



## TIDI CDR

# Telescope Positioning System

Jon Harvey

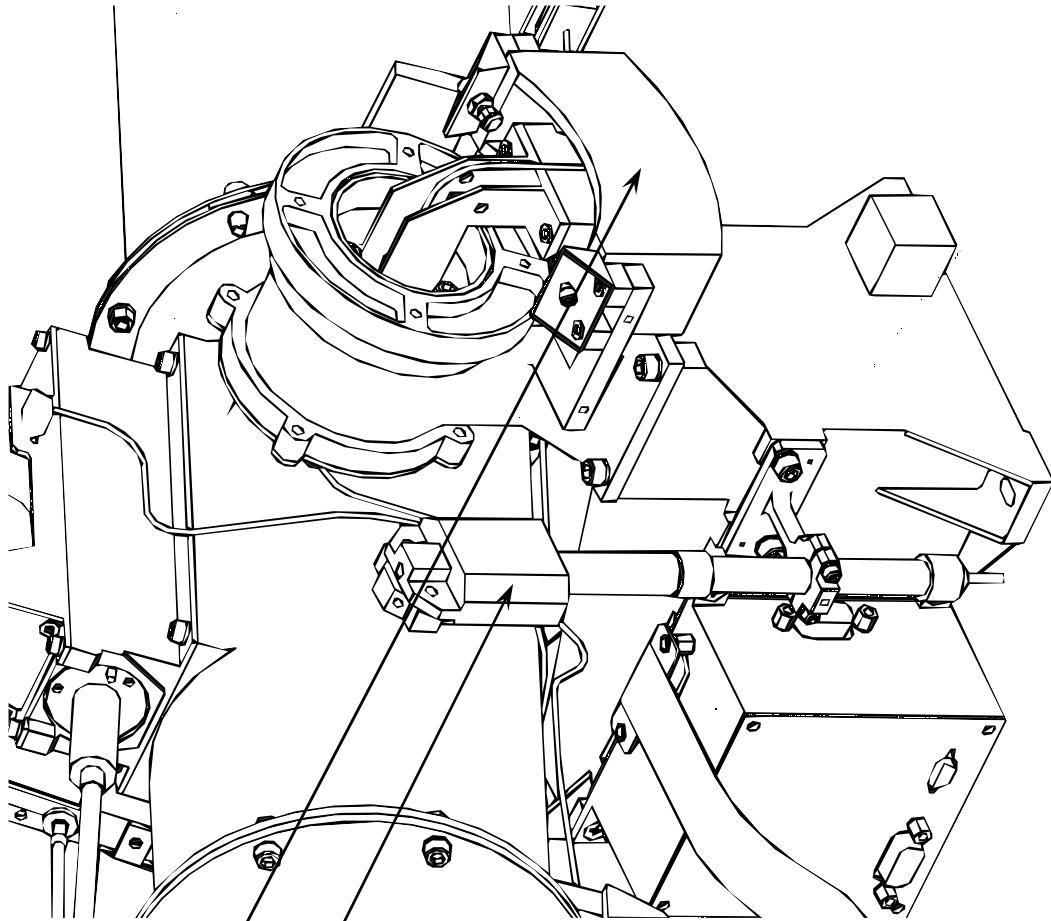
TIDI Mechanical Engineer

(734) 764-6594

[jdh@engin.umich.edu](mailto:jdh@engin.umich.edu)

- **Position Detection**
  - Requirements
  - Configuration
  - Structural, Thermal, Radiation Design
  - Torque
- **Drive System**
  - Torque Margins

## TELESCOPE MECHANISMS



- BEI voice coil
- LVDT actuation mechanism
- Flight Assemblies delivered to APL - Aug 1998

## POSITION DETECTION SYSTEM

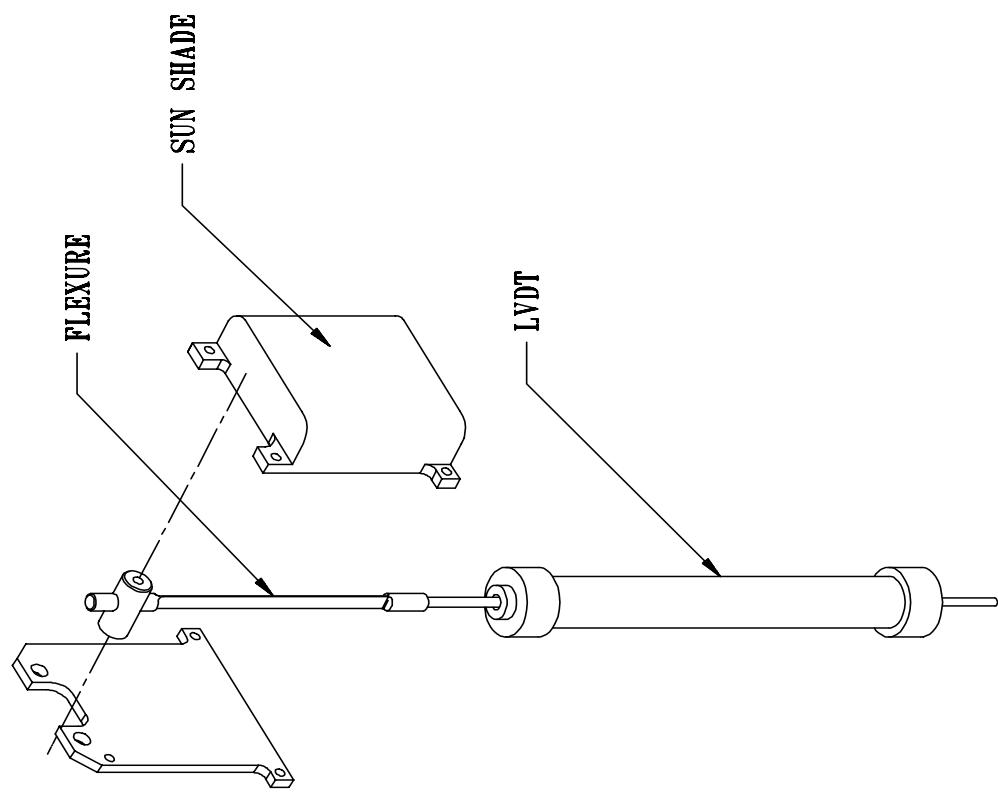
---

- **LVDT Mechanism Requirements**

- Convert rotary motion of telescope to a linear motion for the LVDT
- Accuracy (Knowledge)      60 arcsec (LVDT and Mechanical)
- Lifetime                      1 million cycles (2 year life, baseline scan)
- 5 krad                        0.03 in Tantalum to susceptible components in pre-amp  
                                    < 1.0 oz-in
- Low Torque
- Thermal Transients  
Sun shade/ worst case @ terminator reduced position requirement

# POSITION DETECTION CONFIGURATION

- **Mechanical Configuration**



- Telescope interfaces
- Flexure mount
- Lvd<sup>t</sup> Mount
- Upper Sun Shade Mount
- Ti-6Al-4V Flexure/Link rod to match Tel. Pedestal CTE
- Alum. sun shade to reduce thermal transient effects
- Vespel SP-3 Bushings to prevent LVDT Core rubbing LVDT ID.

## POSITION DETECTION SYSTEM

---

- Structural Design

- Minimum thickness (0.007 - 0.010 in) and maximum length ( 1.80 in)  
to minimize stress in flex element
- Fatigue life = 1million cycles (Baseline scan  $\pm$  5 deg, 2 year life)  
Ti engineering flexure tested to 1 mil cycles ( $\pm$  10 deg.)  
40 flight like samples testing to 2 mil + cycles ( $\pm$  10 deg)
- Surface treatment: 16 micro finish, Tiodize coating

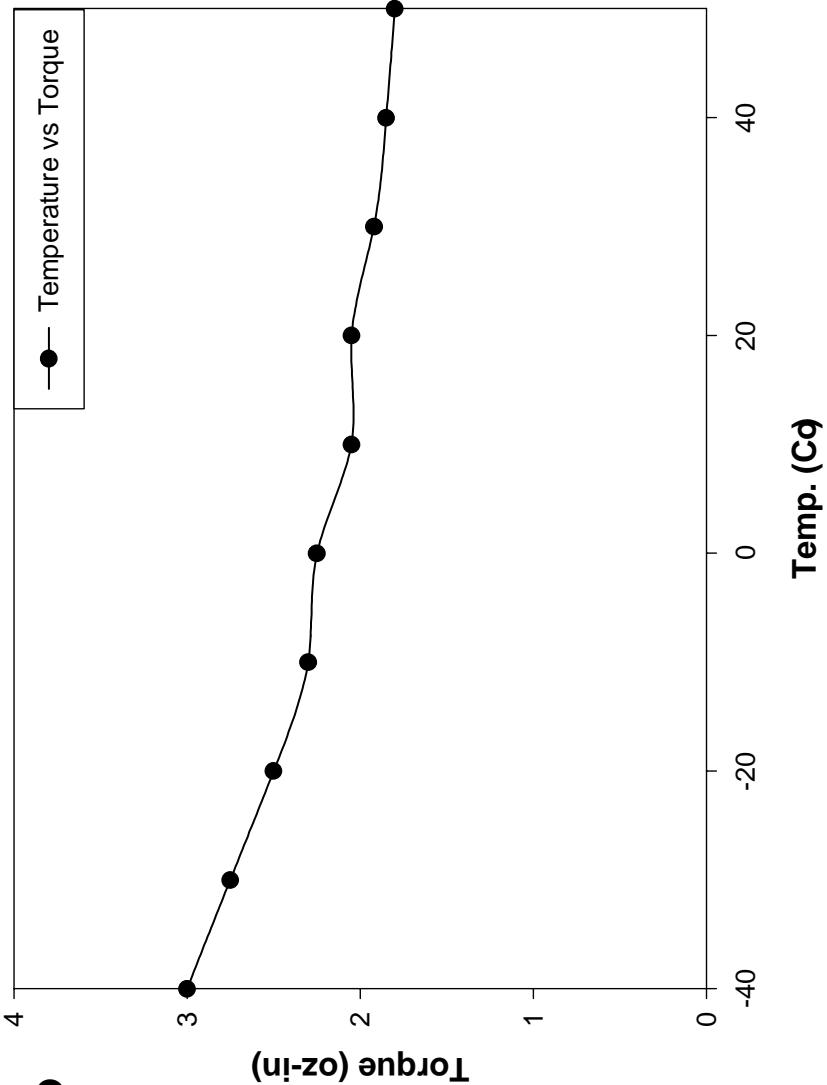
- **Rotary Voice Coil, BEI Model RA68-12-001**

- Rated Peak torque                                    170 in-oz
- De-rated for TIDI to                                50 in-oz
- Stroke (motor max.)                                 $\pm 11.0$  deg.
- Average power dissipation                            0.058 watts (Baseline scan)
- Max power dissipation                                3.0 watts (continuous stall)
- Materials changed to comply with 1% TML and 0.1% VCM

## TORQUE TEST RESULTS

- **Mechanical Model Torque Test Results**

- Combined drag torque
- Ti 6Al-4V Bearing cell
- Similar geometry to APL design.



## MECHANISMS SUMMARY

---

- Mechanisms Summary
  - Life tests
  - Torque margin
  - Torque upsets

MECHANISM	MFG TEST (CY)	2 YEAR LIFE* (CY)	RATED TORQ. (OZ-IN)	DRAG TORQ (OZ-IN)	ACCEL. TORQ. (OZ-IN)	MARGIN
TELESCOPE ACTUATOR	BEI NA	650000	50.0**	5.0 max	45	10:1
FILTER WHEEL	LITTON 263865 M .	325000	5.9	0.36	5.54	16:1
SHUTTER	LITTON 263865 M .	<< Filter Wheel	5.9	0.36	5.54	16:1

\* BASED ON THE BASELINE SCIENCE SCAN.

\*\* DERATED FROM 170 oz-in.

# TORQUE UPSETS

MANEUVER		FORCE (N)	TORQUE (N·m)
Filter Wheel 45° ( dt=0.143s)	0.0715 s	0X+0Y+0Z	0X + 0.0426Y + 0Z
	0.0715 s		0X - 0.0426Y + 0Z
Filter Wheel 90° ( dt=0.202s)	0.101 s	0X+0Y+0Z	0X + 0.0426Y + 0Z
	0.101 s		0X - 0.0426Y + 0Z
Filter Wheel 120° ( dt=0.247s)	0.124 s	0X+0Y+0Z	0X + 0.0426Y + 0Z
	0.124 s		0X - 0.0426Y + 0Z
Filter Wheel 180° ( dt=0.286s)	0.143 s	0X+0Y+0Z	0X + 0.0426Y + 0Z
	0.143 s		0X - 0.0426Y + 0Z
Telescopes 0.050° Step (dt = 0.10 s)	0.05 s	0X+0Y+0Z	+0.0076*
	0.05 s		-0.0076*
Telescopes 0.100° Step (dt = 0.10 s)	0.05 s	0X+0Y+0Z	+0.0157*
	0.05 s		-0.0157*
Telescopes 0.150° Step (dt = 0.10 s)	0.05 s	0X+0Y+0Z	+0.0228*
	0.05 s		-0.0228*
Telescopes 0.400° Step (dt = 0.10 s)	0.05 s	0X+0Y+0Z	+0.0371*
	0.05 s		-0.0371*
Telescopes 20.0° Step (dt = 1.5 s) (Bearing scan)	0.75 s	0X+0Y+0Z	+0.0113*
	0.75 s		-0.0113*

\* Maximum torque with a 10% imbalance between any two telescopes. Direction vectors dependant on assignment of telescope location. No Z component of telescope torque.