperature dependence. This temperature dependence was then used to determine offsets for orbits 53-138. Then one offset was chosen to represent the offset during the entire orbit and offsets were assumed to change at perigee when the instrument was exposed to a large field and thus exercised its various ladder-adder circuits. The instrument temperatures were not available until after the data were processed and assumptions were frequently made on the expected temperatures from data obtained on nearby orbits and from data obtained one year earlier or one year later.

In March 1971 when we wrote our data processing memo "Production Processing of the Data Obtained by the UCLA OGO-5 Fluxgate Magnetometer", we stated we expected an accuracy of from 1 to 2 gammas per component. All indications were from our experience to that date that such was the case. As processing continued into the second and third year of OGO-5, however, temperatures began to drop and during April-May and October-November 1969 and 1970 we would expect that the offset variations within a particular orbit might exceed 2γ per

Memo
March 21, 1973
Page 2

component. Furthermore, during spin up periods the temperatures dropped markedly causing offset problems.

Last but not least, Marcia Neugebauer and Don Hej have found stretches of OGO-5 data during March and April 1968 which they suspect have offsets exceeding the guidelines. This could be caused by several factors: first, clerical error (at least one case of this has been found); two, temperature variations larger than suspected; three, changes in the long term drift of the offset during the orbit and not just at perigee. Thus, at the present time I urge caution in the use of the OGO-5 UCLA fluxgate magnetometer data for absolute measurements in low fields. Until we can do further tests, I suggest that if accurate field values in low fields are essential to a particular study the GSFC magnetometer be used or that the accuracy of the OGO-5 data be verified by comparison with other spacecraft, or by one or another of the several techniques available for measuring spacecraft offsets from inflight data. (Belcher, 1973; Hedgecock, 1973).

We are very interested in checking the offsets using these techniques ourselves, and plan to do this in the near future. As is true for all experimental groups these days, our budget for such studies is limited. Thus, we do not foresee a study of the OGO-5 offsets for the full three year period. However, we plan to attempt to determine enough offsets that an accurate data base is available for magnetospheric studies and that the degree of variability of the offsets is precisely determined. When this study is complete we will write another memo.

References

- Belcher, J.W., A variation of the Davis-Smith method for inflight determination of spacecraft magnetic fields, submitted to J. Geophys. Res., 1973.
- Hedgecock, P.C., An alternative mathematical technique for the determination of spacecraft magnetometer zero levels, submitted to Journal of Scientific Instruments, 1973.

CTR:pr

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Dr. Frederick L. Scarf

4. The Roadmaps. (One Minute Averages)

a) Data Processing

In generating the Roadmap plots all data is processed and averaged, both real time and playback. This data is then stored on a disk pack by orbit in two data sets one for real time data and one for playback data. Then these two data sets are scanned taking data in time sequence from the real time set until a gap is found in the data. Then playback data is searched to try to fill this gap. When this gap is filled or if it cannot be filled the real time data is again read until the next gap and then the process repeats. The end result is a tape with an orbit's data in time sequence containing averages formed from the highest possible telemetry rate. The data from this tape is then printed and microfilm plotted. There are no missing times on these tapes. When data is not available for a particular time it is flagged with a value of 100000.

At the same time, as the Roadmap tape is being created which contains one minute averages, the 4.608 second averages are created. Thus the 4.608 second averages are also in time sequence for one orbit with priority given to the highest telemetry rate data. These tapes are not printed or plotted at UCLA but are sent to H. West at the Lawrence Radiation Laboratory, Livermore, California where they are microfilm plotted. These magnetic tapes are also continuous in time with missing data flagged with values of 100000.

The one minute averages are centered on each minute. The points in this interval are scanned for obvious bad points, the bad points are rejected and the good points are summed and then the total is divided by the number of good points. The number of good points is also saved. We note that this process is performed for each of the three vector components and the total field. The total field calculated is the average of the instantaneous field magnitudes.

In order to retain information on the high frequency end of the spectrum, rms deviations are also calculated for each of the vector components and the total field. We note that the rms deviation of the total field depends somewhat on the accuracy of the offsets used. Thus reliance on the accuracy of the calculation of the rms deviation of the total field should be avoided in low fields. The deviations of the vector components, however, is independent of offset errors.

The rms deviations are not strictly rms deviations in the usual definition of the term, but are actually the rms amplitude of waves in a band of frequencies from 0.07 Hz (15 second period) to the Nyquist frequency which is a function of the telemetry rate. To calculate this amplitude, the input data stream, across averaging intervals, was filtered with a two stage high pass recursive filter. The amplitude response of this filter is shown in figure 4. The output of this filter was squared and summed over each minute and divided by the number of points and then its square root was taken.

We note that this rms deviation is very insensitive to field gradients whereas the usual rms deviation responds readily to field gradients. However, as all deviations it is very sensitive to bad data and sharp spikes in the rms deviations are probably due to telemetry errors.

b) Microfilm Plots in Spacecraft Coordinates

Each microfilm frame contains five hours of data, so that 13 pages are required to plot an orbit. However, we have plotted two frames for each five hour interval: one containing the vector field data and one containing the rms deviation data. Thus there are 26 frames for every orbit. These are numbered in the lower right-hand corner of every plot. (There are two pages 1, two pages 2, etc.). The data corresponding to the first time on the page and the orbit number are plotted in the upper right-hand corner of each page. Also, each page of data in spacecraft coordinates has the heading "Body Coordinates".

The format of the plot of the rms deviations remains fixed throughout the orbit. Figure 2 shows a typical frame of the rms deviation page. The top axis labelled "KBS" indicates the telemetry bit rate. However, since this is derived by counting the number of points in a one minute average it provides more information than just this. If data quality is poor and points have to be discarded, then this quantity will deviate from a straight line. Furthermore, data missing between files on the original data tapes for intervals less than one minute will show

up as a downwards spike on this plot. We note that this quantity is plotted on a log scale.

The next four quantities from top to bottom are the rms deviations B_X , B_Y , B_Z and in the total field. The scale is one gamma per division and is linear. The plots saturate at five gammas. The deviations are usually quite accurate but errors may occur. These usually take the form of isolated spikes. On occasion isolated spikes every 40 minutes can occur. These are caused by incompletely correcting for the calibrate signal or missing it completely. Another possible error is an increase in general noise level due to poor quality data. This can be recognized by the deviation of the bit rate word from a straight line. Although most bad points are rejected from the averages and the rms deviations a few always get through and this raises the power in the fluctuations. Spikes occurring on only one axis or on both the X and Y axes and not the Z axis are especially suspicious, such as the ones at 2000 UT and 2105 UT on figure 2.

Figure 3 shows an rms deviation frame through perigee (Perigee is at 1641 UT). We see that data near perigee can be very noisy. This is not real. From 1500 to 1600 and from 1700 to 1800 we see a general rise and then fall of the noise level. This is due to boom vibrations. The sharp increase (and decreases) near 1600 and the sharp decrease in the deviations near 1700 are caused by the switching on and off of the routine for correcting for instrument transients. This is done because we cannot accurately correct for transients when the instrument

steps too rapidly. The point where we stop correcting depends both on the telemetry rate and the field strength.

Figure 4 shows the plot of the three components of the field and the magnitude of the field corresponding to the deviations in figure 2. Horizontal lines give the zeroes for each component. These can move about to maximize the amount of data on a page. The zero for the total field is the bottom of the plot. The scale is linear and is 10 gammas per division.

Figure 5 shows the field through perigee for the same interval shown in figure 3. The vertical scale is logarithmic with positive values plotted in the upper half of the plot and negative values in the lower half. This is the only logarithmic plot per orbit.

c) Microfilm Plots in Geocentric Solar Ecliptic (GSE) Coordinates

The microfilm plots in GSE coordinates contain only the field data because the rms deviations cannot be rotated. To transform the data to GSE the orbit tape supplied by GSFC has been used. The data on this tape is every minute. Errors in the positional and orientation data as well as in the magnetic field data can affect the data in the GSE plot.

Figures 6 and 7 show the data in figures 5 and 4 rotated into GSE. The format is identical with the exception that the hourly GSE coordinates of the satellite have been printed at the top of each page. The distances are in earth radii. There are 13 frames per orbit.

d) Microfilm Plots in Geocentric Solar Magnetospheric (GSM) Coordinates

These plots are identical to the GSE plots except that the field and the position are given in the GSM system.

e) Magnetic Tapes in Spacecraft Coordinates

These tapes are 9 track, 800 BPI standard labelled binary tapes. They have 5 files per tape, each file corresponding to one orbit. These files usually overlap in time just before perigee. The JCL used to create the tape is

```
//GO.FT10F001 DD DISP=(NEW,KEEP),DSN=BDY001,
// UNIT=2400,LABEL=(1,SL,,OUT),VOL=SER=IG0005,
// DCB=(RECFM=V,LRECL=5128,BLKSIZE=5132)
```

The binary records are written by the Fortran statement:

```
WRITE(10) NREC, (IBT(I), BX(I), BY(I), BZ(I),
BT(I), BXRMS(I), BYRMS(I), BZRMS(I), BTRMS(I),
IQUAL(I), I=1, 128)
```

where

NREC=128

IBT=Bishop time (defined in Appendix)

BX= X component of the field in gammas

BY= Y component of the field in gammas

BZ= Z component of the field in gammas

BT= total field in gammas (obtained by averaging instantaneous values)

BXRMS= X rms deviation in gammas

BYRMS= Y rms deviation in gammas

BZRMS= Z rms deviation in gammas

BTRMS= Total field rms deviation in gammas

IQUAL= Quality indicator

The quality indicator IQUAL is the sum of two numbers, 1000 times NUMPTS + ICHL. NUMPTS is the number of data points used in the average and ICHL is a flag indicating the status of heater, calibrate signal and ladder step corrections during the averaging interval.

ICHL may be thought of as a binary number with seven bits:

$X_0, X_1, X_2, X_3, \dots, X_6$.

If X_0 equals 1, then sometime during the averaging interval a heater correction was required but the exact interval for applying this correction could not be found.

If X_2 equals 1, then sometime during the averaging interval a heater correction was applied.

If X_3 equals 1, then a calibration signal correction was made.

If X_4 equals 1, then at least one correction for a medium ladder step on the Z axis was made.

If X_5 equals 1, then at least one correction for a medium ladder step on the Y axis was made.

If X_6 equals 1, then at least one correction for a medium ladder step on the X axis was made.

We note that X_2 is not used, and that this seven bit binary number actually appears in IQUAL as a three digit decimal number.

f) Magnetic Tapes in GSE Coordinates

These tapes are 9 track, 800 BPI, standard labelled binary tapes. They have 5 files per tape, each file corresponding to one orbit. These files usually overlap in time just before perigee. The JCL used to create the tape is:

```
//GO.FT10FO01 DD DISP=(NEW,KEEP),DSN=GSE001,
// UNIT=2400,LABEL=(1,SL,,OUT),VOL=SER=IG0006,
// DCB=(RECFM=V,LRECL=1228,BLKSIZE=1232)
```

The binary records are written by the Fortran statement:

```
WRITE(10)IORBIT,IBTST,XGSE,YGSE,ZGSE,RE,
BXE,BYE,BZE,BTE,IQUAL
```

where: BXE,BYE,BZE,BTE and IQUAL are arrays of 60 elements each and

IORBIT = Orbit number

IBTST = Bishop time of first point in record (Bishop time is defined in appendix)

XGSE = XGSE coordinate of satellite at start of record in Re

YGSE = YGSE coordinate of satellite at start of record in Re

ZGSE = ZGSE coordinate of satellite at start of record in Re

RE = Radial distance of satellite from the center of the earth in earth radii

BXE = X GSE component of the field in gammas

BYE = Y GSE component of the field in gammas

BZE = Z GSE component of the field in gammas

BTE = Total field magnitude (obtained by averaging instantaneous values)

IQUAL = Quality indicator as explained in previous section.

g) Magnetic Tapes in GSM Coordinates

Format identical to GSE tapes except that field and positional data are in GSM coordinates.

REQ. AGENT
CAW

RAND NO.
RC7558

ACQ. AGENT
DJH

OGO-5

4.608 SECOND AVERAGED B FIELD
68-014A-14C

This data set consists of merged OGO-5 tapes (each having 15 files and being standard label previously before the merging onto new tape) each containing 25 files of non-standard label data. The tapes are 9 track, 1600, binary, with odd parity.

<u>D#</u>	<u>C#</u>	<u>FILES</u>	<u>TIME SPAN</u>
D-29194	C-18795	25	03/05/68 - 05/08/68
D-29195	C-18796	25	05/21/68 - 07/12/68
D-29196	C-18797	25	07/12/68 - 09/15/68
D-29248	C-18940	25	09/15/68 - 11/19/68
D-29249	C-18941	20	11/19/68 - 01/10/69

*NOTE: The last tape processed may not have 25 files on it due to lack of more data.

OGO 5

FLUXGATE MAGNETOMETER

68-014A-14E

THIS DATA SET HAS BEEN RESTORED. THERE WERE ORIGINALLY 14 7-TRACK, 800 BPI TAPES, WRITTEN IN BINARY WITH STANDARD LABELS. THERE ARE 3 RESTORED TAPES. THE RESTORED TAPES ARE UN-LABELED. THE DR TAPES ARE 3480 CARTRIDGES AND THE DS TAPES ARE 9-TRACK, 6250 BPI. THE ORIGINAL TAPES WERE CREATED ON AN IBM 360 COMPUTER. THE DR AND DS NUMBERS ALONG WITH THE CORRESPONDING D NUMBERS AND TIME SPANS ARE AS FOLLOWS:

DR#	DS#	D#	FILES	TIME SPAN
DR002636	DS002636	D005575	1-5	03/05/68 - 03/17/68
		D004813	6-10	03/17/68 - 03/30/68
		D006163	11-15	03/30/68 - 04/12/68
		D006164	16-20	04/12/68 - 04/25/68
		D006371	21-25	05/13/68 - 05/26/68
DR002637	DS002637	D006861	1-5	05/21/68 - 06/03/68
		D006370	6-10	05/26/68 - 06/12/68
		D006862	11-15	06/03/68 - 06/16/68
		D008052	16-20	06/17/68 - 06/30/68
		D008051	21-25	06/30/68 - 07/13/68
DR002638	DS002638	D008049	1-5	07/13/68 - 07/26/68
		D008050	6-10	07/26/68 - 08/08/68
		D008833	11-15	08/06/68 - 08/19/68
		D008834	16-20	08/19/68 - 09/01/68

OGO 5

1-MIN. AVG. B-FIELD, GSM COORD.

68-014A-14F

This data set has been restored. There were originally 15 7-track, 800 BPI tapes, written in Binary with standard labels. There is one restored tape. The restored tape is unlabeled. The DR tape is a 3480 cartridge and the DS tape is 9-track, 6250 BPI. The tapes were created on an IBM 360 computer and were restored on an IBM 3081 computer. The DR and DS number along with the corresponding D numbers and time spans are as follows:

DR#	DS#	D#	FILES	TIME SPAN
DR002775	DS002775	D004814	1-5	03/05/68 - 03/17/68
		D006007	6-10	03/17/68 - 03/30/68
		D006161	11-15	03/30/68 - 04/12/68
		D006162	16-20	04/12/68 - 04/25/68
		D006369	21-25	05/13/68 - 05/26/68
		D006863	26-30	05/21/68 - 06/03/68
		D006368	31-35	05/26/68 - 06/09/68
		D006864	36-40	06/03/68 - 06/16/68
		D008055	41-45	06/17/68 - 06/30/68
		D008056	46-50	06/30/68 - 07/13/68
		D008053	51-55	07/13/68 - 07/26/68
		D008054	56-60	07/26/68 - 08/08/68
		D008835	61-65	08/06/68 - 08/19/68
		D008836	66-70	08/19/68 - 09/01/68
		D029053	71	03/05/68 - 05/05/70

OGO-5

1 MIN. AVG. B FIELD ON TAPE

68-014A-14F

This tape is an addition to the data set. The format of the tape is 9 track, 1600 BPI, unlabelled, binary and was created on an IBM/360. The tape contains 1 file, with the file containing orbits 1 thru 305 (Date 3/05/68 - 5/05/70).

D#
D-29053

C#
C-18728

DATE
3/5/68 - 5/5/70

SSC184 is a 9 track, ⁶²⁵⁰1600 BPI, unlabelled, IBM 360/computer binary tape. The tape contains one file having orbits 1 - 305. The DCB parameters are: RECFM=VBS, LRECL=1228, BLKSIZE=6144, DEN=3.

Tape parameters:

IORBIT = Orbit number (Integer)

IBTST = Bishop time of first point in record (Integer) (see attached for definition)

XGSM = X GSM coordinate of satellite at start of record in Re (Real)

YGSM = Y GSM coordinate of satellite at start of record in Re (Real)

ZGSM = Z GSM coordinate of satellite at start of record in Re (Real)

RE = Radial distance of satellite from the center of the earth in earth radii (Real)

BXGSM = X GSM component of the field in gammas (Real)

BYGSM = Y GSM component of the field in gammas (Real)

BZGSM = Z GSM component of the field in gammas (Real)

BTGSM = Total field magnitude (obtained by averaging instantaneous values) (Real)

IQUAL = Quality indicator as explained in attachment (Integer)

NOTE: BXGSM, BYGSM, BZGSM, BTGSM and IQUAL are arrays of 60 elements each

BTRMS= Total field rms deviation in gammas

IQUAL= Quality indicator

The quality indicator IQUAL is the sum of two numbers, 1000 times NUMPTS + ICHL. NUMPTS is the number of data points used in the average and ICHL is a flag indicating the status of heater, calibrate signal and ladder step corrections during the averaging interval.

ICHL may be thought of as a binary number with seven bits:

$X_0, X_1, X_2, X_3, \dots, X_6$.

If X_0 equals 1, then sometime during the averaging interval a heater correction was required but the exact interval for applying this correction could not be found.

If X_2 equals 1, then sometime during the averaging interval a heater correction was applied.

If X_3 equals 1, then a calibration signal correction was made.

If X_4 equals 1, then at least one correction for a medium ladder step on the Z axis was made.

If X_5 equals 1, then at least one correction for a medium ladder step on the Y axis was made.

If X_6 equals 1, then at least one correction for a medium ladder step on the X axis was made.

We note that X_2 is not used, and that this seven bit binary number actually appears in IQUAL as a three digit decimal number.

```

ROUTINE CONBT ( T, BT )
*****
'BISHOP TIME' CONVERSION SUBROUTINE FOR OGO-5. BT IS DEFINED AS THE
NUMBER OF TENTHS OF A SECOND SINCE THE START OF YEAR 1966, THAT IS,
BT = 0 AT YR 66 DAY 1 HR 0 ETC., AND THE TIME UNIT IS 1/10 SEC.
  CALL CONBT( T, BT ) CONVERTS T ARRAY TO BT.
  CALL BTCON ( BT, T ) CONVERTS BT TO T ARRAY.
* THE T ARRAY IS DEFINED AS FOLLOWS:
*   T(1) = YEAR (66-71)           T(5) = HOUR (0-23)
*   T(2) = DAY OF YEAR (1-366)    T(6) = MINUTE (0-59)
*   T(3) = MONTH (1-12)          T(7) = SECOND (0-59)
*   T(4) = DAY OF MONTH (1-31)    T(8) = MILLISECOND (0-999)
* WHEN CONVERTING TO BT, T(3) AND T(4) ARE USED ONLY IF T(2) = 0.
* OTHERWISE T(3) AND T(4) ARE IGNORED. WHEN CONVERTING FROM BT, ALL
* EIGHT ENTRIES OF THE T ARRAY ARE COMPUTED.
* THE SUBROUTINE FAILS AFTER FEB. 28, 1972 AND BISHOP TIME
* OVERFLOWS THE 360 WORD LATER THAT YEAR.
*
*                                     PROGRAMMER - NEAL CLINE JAN. 1968
*****
  INTEGER T(8), BT, M(13)
  * / 0, 31, 59, 90, 120, 151, 181, 212, 243, 273, 304, 334, 365 /
  N = ( T(1) - 66 ) * 365
  IF ( T(1) .GT. 68 ) N = N + 1
  IF ( T(2) .NE. 0 ) GO TO 10
    N = N + M(T(3)) + T(4) - 1
    IF ( T(3) .GT. 2 .AND. T(1) .EQ. 68 ) N = N + 1
  GO TO 20
10 N = N + T(2) - 1
20 BT = N*864000 + T(5)*36000 + T(6)*600 + T(7)*10 + T(8)/100
  RETURN
  ENTRY BTCON ( BT, T )
  N = BT / 864000
  IF ( N - 1095 ) 50, 30, 40
30   T(1) = 68
   T(2) = 366
   GO TO 60
40   N = N - 1
50   T(1) = N/365 + 66
   T(2) = MOD( N, 365 ) + 1
60 N = T(2)
  IF ( T(1) .NE. 68 ) GO TO 90
  IF ( N - 60 ) 90, 70, 80
70   T(3) = 2
   T(4) = 29
   GO TO 120
80   N = N - 1
90 DO 100 K = 2, 13
   IF ( N .LE. M(K) ) GO TO 110
100  CONTINUE
110 T(3) = K - 1
   T(4) = N - M(K-1)
120 T(5) = MOD( BT/36000, 24 )
   T(6) = MOD( BT/600, 60 )
   T(7) = MOD( BT/10, 60 )
   T(8) = MOD( BT, 10 ) * 100
  RETURN
  END

```

Appendix

Bishop time is the name of the unit of time used for the majority of the processing of the OGO-5 and ATS-1 fluxgate magnetometer data at UCLA. It is defined as the number of tenths of seconds since the start of the year 1966, that is, Bishop time equals zero, at 0000 U.T. on January 1, 1966. The advantage of using Bishop time is that one single 360 word can be used to cover a period of six years. Six years is longer than the life-expectancy of most satellites. The disadvantage is that this time word cannot be used to provide timing for the high telemetry rate data of OGO-5. This problem does not arise for the data discussed in this report because the highest sample rate given on these tapes is one point every 4.608 seconds.

On the next page is the listing of a subroutine to convert from Bishop time to ordinary Universal time and vice versa. The entry point BTCON converts from Bishop time while the entry point CONBT converts to Bishop time.

FORTRAN IV G LEVEL 21

MAIN

DATE = 77035

14/54/23

C PROGRAM READS TAPE SSC184 AND PRINTS OUT FIRST 50 RECORDS

0001	INTEGER NORB,NBT,T(8)/8*0/,IQL(60)	BKF00160
0002	REAL C(4),B(60,4)	BKF00180
0003	DO 10 NREC=1,50	BKF00200
0004	READ(1) NORB,NBT,C,B,IQL	BKF00220
0005	CALL BTCUN(NBT,T)	BKF00260
0006	WRITE(6,2000) T,NORB,C,B(1,1),B(1,2),B(1,3),B(1,4),IQL(1)	BKF00280
0007	2000 FORMAT(1X,8I4,1X,14,1X,8F10.3,1X,18)	BKF00300
0008	DO 20 I=1,8	BKF00320
0009	20 T(I)=C	BKF00340
0010	10 CONTINUE	BKF00360
0011	STOP	BKF00380
0012	END	BKF00400

D12000-000A
DLO-T
HCK-P

500015-000

68-014A-14A
68-014A-14B
68-014A-14C
68-014A-14D
68-014A-14E
68-014A-14F
68-014A-14

PRODUCTION PROCESSING OF THE DATA OBTAINED
BY THE UCLA OGO-5 FLUXGATE MAGNETOMETER

Christopher T. Russell
Institute of Geophysics and Planetary Physics
University of California, Los Angeles

Publication No. 905

March 1971

Backup Time
IBT BX BY BZ BT 1900-
UT IX, I19, 2X, I10, 5X, 4(5 15.5, 5X), I15
YYDDDHHMMSSMSS

Introduction

In designing the production processing plan for the UCLA OGO-5 fluxgate magnetometer data, it was decided to process the entire input data stream to provide a complete data base from which to undertake further studies. It was hoped that this data base could provide the criteria for data selection not only for the OGO-5 magnetometer experimenters but for other experimenters as well. With this in mind a series of plots were designed to describe the character of the data: to allow one to recognize different regions and to distinguish different regimes within these regions; to locate the boundaries of these regions; and to determine which time intervals were candidates for further analysis. At the same time it was recognized that such summary data could also be used as an analytical tool itself, so therefore these data were also stored on magnetic tape as well as plotted on microfilm plots. A useful summary plot, of course, maintains a constant time scale, and contains all the data in time sequence. So too, the summary data tapes become convenient because they have a fixed data rate and are time ordered, a feature not present in the original OGO-5 data. Needless to say, the summary tapes contain average data only and studies requiring high resolution data require recourse to the original data tapes.

Often times, the orbital position of the satellite rather than some character of the data dictates selecting a region for study. In order to be able to use orbital criteria, a series of orbit plots were also produced in several coordinate systems.

To obtain the most general overview of the data it was decided to make one minute averages of the data. These were plotted five hours to a page or microfilm frame. These plots, however, do not give the precise timing that is necessary for selecting intervals to study for certain phenomena such as the bow shock and magnetopause and thus another plot was made of the data using 4.608 second averages. This interval was dictated in part by the sample rate of the spacecraft. It represents 4, 32, or 256 individual vector measurements depending on telemetry bit rate. The 4.6 second averages were plotted with 20 minutes per page.

Both the one minute averages and the 4.6 second averages were plotted in the spacecraft coordinate system which is a quasi-inertial system but which is a function of orbit position and time of year. In this way the processing of the data would be independent of the receipt of orbit data and any instrument anomalies would maintain their character, e.g., relative size in the various vector components. However, since certain phenomena are more easily recognized in one coordinate system than another, the one minute averages were also converted to both geocentric solar magnetosphere (GSM) and geocentric solar ecliptic (GSE) coordinates and plotted. Thus there are three

plots of the one minute averages: in spacecraft coordinates, in GSM coordinates and in GSE coordinates.

The OGO-5 spacecraft can transmit data at any one of three telemetry rates: 1, 8 or 64 kilobits per second. At the same time it can store data at 1 kilobit/sec for later transmission. Thus there can be two original data tapes for any one time interval at two different sample rates. In performing the data reduction, the highest data rate data has always been used in preference to the lowest data rate.

Needless to say processing all the data is relatively expensive, although highly valuable, and thus the amount of magnetic field data processed is a function of funding. The orbital data is much less expensive because there are much fewer data points per unit time. Thus orbital data processing is usually far ahead of the magnetic field data processing.

Printouts of all one minute average data and of many of the orbital parameters from the orbit tapes have been produced. It is not intended to send these to the National Space Science Data Center (NSSDC) since these printouts can be duplicated from the tapes.

Finally some remarks about data presentation. All data, on plots and on tapes are presented as vector components and total field. Such data can be more easily transformed and manipulated than data presented as magnitudes and angles and in general is as easy to interpret. Data presented as angles

can be confusing if the angle is near one of its limits (say 90° or -90°) when it flips back and forth in response to small fluctuations.

In the sections to follow, we shall briefly describe the instrument, discuss the data processing procedure, and then describe the formats of the resulting plots and tapes. The description of the production of orbital plots has been given elsewhere¹, and will not be repeated in this report.

¹Russell, C.T., OGO-5 orbital plots generated by the UCLA Fluxgate Magnetometer Group, Publication No. 792, Institute of Geophysics and Planetary Physics, University of California, Los Angeles, 1969.

2. The Instrument

The UCLA fluxgate magnetometer was designed to provide an accurate triaxial vector measurement of the magnetic field from perigee at low altitudes to apogee in the interplanetary medium. Each of the three orthogonal sensors has a dynamic range of $\pm 64,000$ gammas and in low fields can resolve field changes of $1/8$ th of a gamma. This was accomplished with a basic magnetometer that measures ± 16 gammas and a set of coils that provide fields to null out the field at the basic magnetometer to within $\pm 16\gamma$. The currents for these coils are provided in 64 steps of 16γ and 128 steps of 1024γ . This is accomplished as follows: If a field of greater than $+16\gamma$ or less than -16γ reaches the basic magnetometer, this field is reduced in steps of 16γ until the field at the basic magnetometer is within its operating range. When all available 16γ steps have been applied (64 possible) a field of 1024γ is applied and 63 of the 16γ steps are removed. This stepping procedure has a cycle rate of 500 hz which is far above the magnetometer sampling rates.

The measured field consists then of three quantities: the number of 1024γ nulling fields applied, the number of 16γ nulling fields and the output of the basic magnetometer from $+16$ to -16γ digitized in 256 parts, each $1/8\gamma$. The sum of these three quantities for each independent axis gives the measured vector field.

The basic magnetometer is operated as a closed loop magnetometer with a frequency response that is flat to 150 hz and then rolls off at 20 db per decade above 150 hz. The three possible OGO-5 telemetry rates, 1, 8 and 64 kilobits per second, correspond to Nyquist frequencies of .43, 3.5 and 27.8 hz for the instrument. Since meaningful wave studies can be performed only if no signals above the Nyquist frequency reach the telemetry system, the output of the basic magnetometer enters a bit rate dependent filter before being digitally sampled. This critically damped fourth order filter has 8 db attenuation at half the Nyquist frequency, 20 db attenuation at the Nyquist frequency and 40 db attenuation at twice the Nyquist frequency.

The satellite can simultaneously transmit data to earth (real time data) and store data on the spacecraft on magnetic tape for later transmission (playback data). These data can be sampled at different rates: playback data is always sampled at 1 kilobit per second whereas the real time data has three possible rates. Thus, the instrument has actually two outputs, each with its independent filter depending on the sampling rate of the digitization unit to which the signal is routed.

The absolute accuracy of the measured field depends on many factors: the sensitivity of the magnetometer, the size of spacecraft fields and the possibility of drifts in the zero levels of the magnetometer. This magnetometer is the most sensitive fluxgate magnetometer ever flown on a spacecraft and is separated from the main body of the spacecraft by a

twenty foot boom. However, there are other nearby experiments and this was a newly designed magnetometer. Comparing with the Goddard magnetometers on board which are on a similar boom restricted only to magnetometers, it was found that there was a slow drift from orbit to orbit of the apparent zero levels of the UCLA magnetometer. The Goddard magnetometers consist of a Rb vapor magnetometer and a fluxgate magnetometer both of which have been flown before on OGO-1 and OGO-3 and which provide consistent fields when compared. Data from these magnetometers, graciously supplied by the experimenters have been used to determine the zero level for each OGO-5 orbit. However, in view of the slow drift of the zero levels the absolute value of any one component may be in error from one to two gammas. On the other hand the rate of drift is exceedingly slow compared to the time scales of physical processes such as waves, discontinuities, etc. Thus changes in the field components can be accurately measured to the digitization window of the experiment, 1/8 gamma.

In order to check the calibration of the instrument, a calibration signal is applied to each sensor approximately every 40 minutes (actually every 39 minutes 19.296 seconds). The calibrate signal is 64 data points long, where the number of points is counted at the real time data rate if the satellite is transmitting real time data and at the data storage rate if it isn't. Four bias fields of 8, 32, -8 and -32 gammas are applied to each sensor and each is applied for 16 consecutive

data points. The effect of these bias signals is removed in all data processing.

The unit housing the sensors has a heater which has a magnetic field when it is turned on. This heater bias field is approximately 8 gammas on the X and Y axes and 0.5 gammas on the Z-axis. This bias is also removed from all processed data.

3. General Remarks on Data Reduction

In processing a section of data the first step is to determine the sensor offsets. This is done by comparing with simultaneous measurements of the GSFC fluxgate magnetometer. (The GSFC data is corrected for its offsets with values determined from the Rubidium magnetometer data by the GSFC magnetometer group.) This is usually done once per orbit.

When the data enters the computer program, besides converting from voltages to gammas, the program corrects for three effects. The first effect is due to the heater bias. The program finds the heater signature by checking a heater on/off word which is sampled at 1/128th of the data rate and then looks for the expected heater on or off signature in the interval of 128 points bracketed by the change in the heater on/off word. This can fail if the data were very active, if there are data gaps or if the heater came on or went off at or near the end of a file of data (a file of data is defined by a continuous sequence of data on the original data tapes).

The second effect is that of the calibrate signal. The calibrate signal is much easier to identify than the heater signature. However, the occurrence of a calibration signal is not flagged by the instrument. Therefore, it is continuously searched for. It can be missed for the same reasons as the heater signature.

The third effect is the occurrence of transients whenever the medium ladder steps. Since the instrument obeys the Nyquist sampling criterion by having filters to remove signals above half the Nyquist frequency any step change in the data decays with a time constant which for this instrument equals six data points. The filters are applied only to the fine output of the magnetometer. Thus when an additional nulling field is applied to the sensor by the medium ladder (the medium ladder is the array of sixty-four 16 gamma steps that can be applied to each sensor) there is a transient 6 data points in duration. Various schemes have been applied to remove this transient depending in part on the nature of the data.

After these corrections the data is plotted, printed or averaged as required.

4. The Roadmaps. (One Minute Averages)

a) Data Processing

In generating the Roadmap plots all data is processed and averaged, both real time and playback. This data is then stored on a disk pack by orbit in two data sets one for real time data and one for playback data. Then these two data sets are scanned taking data in time sequence from the real time set until a gap is found in the data. Then playback data is searched to try to fill this gap. When this gap is filled or if it cannot be filled the real time data is again read until the next gap and then the process repeats. The end result is a tape with an orbit's data in time sequence containing averages formed from the highest possible telemetry rate. The data from this tape is then printed and microfilm plotted. There are no missing times on these tapes. When data is not available for a particular time it is flagged with a value of 100000.

At the same time, as the Roadmap tape is being created which contains one minute averages, the 4.608 second averages are created. Thus the 4.608 second averages are also in time sequence for one orbit with priority given to the highest telemetry rate data. These tapes are not printed or plotted at UCLA but are sent to H. West at the Lawrence Radiation Laboratory, Livermore, California where they are microfilm plotted. These magnetic tapes are also continuous in time with missing data flagged with values of 100000.

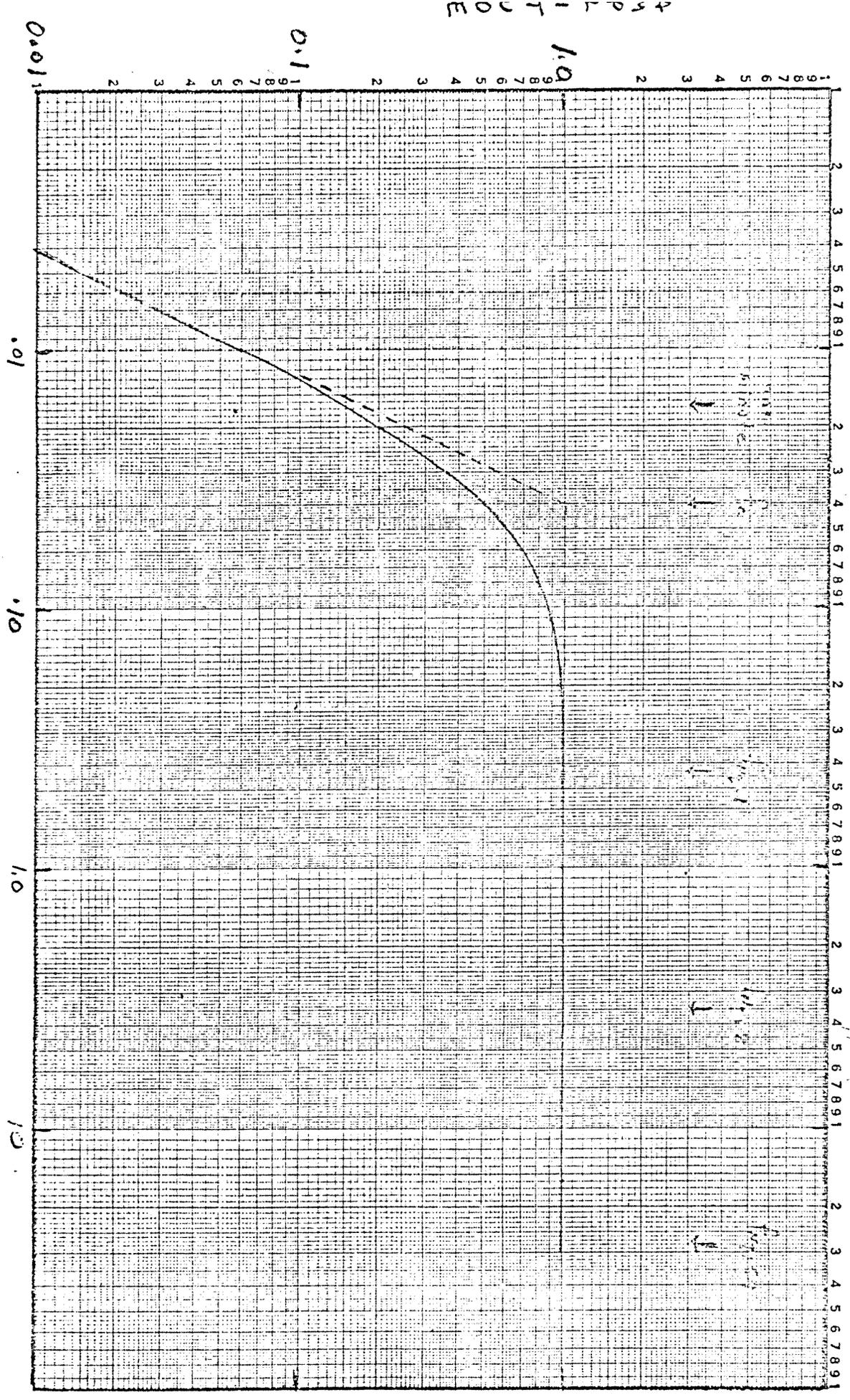
The one minute averages are centered on each minute. The points in this interval are scanned for obvious bad points, the bad points are rejected and the good points are summed and then the total is divided by the number of good points. The number of good points is also saved. We note that this process is performed for each of the three vector components and the total field. The total field calculated is the average of the instantaneous field magnitudes.

In order to retain information on the high frequency end of the spectrum, rms deviations are also calculated for each of the vector components and the total field. We note that the rms deviation of the total field depends somewhat on the accuracy of the offsets used. Thus reliance on the accuracy of the calculation of the rms deviation of the total field should be avoided in low fields. The deviations of the vector components, however, is independent of offset errors.

The rms deviations are not strictly rms deviations in the usual definition of the term, but are actually the rms amplitude of waves in a band of frequencies from 0.07 Hz (15 second period) to the Nyquist frequency which is a function of the telemetry rate. To calculate this amplitude, the input data stream, across averaging intervals, was filtered with a two stage high pass recursive filter. The amplitude response of this filter is shown in figure 1. The output of this filter was squared and summed over each minute and divided by the number of points and then its square root was taken.

*Revised
1/2/68*

FREQUENCY RESPONSE OF TWO STAGE HIGH PASS FILTER USED IN RMS DEVIATIONS IN ROAD MAPS



FREQUENCY (Hz)

Figure 1

We note that this rms deviation is very insensitive to field gradients whereas the usual rms deviation responds readily to field gradients. However, as all deviations it is very sensitive to bad data and sharp spikes in the rms deviations are probably due to telemetry errors.

b) Microfilm Plots in Spacecraft Coordinates

Each microfilm frame contains five hours of data, so that 13 pages are required to plot an orbit. However, we have plotted two frames for each five hour interval: one containing the vector field data and one containing the rms deviation data. Thus there are 26 frames for every orbit. These are numbered in the lower right-hand corner of every plot. (There are two pages 1, two pages 2, etc.). The data corresponding to the first time on the page and the orbit number are plotted in the upper right-hand corner of each page. Also, each page of data in spacecraft coordinates has the heading "Body Coordinates".

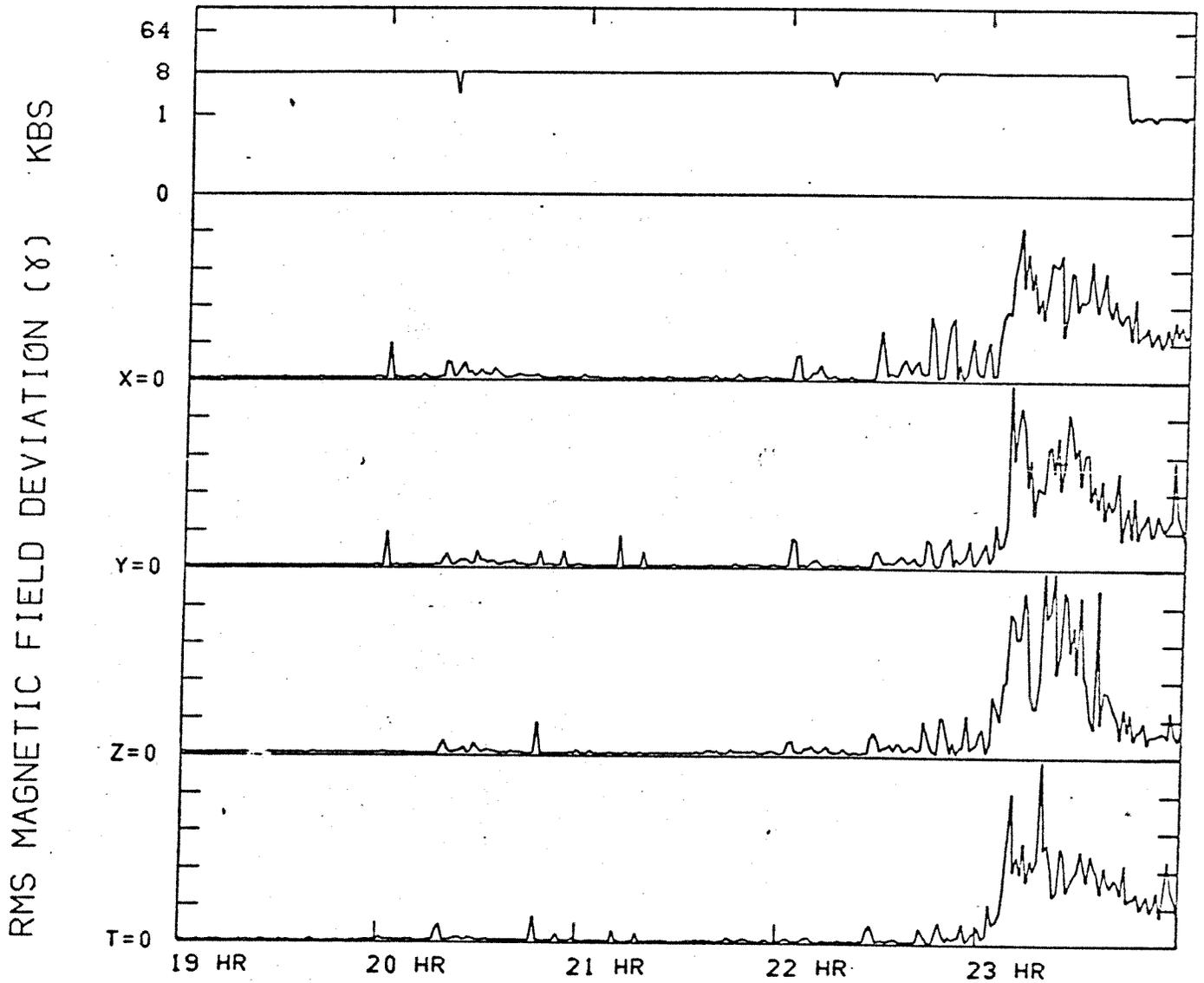
The format of the plot of the rms deviations remains fixed throughout the orbit. Figure 2 shows a typical frame of the rms deviation page. The top axis labelled "KBS" indicates the telemetry bit rate. However, since this is derived by counting the number of points in a one minute average it provides more information than just this. If data quality is poor and points have to be discarded, then this quantity will deviate from a straight line. Furthermore, data missing between files on the original data tapes for intervals less than one minute will show

UCLA OGO-5 FLUXGATE MAGNETOMETER

BODY COORDINATES

28 DEC 1968

ORBIT 116



UNIVERSAL TIME (HOURS)

Fig. 2

Date quality indicators

up as a downwards spike on this plot. We note that this quantity is plotted on a log scale.

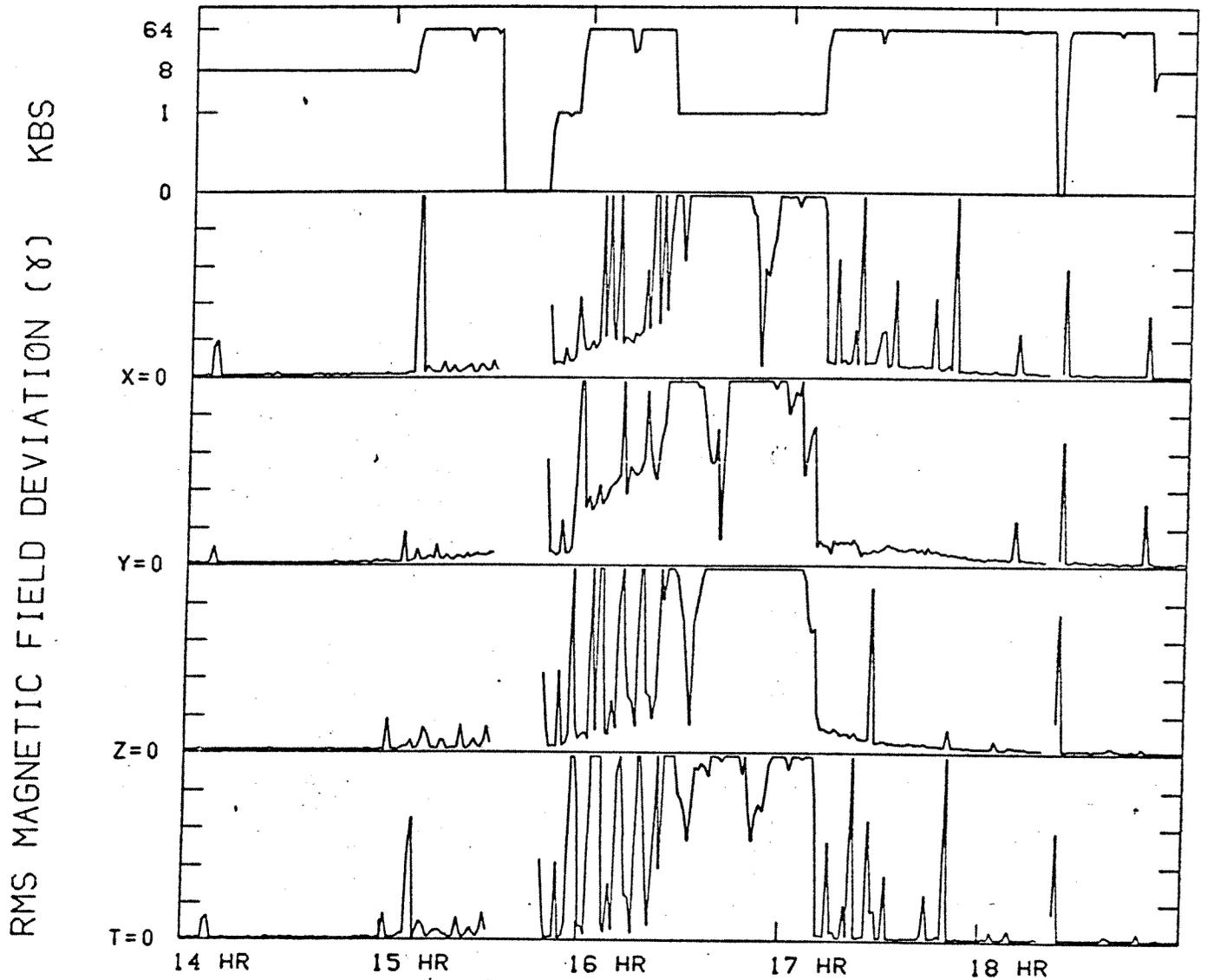
The next four quantities from top to bottom are the rms deviations B_X , B_Y , B_Z and in the total field. The scale is one gamma per division and is linear. The plots saturate at five gammas. The deviations are usually quite accurate but errors may occur. These usually take the form of isolated spikes. On occasion isolated spikes every 40 minutes can occur. These are caused by incompletely correcting for the calibrate signal or missing it completely. Another possible error is an increase in general noise level due to poor quality data. This can be recognized by the deviation of the bit rate word from a straight line. Although most bad points are rejected from the averages and the rms deviations a few always get through and this raises the power in the fluctuations. Spikes occurring on only one axis or on both the X and Y axes and not the Z axis are especially suspicious, such as the ones at 2000 UT and 2105 UT on figure 2.

Figure 3 shows an rms deviation frame through perigee (Perigee is at 1641 UT). We see that data near perigee can be very noisy. This is not real. From 1500 to 1600 and from 1700 to 1800 we see a general rise and then fall of the noise level. This is due to boom vibrations. The sharp increase (and decreases) near 1600 and the sharp decrease in the deviations near 1700 are caused by the switching on and off of the routine for correcting for instrument transients. This is done because we cannot accurately correct for transients when the instrument

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steps too rapidly. The point where we stop correcting depends both on the telemetry rate and the field strength.

Figure 4 shows the plot of the three components of the field and the magnitude of the field corresponding to the deviations in figure 2. Horizontal lines give the zeroes for each component. These can move about to maximize the amount of data on a page. The zero for the total field is the bottom of the plot. The scale is linear and is 10 gammas per division.

Figure 5 shows the field through perigee for the same interval shown in figure 3. The vertical scale is logarithmic with positive values plotted in the upper half of the plot and negative values in the lower half. This is the only logarithmic plot per orbit.

c) Microfilm Plots in Geocentric Solar Ecliptic (GSE) Coordinates

The microfilm plots in GSE coordinates contain only the field data because the rms deviations cannot be rotated. To transform the data to GSE the orbit tape supplied by GSFC has been used. The data on this tape is every minute. Errors in the positional and orientation data as well as in the magnetic field data can affect the data in the GSE plot.

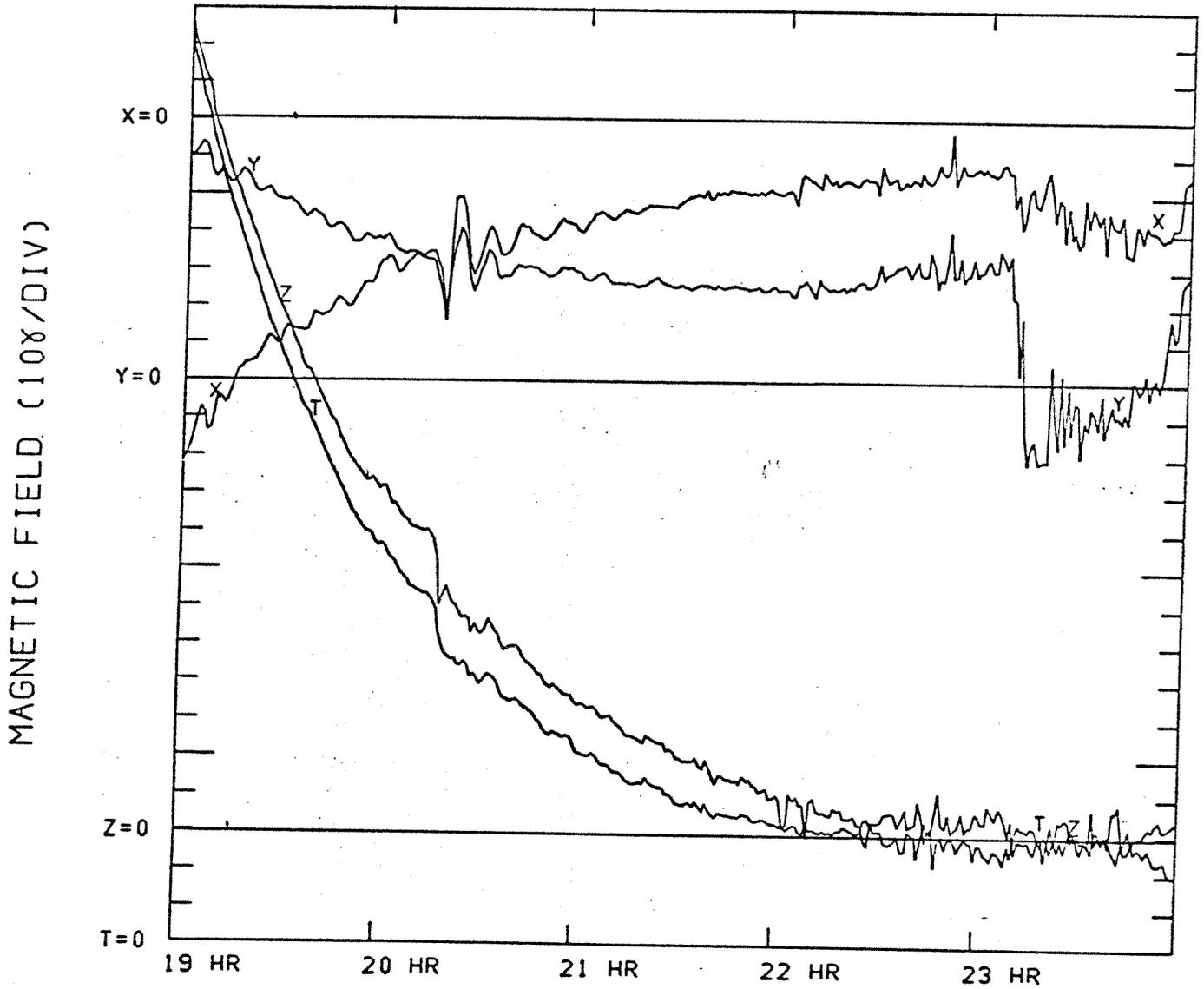
Figures 6 and 7 show the data in figures 5 and 4 rotated into GSE. The format is identical with the exception that the hourly GSE coordinates of the satellite have been printed at the top of each page. The distances are in earth radii. There are 13 frames per orbit.

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BODY COORDINATES

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ORBIT 116



UNIVERSAL TIME (HOURS)

UCLA OGO-5 FLUXGATE MAGNETOMETER

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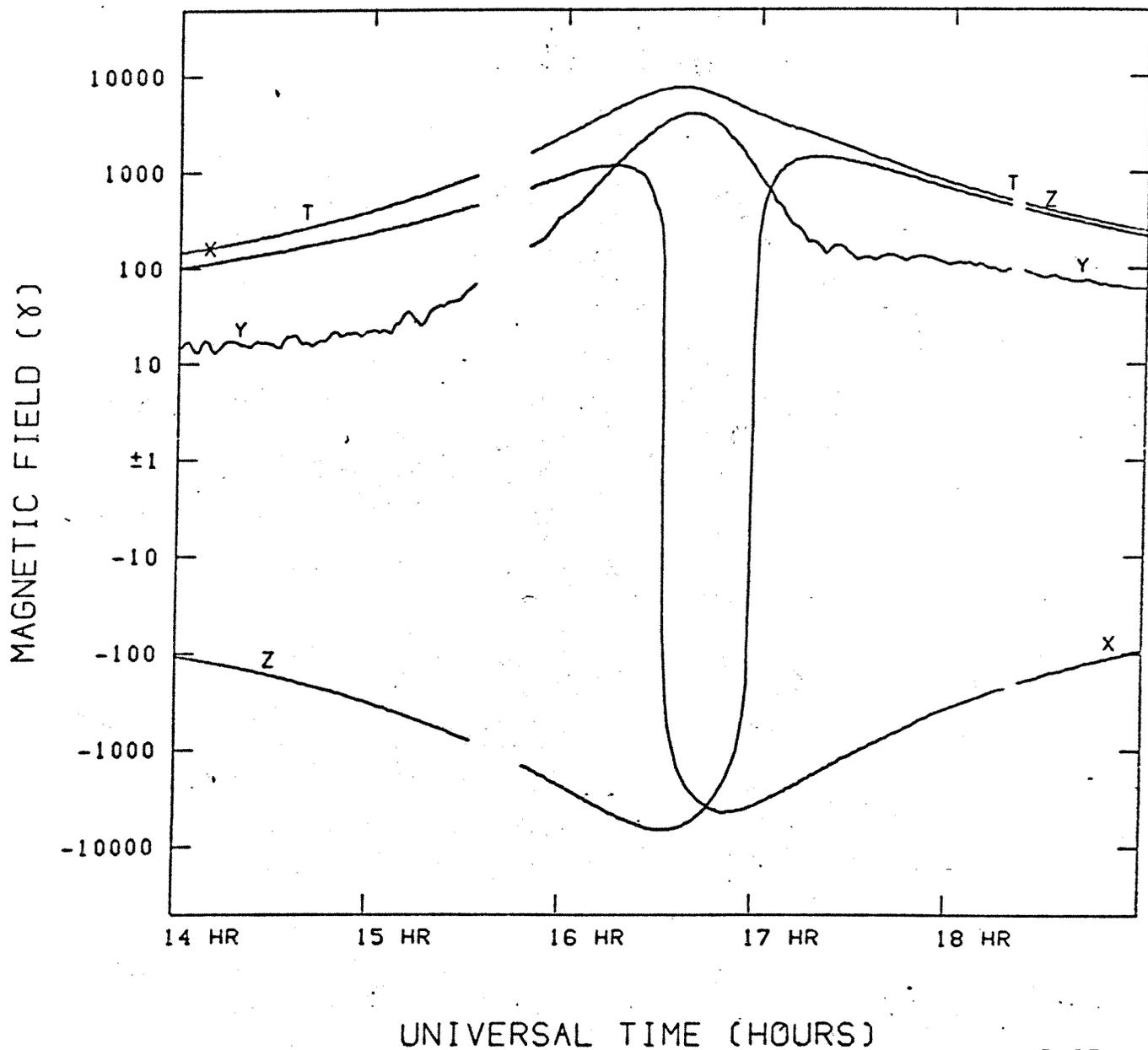


Fig. 5

ORBIT 116 UCLA OGO-5 FLUXGATE MAGNETOMETER 28 DEC 1968
 GSE COORDINATES

X	3.10	1.53	-0.31	-1.23	0.08	RE
Y	5.61	3.99	1.58	-1.67	-2.65	RE
Z	-1.41	-2.03	-2.18	-0.03	2.99	RE
R	6.56	4.73	2.71	2.07	3.100	RE

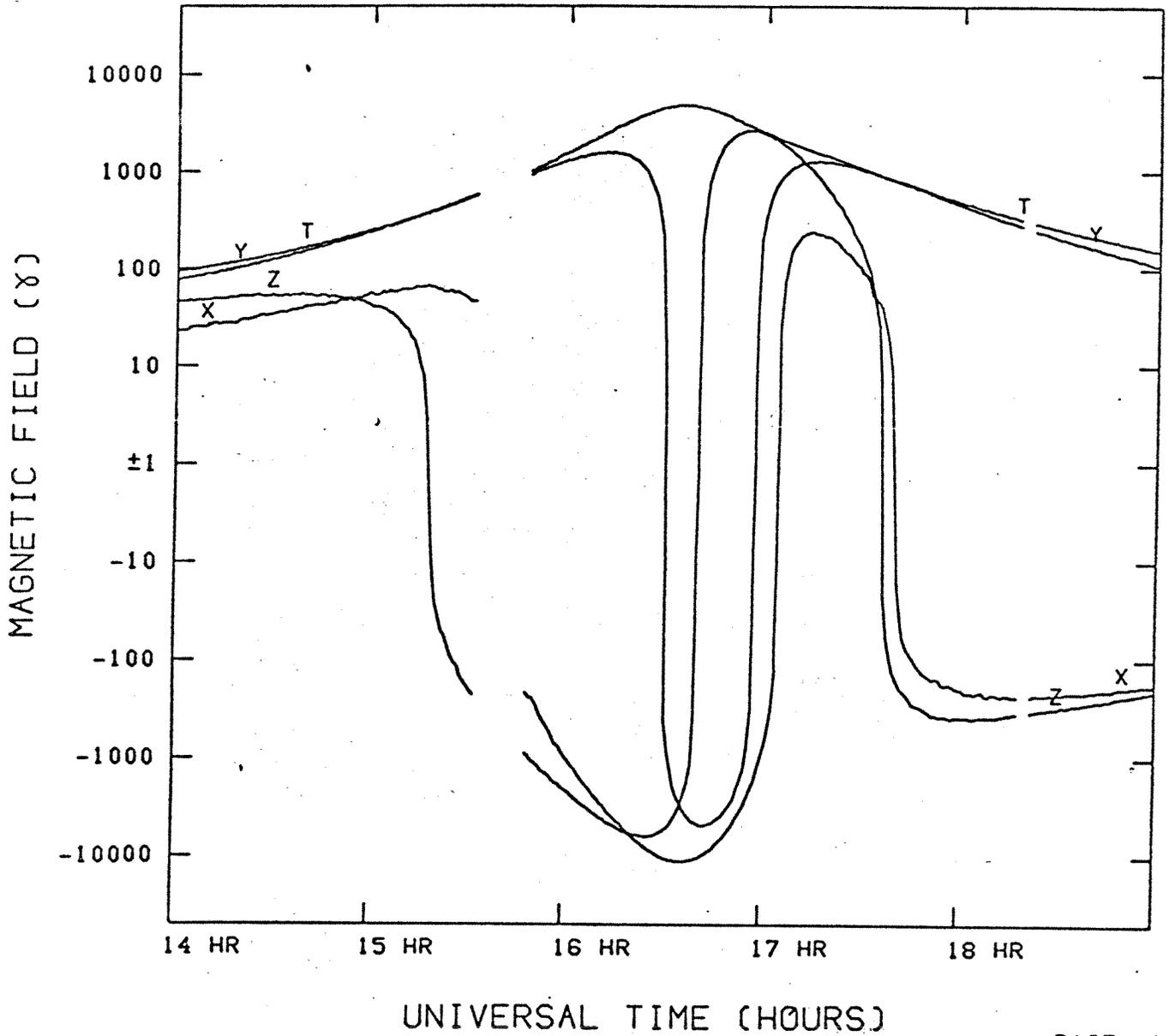


Fig. 6

ORBIT 116 UCLA 060-5 FLUXGATE MAGNETOMETER 28 DEC 1968
 GSE COORDINATES

X	1.52	2.82	3.99	5.06	6.04	RE
Y	-2.60	-2.27	-1.84	-1.35	-0.84	RE
Z	5.09	6.68	7.95	9.01	9.91	RE
R	5.91	7.60	9.08	10.42	11.63	RE

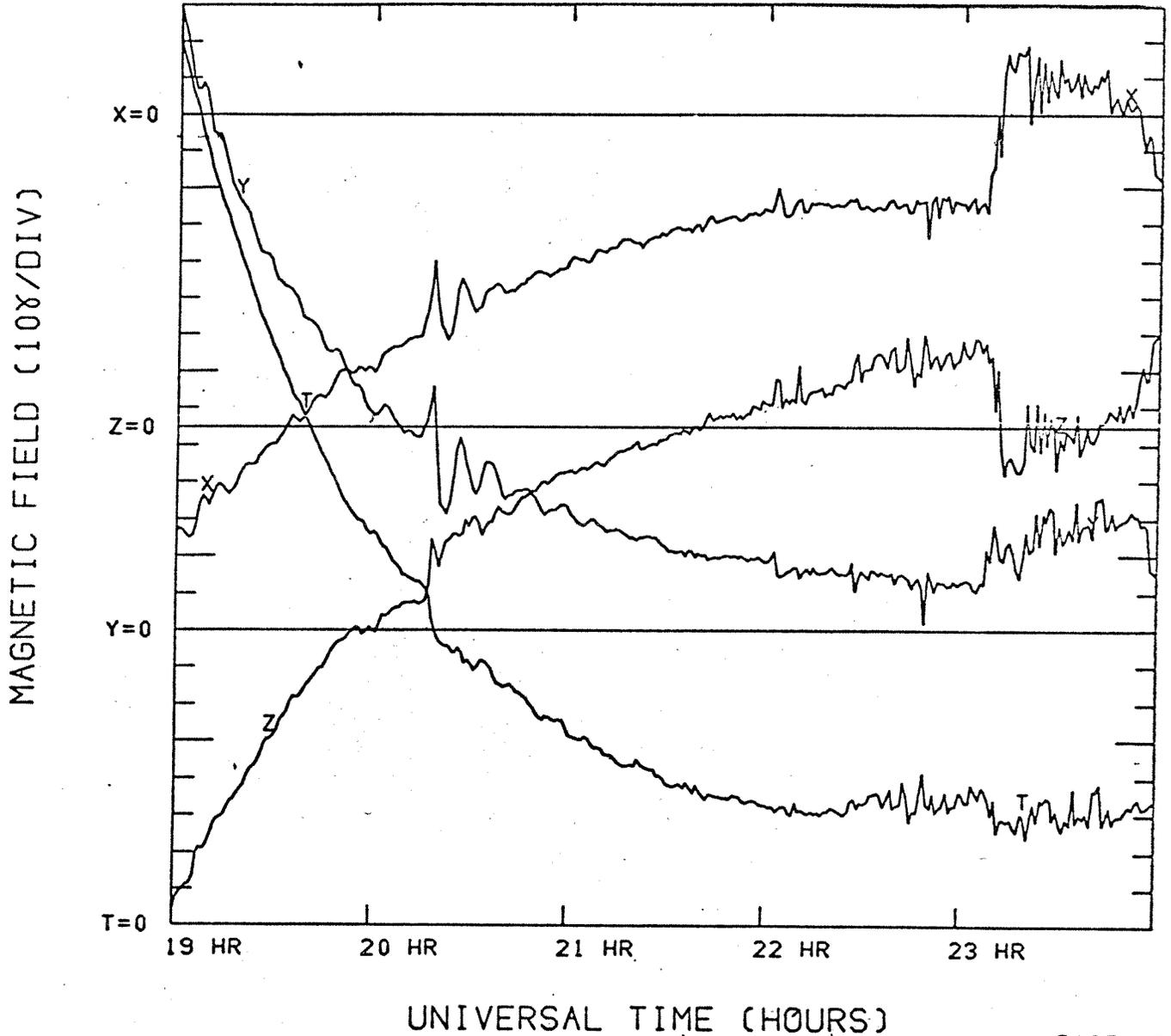


Fig. 7

d) Microfilm Plots in Geocentric Solar Magnetospheric (GSM) Coordinates

These plots are identical to the GSE plots except that the field and the position are given in the GSM system.

e) Magnetic Tapes in Spacecraft Coordinates

These tapes are 9 track, 800 BPI standard labelled binary tapes. They have 5 files per tape, each file corresponding to one orbit. These files usually overlap in time just before perigee. The JCL used to create the tape is

```
//GO.FT10F001 DD DISP=(NEW,KEEP),DSN=BDY001,
// UNIT=2400,LABEL=(1,SL,,OUT),VOL=SER=IG0005,
// DCB=(RECFM=V,LRECL=5128,BLKSIZE=5132)
```

The binary records are written by the Fortran statement:

```
WRITE(10) NREC, (IBT(I), BX(I), BY(I), BZ(I),
BT(I), BXRMS(I), BYRMS(I), BZRMS(I), BTRMS(I),
IQUAL(I), I=1, 128)
```

where

NREC=128

IBT=Bishop time (defined in Appendix)

BX= X component of the field in gammas

BY= Y component of the field in gammas

BZ= Z component of the field in gammas

BT= total field in gammas (obtained by averaging instantaneous values)

BXRMS= X rms deviation in gammas

BYRMS= Y rms deviation in gammas

BZRMS= Z rms deviation in gammas

BTRMS= Total field rms deviation in gammas

IQUAL= Quality indicator

The quality indicator IQUAL is the sum of two numbers, 1000 times NUMPTS + ICHL. NUMPTS is the number of data points used in the average and ICHL is a flag indicating the status of heater, calibration signal and ladder step corrections during the averaging interval.

ICHL may be thought of as a binary number with seven bits:

$X_0, X_1, X_2, X_3, \dots, X_6.$

If X_0 equals 1, then sometime during the averaging interval a heater correction was required but the exact interval for applying this correction could not be found.

If X_2 equals 1, then sometime during the averaging interval a heater correction was applied.

If X_3 equals 1, then a calibration signal correction was made.

If X_4 equals 1, then at least one correction for a medium ladder step on the Z axis was made.

If X_5 equals 1, then at least one correction for a medium ladder step on the Y axis was made.

If X_6 equals 1, then at least one correction for a medium ladder step on the X axis was made.

We note that X_2 is not used, and that this seven bit binary number actually appears in IQUAL as a three digit decimal number.

f) Magnetic Tapes in GSE Coordinates

These tapes are 9 track, 800 BPI, standard labelled binary tapes. They have 5 files per tape, each file corresponding to one orbit. These files usually overlap in time just before perigee. The JCL used to create the tape is:

```
//GO.FT10F001 DD DISP=(NEW,KEEP),DSN=GSE001,
// UNIT=2400,LABEL=(1,SL,,OUT),VOL=SER=IG0006,
// DCB=(RECFM=V,(LRECL=1228,BLKSIZE=1232))
```

Tell ops print P JL

21

The binary records are written by the Fortran statement:

```
WRITE(10)IORBIT,IBTST,XGSE,YGSE,ZGSE,RE,
BXE,BYE,BZE,BTE,IQUAL
```

where: BXE,BYE,BZE,BTE and IQUAL are arrays of 60 elements each and

IORBIT = Orbit number

IBTST = Bishop time of first point in record (Bishop time is defined in appendix)

XGSE = XGSE coordinate of satellite at start of record in Re

YGSE = YGSE coordinate of satellite at start of record in Re

ZGSE = ZGSE coordinate of satellite at start of record in Re

RE = Radial distance of satellite from the center of the earth

in earth radii

BXE = X GSE component of the field in gammas

BYE = Y GSE component of the field in gammas

BZE = Z GSE component of the field in gammas

BTE = Total field magnitude (obtained by averaging instantaneous values)

IQUAL = Quality indicator as explained in previous section.

g) Magnetic Tapes in GSM Coordinates

Format identical to GSE tapes except that field and positional data are in GSM coordinates.

4.608 Second Averages

a) Data Processing

The data processing for the 4.608 second averages is performed at the same time as the one minute averages and is completely analogous to the one minute average processing except that no rms deviations are produced.

b) Microfilm Plots in Spacecraft Coordinates

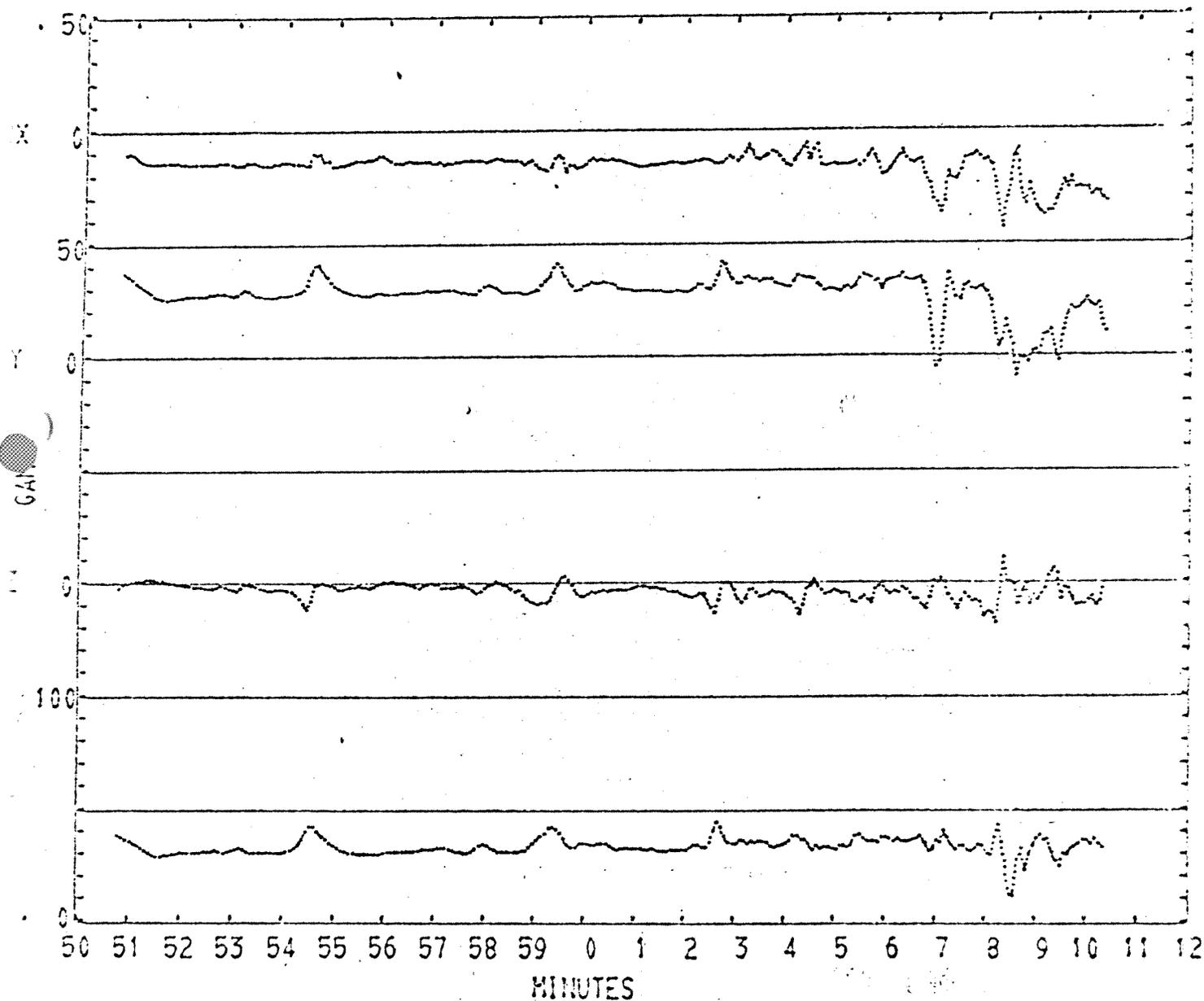
The microfilm plots of the 4.608 averages are produced at the Lawrence Radiation Laboratory, Livermore under the supervision of H.I. West, Jr. The plots are in spacecraft coordinates only and cover 20 minutes of data per frame. Thus there are approximately 180 frames per orbit. The scale on the plots is linear. The usual scale for the plots is 10 gammas per division but near perigee this scale is increased to 100 or 1000 gammas per division as necessary to keep the data on scale.

Figure 8 shows a sample of these plots, for the period of the magnetopause crossing shown in the previous figures (2, 4 and 6). The header at the top of each page identifies the time interval. The orbit number, year, month, day of month, day of year, day from launch and the times of the first and last plotted points on the page are given here. At the bottom of the page is information obtained from the orbit tape. The field given, here, in spacecraft coordinates is that predicted by the reference field only. Also given are the predicted L value, and magnetic latitude, the radial distance to the

CGO V	ORBIT	YEAR	MONTH	DATE	Y DAY	L DAY	HOUR	MINUTES	SECONDS	RECORD	PAGE
INIT.	116	68	DEC	28	363	299	22	50	48.192	55	20
FINAL							23	10	23.232	56	

MAGNETOMETER

1 191



T-ORB	BX	BY	BZ	B	L	MAG LAT	R	PHI	THETA
INIT.	-6.4	16.3	22.3	28.3	15.90	32.17	11.45	351.1	59.6
FINAL	-5.7	15.1	19.6	25.3	16.03	31.03	11.83	353.1	58.2

Fig. 8

satellite and the solar ecliptic longitude and latitude of the satellite.

Occasional errors do appear on these plots and we have not redone these plots to correct them. Some of these errors have been mentioned before: bad telemetry, missed heater corrections and missed calibrate signals, (or incorrectly compensated calibrate signals). Bad telemetry usually shows up as isolated spikes. Missed heater corrections appear as a short duration increase or decrease of 8 gammas on both X and Y axes and no discernible change in Z. Missed calibration signals appear on all three axes. Incorrectly compensated calibrations may only appear on one axis but its 4 steps are usually recognizable. Plotting errors can also occur on these plots. These usually result in missing data, or incomplete plots. Also the zero levels on the plots and tapes for orbits 1-37 may be slightly different due to reprocessing of the tape when better offsets were determined. When differences are noted, the tape contains the correct values.

d) Magnetic Tapes

These tapes are 9 track standard labelled binary tapes. They have 5 files per tape, each file corresponding to one orbit. These files usually overlap in time just before perigee. The JCL used to create the tape is:

```
//GO.FTIOF001 DD DISP=(NEW,KEEP),DSN=PNT001,UNIT=2400,  
  
// LABEL=(1,SL,,OUT),VOL=SER=IG0012,  
  
// DCB=(RECFM=V,LRECL=3080,BLKSIZE=3084)
```



The binary records are written by the Fortran statement.

```
WRITE(10)NREC,(IBT(I),BX(I),BY(I),BZ(I),BT(I),IQUAL(I),  
I=1,128)
```

where NREC = 128

IBT = Bishop time of data (see appendix)

BX = X spacecraft component of the field in gammas

BY = Y spacecraft component of the field in gammas

BZ = Z spacecraft component of the field in gammas

BT = total field in gammas

IQUAL = Quality indicator as explained in a previous section

Appendix

Bishop time is the name of the unit of time used for the majority of the processing of the OGO-5 and ATS-1 fluxgate magnetometer data at UCLA. It is defined as the number of tenths of seconds since the start of the year 1966, that is, Bishop time equals zero, at 0000 U.T. on January 1, 1966. The advantage of using Bishop time is that one single 360 word can be used to cover a period of six years. Six years is longer than the life-expectancy of most satellites. The disadvantage is that this time word cannot be used to provide timing for the high telemetry rate data of OGO-5. This problem does not arise for the data discussed in this report because the highest sample rate given on these tapes is one point every 4.608 seconds.

On the next page is the listing of a subroutine to convert from Bishop time to ordinary Universal time and vice versa. The entry point BTCON converts from Bishop time while the entry point CONBT converts to Bishop time.

```

SUBROUTINE CONBT ( T, BT )
*****
C * 'BISHOP TIME' CONVERSION SUBROUTINE FOR OGO-5. BT IS DEFINED AS THE
C * NUMBER OF TENTHS OF A SECOND SINCE THE START OF YEAR 1966, THAT IS,
C * BT = 0 AT YR 66 DAY 1 HR 0 ETC., AND THE TIME UNIT IS 1/10 SEC.
C * CALL CONBT( T, BT ) CONVERTS T ARRAY TO BT.
C * CALL BTCON ( BT, T ) CONVERTS BT TO T ARRAY.
C * THE T ARRAY IS DEFINED AS FOLLOWS:
C * T(1) = YEAR (66-71) T(5) = HOUR (0-23)
C * T(2) = DAY OF YEAR (1-366) T(6) = MINUTE (0-59)
C * T(3) = MONTH (1-12) T(7) = SECOND (0-59)
C * T(4) = DAY OF MONTH (1-31) T(8) = MILLISECOND (0-999)
C * WHEN CONVERTING TO BT, T(3) AND T(4) ARE USED ONLY IF T(2) = 0.
C * OTHERWISE T(3) AND T(4) ARE IGNORED. WHEN CONVERTING FROM BT, ALL
C * EIGHT ENTRIES OF THE T ARRAY ARE COMPUTED.
C * THE SUBROUTINE FAILS AFTER FEB. 28, 1972 AND BISHOP TIME
C * OVERFLOWS THE 360, WORD LATER THAT YEAR.
C * PROGRAMMER - NEAL CLINE JAN. 1968
C *****
INTEGER T(8), BT, M(13)
* / 0, 31, 59, 90, 120, 151, 181, 212, 243, 273, 304, 334, 365 /
N = ( T(1) - 66 ) * 365
IF ( T(1) .GT. 68 ) N = N + 1
IF ( T(2) .NE. 0 ) GO TO 10
N = N + M(T(3)) + T(4) - 1
IF ( T(3) .GT. 2 .AND. T(1) .EQ. 68 ) N = N + 1
GO TO 20
10 N = N + T(2) - 1
20 BT = N*864000 + T(5)*36000 + T(6)*600 + T(7)*10 + T(8)/100
RETURN
ENTRY BTCON ( BT, T )
N = BT / 864000
IF ( N - 1095 ) 50, 30, 40
30 T(1) = 68
T(2) = 366
GO TO 60
40 N = N - 1
50 T(1) = N/365 + 66
T(2) = MOD( N, 365 ) + 1
60 N = T(2)
IF ( T(1) .NE. 68 ) GO TO 90
IF ( N - 60 ) 90, 70, 80
70 T(3) = 2
T(4) = 29
GO TO 120
80 N = N - 1
90 DO 100 K = 2, 13
IF ( N .LE. M(K) ) GO TO 110
100 CONTINUE
110 T(3) = K - 1
T(4) = N - M(K-1)
120 T(5) = MOD( BT/36000, 24 )
T(6) = MOD( BT/600, 60 )
T(7) = MOD( BT/10, 60 )
T(8) = MOD( BT, 10 ) * 100
RETURN
END

```

\$JOB 13:03:25
SNOP DUMP OF X-379
SASS IN MS4
SEXEC DPHEX BS
INPUT TAPE ON MS4

25 FILES

060-5

HFI

TIME = BISHOP TIME

03/05/68 - 05/08/68

D-29194

DATA INPUT 1 1 1

FILE	1	RECORD	1	LENGTH	3184 BYTES						
(40)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	00000000	28E82B2E
(80)	00000000	28E82B8A	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(120)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(160)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(200)	00000000	28E82C70	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(240)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(280)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(320)	00000000	28E82D57	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(360)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(400)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(440)	00000000	28E82E3D	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(480)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(520)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(560)	00000000	28E82F23	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(600)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(640)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(680)	00000000	28E8300A	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(720)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(760)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(800)	00000000	28E830FC	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(840)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(880)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(920)	00000000	28E83167	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(960)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1000)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1040)	00000000	28E832B0	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1080)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1120)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1160)	00000000	28E833A3	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1200)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1240)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1280)	00000000	28E8348A	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1320)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1360)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1400)	00000000	28E83570	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1440)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1480)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1520)	00000000	28E83657	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1560)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1600)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1640)	00000000	28E8373D	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1680)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1720)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1760)	00000000	28E83823	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1800)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1840)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1880)	00000000	28E8390A	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1920)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(1960)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(2000)	00000000	28E839F0	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(2040)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(2080)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(2120)	00000000	28E83AD7	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(2160)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00
(2200)	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00	45186A00

[28E82B00]

CONVERT TO
DECIMAL AND
THAT = 1/10 OF
A SEC.

DIVIDE DECIMAL
BY 864,000
AND GIVES YOU
OF DAYS.

START FROM
YR 66 AT
DAY 1.

EXAMPLE: (535)
DAYS WOULD BE
535
-365
170 DAY 170
WHICH IS 06/20/68

(1800)	C2AA400F	43165EE9	0003E801	28FFC0FA	427D2A0D	43121A85	C2AA8BFE	43166AEE	0003E800	427B51C8	43121BF4
(1840)	427F2887	431218A4	C2AAF32A	431677B0	0003E800	28FFCD57	428112F5	43121635	C2AB6AC1	43168433	28FFCD28
(1880)	0003E800	28FFCD85	428318E1	43121500	C2ABC237	43169182	0003E800	28FFCDB3	42851026	4312143A	
(1920)	C2AC2A25	43169F78	0003E800	28FFCDE1	42871079	43121207	C2AC9460	4316ADAB	0003E800	28FFCE0F	
(1960)	42891BE9	43120FE3	C2AD05DF	4316BAA6	0003E800	28FFCE3D	428B3760	43120CB0	C2AD7546	4316C837	
(2000)	0003E801	28FFCE6B	428D49FC	43120789	C2ADF5CA	4316D486	0003E800	28FFCE99	428F4AEF	4312059D	
(2040)	C2AE65EE	4316E301	0003E800	28FFCEC7	42915734	43120300	C2AEE869	4316F16C	0003E800	28FFCEF5	
(2080)	429376DB	4311FDE3	C2AF7C8A	4316FFAD	0003E800	28FFCF23	42957DD5	4311F9C6	C2B01312	43170E05	
(2120)	0003E800	28FFCF51	429783FC	4311F430	C2B0723E	43171986	0003E800	28FFCF80	42998972	4311EDDB	
(2160)	C2B10749	43172695	0003E800	28FFCFAE	429B8576	4311E952	C2B1662E	43173324	0003E801	28FFCFDC	
(2200)	429D6FD7	4311E40B	C2B1DB01	43173FE7	0003E800	28FFD00A	429E692A	4311E10C	C2B2441B	43174DFE	
(2240)	0003E800	28FFD038	42A166EE	4311DCE3	C2B2B47A	43175B9B	0003E800	28FFD066	42A34EA8	4311D855	
(2280)	C2B32816	431768D0	0003E800	28FFD094	42A54485	4311D27C	C2B3A3E0	431775D0	0003E800	28FFD0C2	
(2320)	42A73CCA	4311CBE2	C2B42687	431782A8	0003E800	28FFD0FD	42A93FD7	4311C596	C2B4C06E	431790E3	
(2360)	0003E800	28FFD11E	42AB61DD	4311BFED	C2B55C88	4317ACAB	0003E801	28FFD14C	42AD58C4	4311B8BD	
(2400)	C2B5FAA6	4317AE55	0003E800	28FFD17A	42AF6D4B	4311B2FD	C2B6710B	4317BCED	0003E800	28FFD1A8	
(2440)	42B1397C	4311AE2F	C2B70956	4317CB43	0003E804	28FFD1D7	42B324CB	4311A720	C2B77D06	4317D7DC	
(2480)	0003E800	28FFD205	42B4FA1E	4311A262	C2B7FEF9	4317E618	0003E800	28FFD233	42B6DA89	43119E19	
(2520)	C2B88974	4317F55F	0003E800	28FFD261	42B8C8C4	431198E8	C2B8ECC0	43180357	0003E800	28FFD28F	
(2560)	42BAE113	431192B8	C2B9346D	4318112A	0003E801	28FFD2BD	42BCCD8B	43118C4D	C2B99357	43181E56	
(2600)	0003E800	28FFD2EB	42BEAE11	4311855F	C2BA1621	43182BFD	0003E800	28FFD319	42C09073	43117DC0	
(2640)	C2BA95C6	4318393C	0003E800	28FFD347	42C289A7	43117485	C2BB2A90	431846F3	0003E800	28FFD375	
(2680)	42C480EE	43116CE8	C2BBD0B2	4318562B	0003E800	28FFD3A3	42C66E9A	43116423	C2BC7858	43186497	
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(2760)	C2BDC74B	43188367	0003E800	28FFD42E	42CC5E92	43114BB6	C2BEEF74	43189737	0003E801	28FFD45C	
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(3000)	C2C36C24	4319195E	0003E800	28FFD5FA	42DF5611	4310F877	C2C3D0DC	431926E5	0003E800	28FFD628	
(3040)	42E1571D	4310EE6B	C2C459A4	43193626	0003E800	28FFD657	42E33AEE	4310E555	C2C4EFOE	4319458D	
(3080)	0003E800										

FILE	1	# OF DATA RECORDS	263	# SUCCESSFUL READS	263
	# PERMANENT READ ERRORS	0	# ZERO BYTE ERRORS	1	# SHORT RECORDS
	# OF RECORDS RETRIED	1	TOTAL # OF RETRIES	1	# UNDEFINED ERRORS
				0	0

DATAFILE FORMER, INC. - W

(2320)	45186A00	45186A00	45186A00	45186A00	00000000	28E83C75	45186A00	45186A00	45186A00	28E83C47
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(2440)	45186A00	45186A00	45186A00	45186A00	00000000	28E83D5C	45186A00	45186A00	45186A00	45186A00
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(1160)	0003E800	28FFC81E	4245DF69	43122048	C29E9F95	43151DDC	0003E800	28FFC84C	4247DD09	4312218D	
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(1480)	42618804	43122826	C2A45F07	4315B845	0003E800	28FFCAA3	4262A681	43122773	C2A4EDFB	4315C497	
(1520)	0003E800	28FFCAD1	4264C083	431226D4	C2A55A20	4315D0E4	0003E800	28FFCB00	4266CED6	4312277E	
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(1600)	428AE5E4	431225E5	C2A89B93	4315E6C9	0003E801	28FFCB8A	426CDED5	4312242D	C2A6F5E6	4316D1AF	
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RECORD 3899 OF FILE 1
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