



Flight Software

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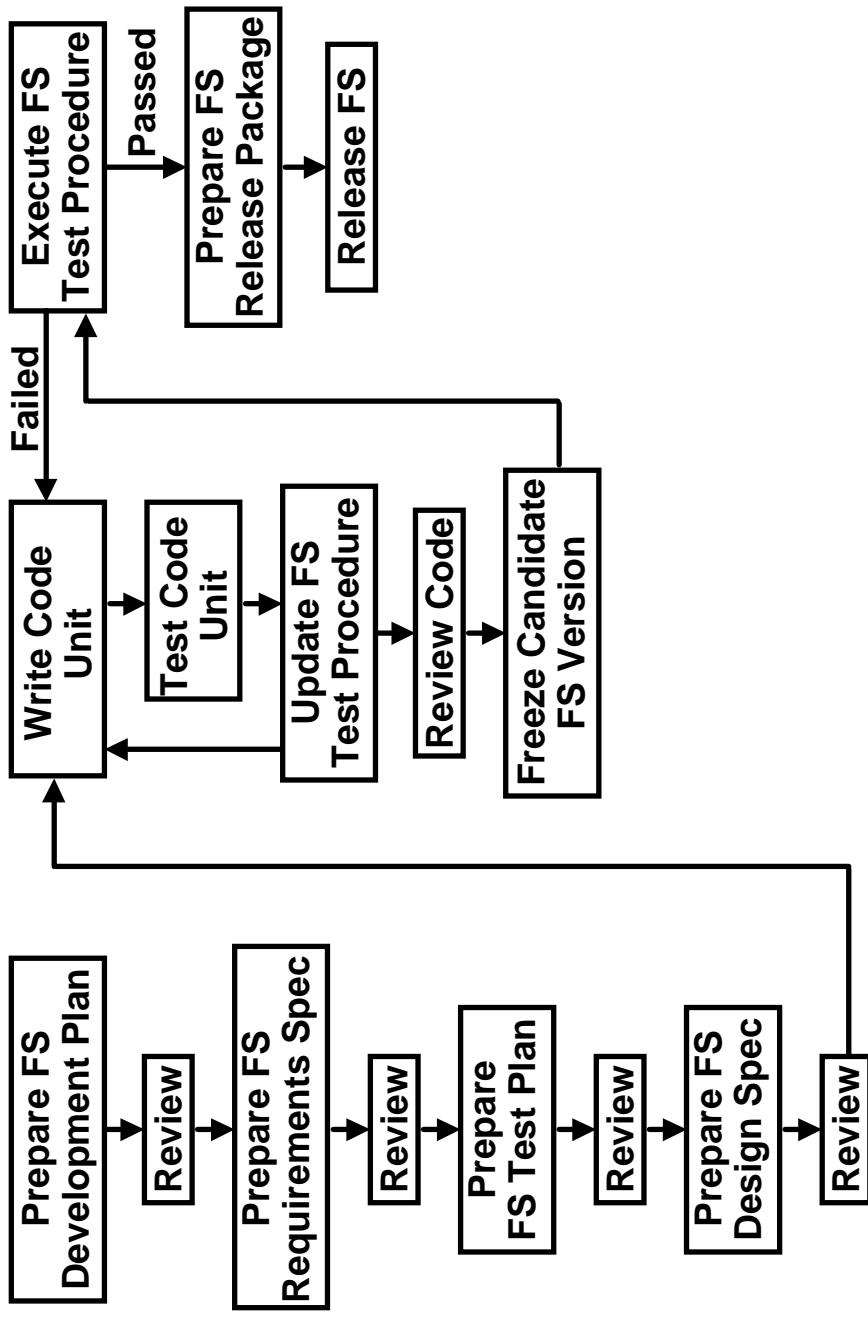
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Flight Software Topics

- Development Process & Documents
 - Status
 - Software Development and Test System
 - Requirements
 - Design
 - Memory Usage and Performance
- Test Plan
- Changes from PDR

Flight Software Development Process & Documents

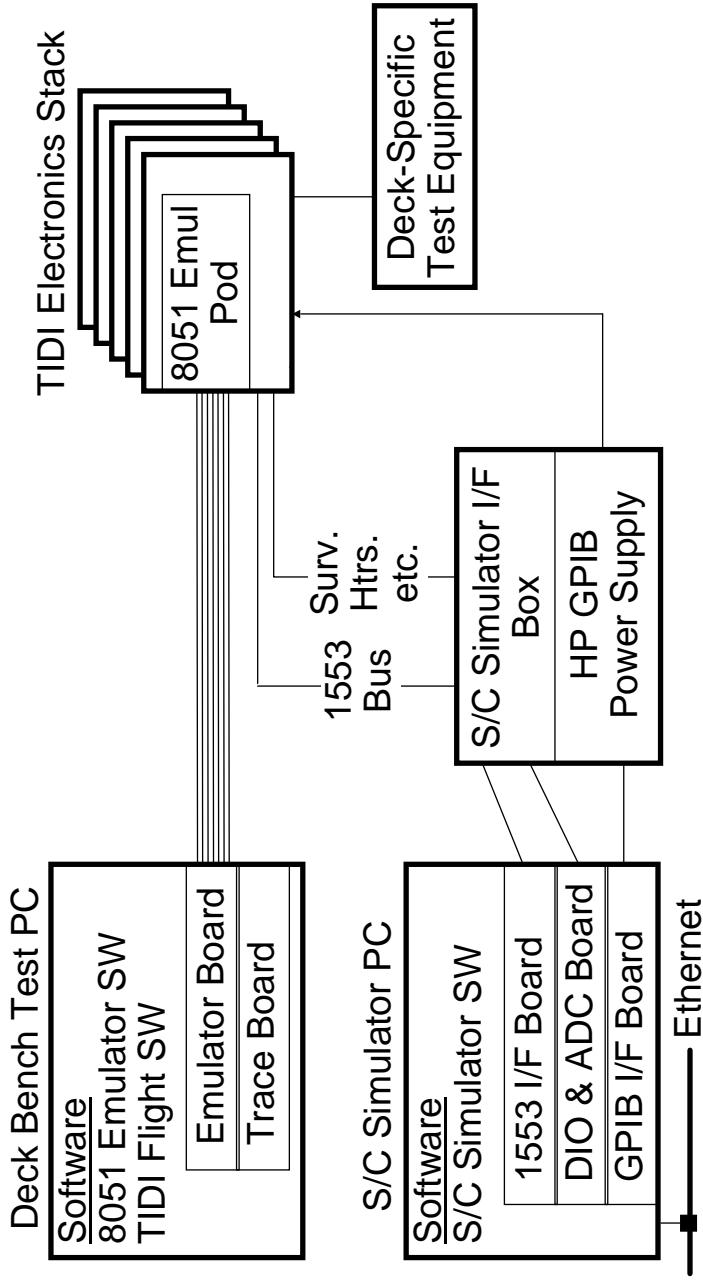




Flight Software Status

- Requirement Spec completed
- Design Spec completed
- Coding and Unit Test 50% completed - will be completed 9/1/98
- Test Plan completed
- Test Procedure will be completed 12/1/98

Flight Software Bench Test System





Flight Software Software Development Tools

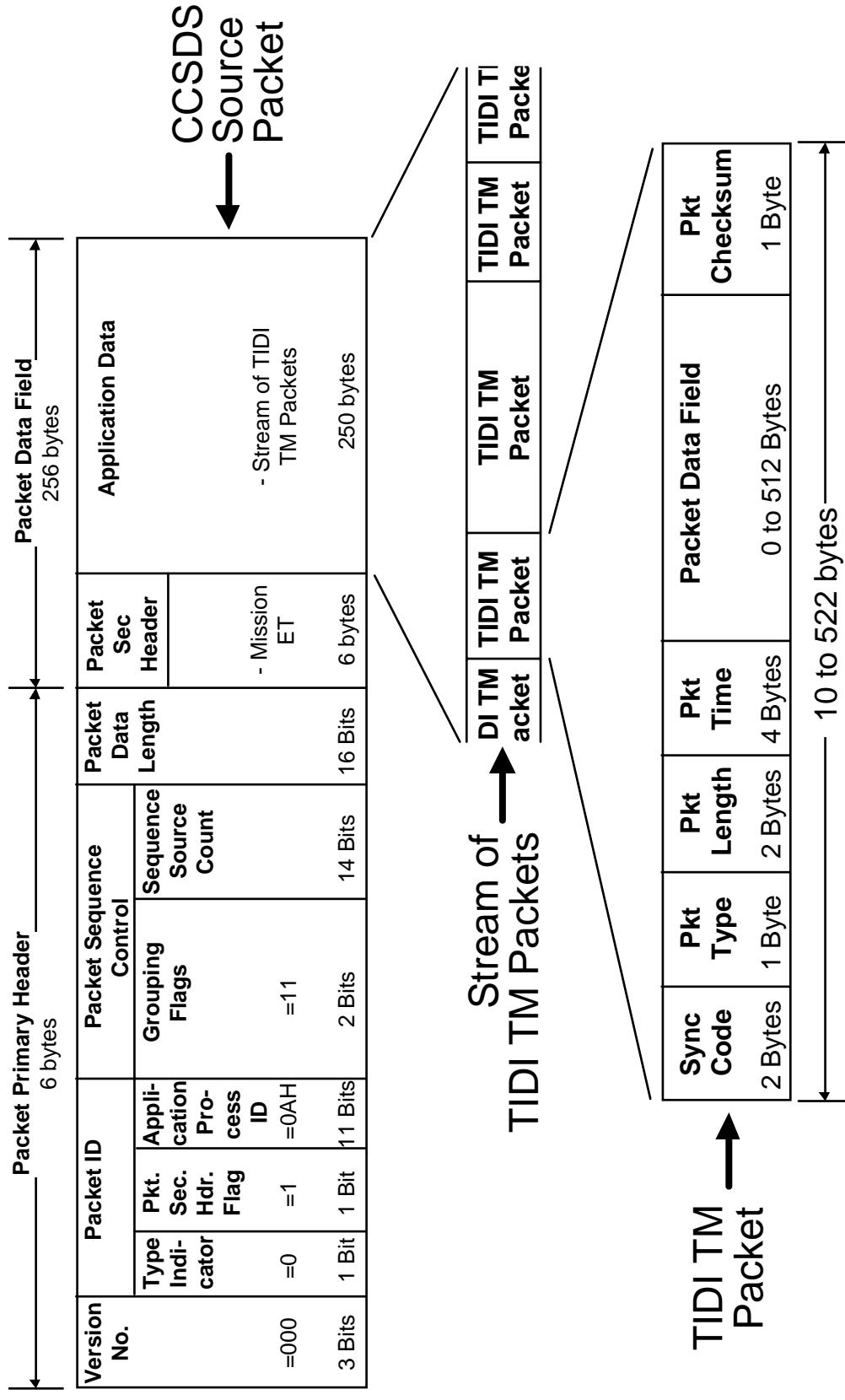
- Keil 8051 C Compiler
- Keil 8051 Simulator
- MKS Source Integrity Version Control System
- Opus Make
- Codewright Editor

Flight Software Requirements

- Execute commands from 1553 bus
- Execute Control Program
 - Control Scanning
 - Control Temperatures
 - Control shutters and telescope positions for Sun avoidance
 - Read housekeeping sensors
 - Sync instrument time with S/C time
 - Format and transmit science and engineering TM
- Respond to spacecraft warnings
 - Solar panel rotation
 - Loss of attitude control
 - Power down
- Limit check critical housekeeping values

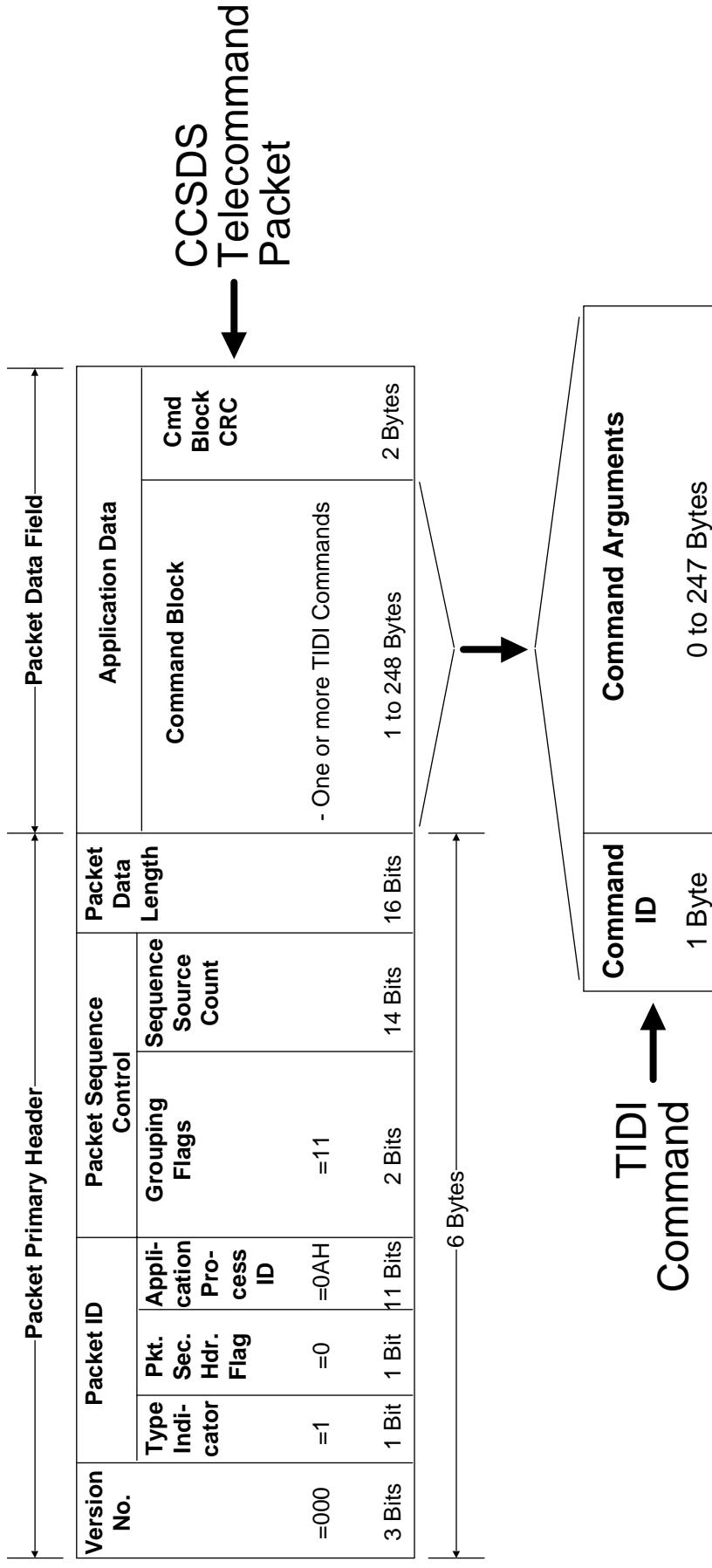
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Telemetry Packetization





Flight Software Command Packetization



Flight Software

Instrument Status Word

- **64 bits of instrument status that is inserted in S/C real time telemetry**
- **Not packetized**
- **Transmitted to S/C via dedicated 1553 subaddress**
- **Updated by the instrument at 1 Hz.**

- **Status Word Values**
 - Aliveness Toggle 1 bit
 - Inst. Autonomy Bit 1 bit
 - CMD Packet Count 3 bits
 - Cmd Reject Count 3 bits
 - Error Count 4 bits
 - Error Pkt. Sent 1 bit
 - Reboot Flag 1 bit
 - Limit Flags 10 bits
 - Position Error Flags 6 bits
 - Filter & Shutter Pos. 10 bits
 - Boot Code Flag 1 bit
 - Mechanism Moved 1 bit
 - Cal. Lamp States 4 bits
 - Spare 18 bits

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Boot Code vs. Instrument Software

- **Boot Code**
 - Executes after CPU reset
 - Stored in PROM
 - Executes out of PROM
 - Automatically boots the Instrument Software
 - Limited command set
 - Special version for thorough memory testing
- **Instrument Software**
 - Stored in EEPROM (uploadable)
 - Executes out of RAM
 - Full command set

Flight Software Boot Code Commands

- Disable Autoboot
- Boot Now
- Write Memory
 - RAM
 - EEPROM
 - I/O Registers
- Dump Memory
 - PROM
 - RAM
 - EEPROM
 - I/O Registers
- Calculate Cyclic Redundancy Check (CRC)
- Execute RAM Code
- No Operation

Flight Software Instrument Software Commands

- **Control Program Execution**
 - Start Control Program
 - Stop Control Program
 - Clear Control Program Buffer
 - Append to Control Program Buffer
 - Jump
 - Jump if Equal
 - Jump if Not Equal
 - Jump if Greater Than
 - Jump if Less Than
 - Wait
 - Call Subroutine
 - Return from Subroutine
- **Parameter Manipulation**
 - Load Parameter
 - Add Parameter
 - Subtract Parameter
 - Increment Parameter
 - Decrement Parameter
 - Compare Parameter

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Instrument Software Commands (cont)

- **Hardware Control**
 - Load Scan Table
 - Start Scanning
 - Stop Scanning
 - Set Filter Wheel Position
 - Set Calibration Lamp States
 - Set Telescope Elevation
 - Set Shutter Position
 - Clear CCD Binning Table
 - Append to CCD Binning Table
- **Miscellaneous**
 - Write Memory
 - Dump Memory
 - Calculate CRC
 - Execute RAM Code
 - No Operation
 - Let Watchdog Timeout

Flight Software Instrument Control Program

- **Control Program**
 - Comprises a block of commands
 - Loaded with Append to Control Program command
 - Executed continuously by the Instrument Software
 - Has access to the Instrument Parameter Table
- **1553 commands have priority over the Control Program**
- **Default Control Program is stored in EEPROM**
 - Loaded and executed at initialization
 - Used for parameter set up, default scan control etc.

Flight Software Commandable Instrument Parameters

- **Commandable Parameters**

- PI Temp Controller Parameters
- Heater Duty Cycles (when PI temp control is disabled)
- Sun Avoidance Mode Entry Sun Angle
- Sun Avoidance Mode Exit Sun Angle
- CCD Control Parameters
- Telescope Control Parameters
- Earth Oblateness Comp. On/Off
- Control Program Global Variables
- Status TM Packet Rate
- Control Program Execution Time
- Red and Yellow Limits

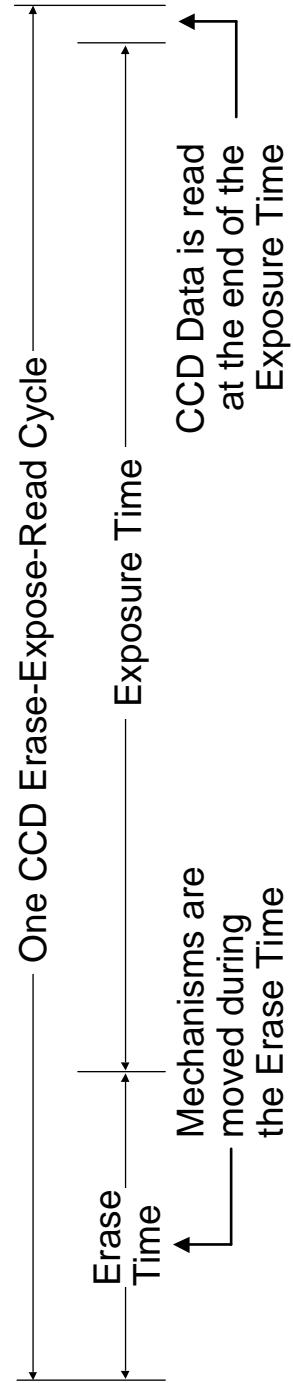
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Non-commandable Instrument Params

- **Instrument Status**
 - Analog Sensor Readings
 - Filter Wheel Positions
 - Telescope Positions
 - Current Scan Table ID
 - Commanded Shutter Positions
 - Filter Wheel Position Error Flags
 - Telescope Position Error Flags
 - Latched Reboot Flag
 - Scanning Flag
 - Executing Control Program Flag
 - Other miscellaneous status
- **Spacecraft Status**
 - Most Recent Terminator Crossing
 - Most Recent Node Crossing
 - Universal Time
 - Latitude, Longitude, Altitude
 - Velocity
 - Yaw, Pitch, Roll
 - Sun Vector
 - Latched Warning Flags
 - Solar Panel Rotation
 - Yaw Maneuver
 - Loss of Attitude Control
 - Power Down

Flight Software Scanning Control

- **Scanning is the coordinated control of:**
 - Telescope, Filter Wheel and Shutter Positions
 - Calibration Lamp states
 - CCD Erase and Exposure Times
 - CCD ADC Gain
 - Science Data Mode
- **Scan timing is controlled by the Scan Table**
- **Scanning is started and stopped via command**



Flight Software Science Data TM Packets

- 4 Science Data TM Packet Types
 - Spectral Science Data TM Packets contain 120 14-bit channel values
 - Calibration Science Data TM Packets contain 150 14-bit channel values
 - CCD Image Science Data TM Packets contain 50 x 300 14-bit pixel values
 - Photometric Science Data TM Packets contain 5 14-bit photometric values
- All Science Data TM Packets contain:
 - Data Validity Flags
 - Mechanism Positions and Position Error Flags
 - Calibration Lamp States
 - Instrument Time at start of CCD exposure
 - Scan Table ID
 - Exposure Count

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Miscellaneous TM Packet Types

- **Status TM Packet**
 - Contains all Instrument Parameter Values except Control Program Global Variables
 - Programmable packet transmission rate (1 pkt/sec or slower)
- **Command Confirmation Packet**
 - Memory Dump Packet
 - Control Program Global Variable Dump Packet
- **CRC TM Packet**
- **Error Report Packet**
- **Null Packet**



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TM Production

	TIDI TM Pkt Size (bits)	TIDI TM Pkt Rate (pkts/sec)	CCSDS Source Pkt Overhead (bits/sec)	Total TM Rate (bits/sec)	
Science Data TM Packet	1872	1	1872	74	1956
Status TM Packet	2704	0.1	270	11	281
Margin					257
					2494

Flight Software Top Level Design

- **Code is divided into**
 - Interrupt code (High Priority)
 - Interrupt Service Routines**
 - Event Service Routines**
 - Non-interrupt code (Low Priority)
 - Main Loop**
 - Tasks**
 - Utility Routines**
- **Tasks are state machines called from a main loop**
 - Each task limits its own execution time
- **Tasks share the CPU through cooperative multitasking**
 - **Same architecture used for TOMS/Earth Probe flight SW**

Flight Software ISRs and ESRs

- **Interrupt Service Routines**

- Millisecond ISR
- 1553 ISR
- I/O Bus ISR
- ADC Timer ISR

- **Event Service Routines**

- Centisecond ESR
- Command Message ESR
- TM Message ESR
- S/C Status Message ESR
- Start of Second ESR
- Time Code ESR
- Motor Heater Deck ESR
- CCD Data Available ESR
- Filter Wheel Position ESR
- Shutter Position ESR
- Telescope Position ESR



Flight Software Tasks

- Prepare Commands
- Execute Commands
- Control Motors
- Send Source Packets
 - Load Scan Control Block
 - Build Science Data Packet
 - Sync Instrument Time
 - Send Status Packet
 - Read S/C Status
 - Do Housekeeping

Flight Software Projected Total Memory Usage

- **The following memory estimates are based on the design specification and the code already written**
 - PROM
 - 16K total available, 13K will be required for Boot PROM code
 - Data RAM
 - 64K total available, 48K will be required for program variables
 - Program RAM
 - 64K total available, 22K will be required for Instrument Software
 - EEPROM
 - 128K total available, 76K will be required for Instrument Software and Default Control Program

Flight Software Performance

- Critical Tasks and ISRs are coded and tested.
 - Instrument timekeeping
 - CMD reception
 - TM production and transmission
 - Instrument parameter access
- No performance concerns to date although tight coding has been required
- Almost all deadlines are handled by ISR code allowing the tasks to use up to 75 msec per invocation
- The most demanding task code deadline is 975 msec (Spacecraft Start of Second message)
- Design Spec CPU Load Estimate has held up so far at approximately 30% CPU Utilization

Flight Software Test Plan

- Visually inspect code
- Unit Test with 8051 simulator on PC
- Unit Test with 8051 emulator on the engineering model electronics stack (100% coverage)
- System Testing
- Stress Testing
 - Try to crash the flight software with high command rates
 - Try to crash the flight software with invalid commands
- Code Review
- **Formal Test Procedure - Test all requirements.**
Executed on the flight model before instrument calibration begins.

Flight Software Significant Changes from PDR

- Sun avoidance now requires moving telescopes to lowest elevation
- Modified commands and status for 2nd filter wheel
- Eliminated programmable format for Status TM packets. Status TM packet size now fixed.
- Added “Allocate Local Vars” and “Deallocate Local Vars” commands
- Removed autonomous bearing lube overscanning.
- Changed temp control from PID to PI
- Removed “Optimize Telescope Movement” and “Optimize Filter Wheel Movement” commands

Flight Software CCD Binning

- Multiple binning tables are stored in RAM
- CCD Binning is controlled by the current Binning Table
- Current Binning Table is selected in the Scan Table
 - Can be changed many times during a scan
- Binning Table contains one entry for each horiz. bin (up to 256 bins)
- Each Binning Table entry contains a bin width (1 to 255 pixels), a bin gain (4 ranges) and a "discard bin" bit

