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Thermosphere • Ionosphere • Mesosphere • Energetics and Dynamics

Structural Analysis & Verification

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Presentation Outline

- **Design Requirements**
 - Launch Vehicle
 - Instruments
- **Selected Materials**
- **Design Criteria**
- **Design & Analysis**
 - Spacecraft
 - Launch Configuration
 - Orbit Configuration
 - Instrument Bench
 - Launch Configuration
 - Orbit Configuration
- **Structural Verification**
 - Spacecraft
 - Instruments / Subsystems
- **Mass Properties**



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Design Requirements

- **Spacecraft Design & Test**

- NASA-STD-5001 Structural Design & Test Factors of Safety for Space Flight Hardware
- NASA-STD-5002 Loads Analysis of Spacecraft Payloads
- NASA-STD-7001 Payload Vibroacoustic Test Criteria
- NASA-STD-7002 Payload Test Requirements
- NASA-SP-8077 Transportation and Handling Loads
- GEVS-SE General Environmental Verification Specification for STS & ELV Payloads, Subsystems and Components

- **Material Selection**

- MSFC-SPEC- 522B Design Criteria for Controlling Stress Corrosion Cracking
- MIL-STD-1568 Corrosion Prevention & Control
- MIL-STD- 889B Protection of Dissimilar Metal Combinations
- NASA-RP-1124 Outgassing Data for Spacecraft Materials

- **Material Properties**

- MIL- HDBK-5E Metallic Materials & Elements
- MIL- HDBK-17-2C Polymer Matrix Composites



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Launch Vehicle Requirements

Launch Vehicle: *Delta II 7920-10C (2 stage)*

• Limit Load Factors:	Lift-off /Aero	MECO
Thrust: Steady State	-----	7.4
Transient	-----	0.6/-0.6
Combined	2.8/-0.2	8.0/ 6.8
Lateral: Steady State	-----	-----
Transient	-----	0.1/-0.1
Combined	3.0/-3.0	0.1/-0.1
• Frequency Constraints:		
Thrust Axis	>35.0 Hz.	
Lateral Axes	>20.0 Hz.	
• Sinusoidal Vibration	Frequency (Hz)	Level
Thrust Axis	5.0 - 6.2	0.5 in DA
	6.2 - 100	1.0 g
Lateral Axes	5.0 - 100	0.7 g

- Notes:**
1. The limit load factors are multiplied by 1.25 to obtain the ultimate loads
 2. The vibration levels are applied at the base of the payload attach fitting



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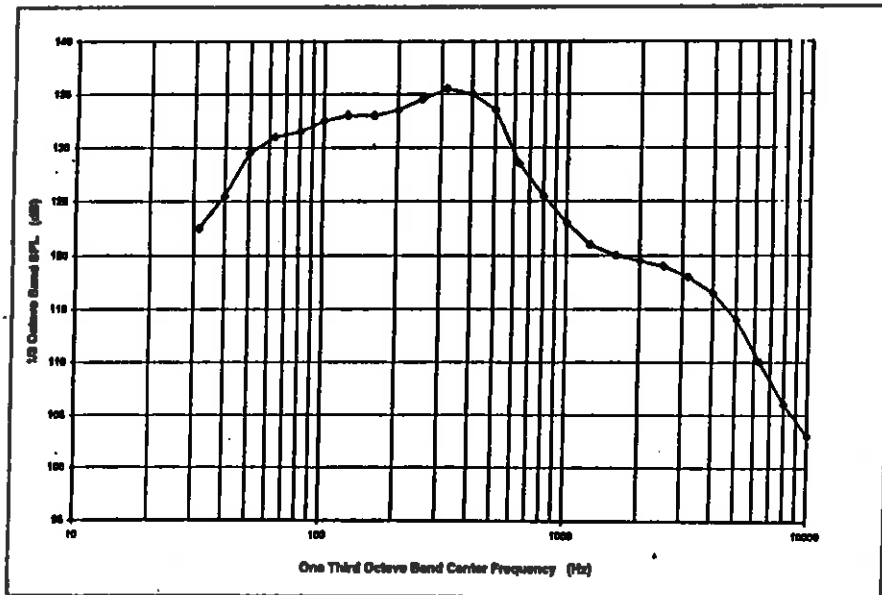
Launch Vehicle Requirement

Max. Expected Flight Level (+3.0 dB.)

Inside the Dual Payload Attach Fitting (DPAF)

10.0 ft. Composite Fairing, with 3.0 in. Acoustic Blanket

Based on a 60% fill factor



1/3 Octave Band Frequency (Hz.)	Sound Pressure Level (dB.)	1/3 Octave Band Frequency (Hz.)	Sound Pressure Level (dB.)
31.5	122.5	630.0	128.5
40.0	125.5	800.0	125.5
50.0	129.5	1000.0	123.0
63.0	131.0	1250.0	121.0
80.0	131.5	1600.0	120.0
100.0	132.5	2000.0	119.5
125.0	133.0	2500.0	119.0
160.0	133.0	3150.0	118.0
200.0	133.5	4000.0	116.5
250.0	134.5	5000.0	114.0
315.0	135.5	6300.0	110.0
400.0	135.0	8000.0	106.0
500.0	133.5	10000.0	103.0
		OASPL	144.1

dB Reference, 20 micro Pa.



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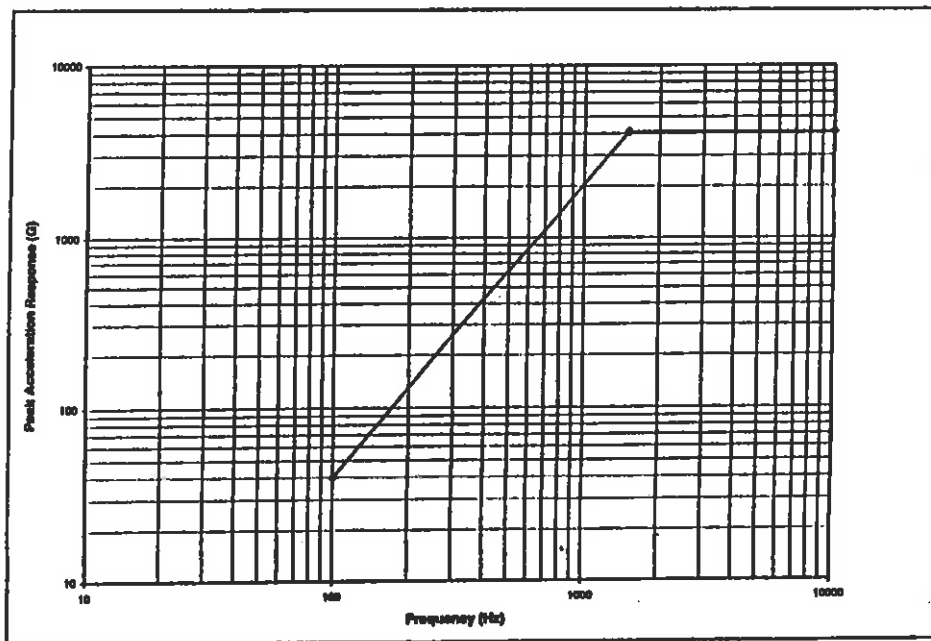


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Launch Vehicle Requirement

Shock Response Spectrum

3712C Payload Attach Fitting with Separation Bolt Preload 5700 lbs.



Frequency

(Hz.)

100

1500

10000

Response

Acceleration (g's)

40

4100

4100



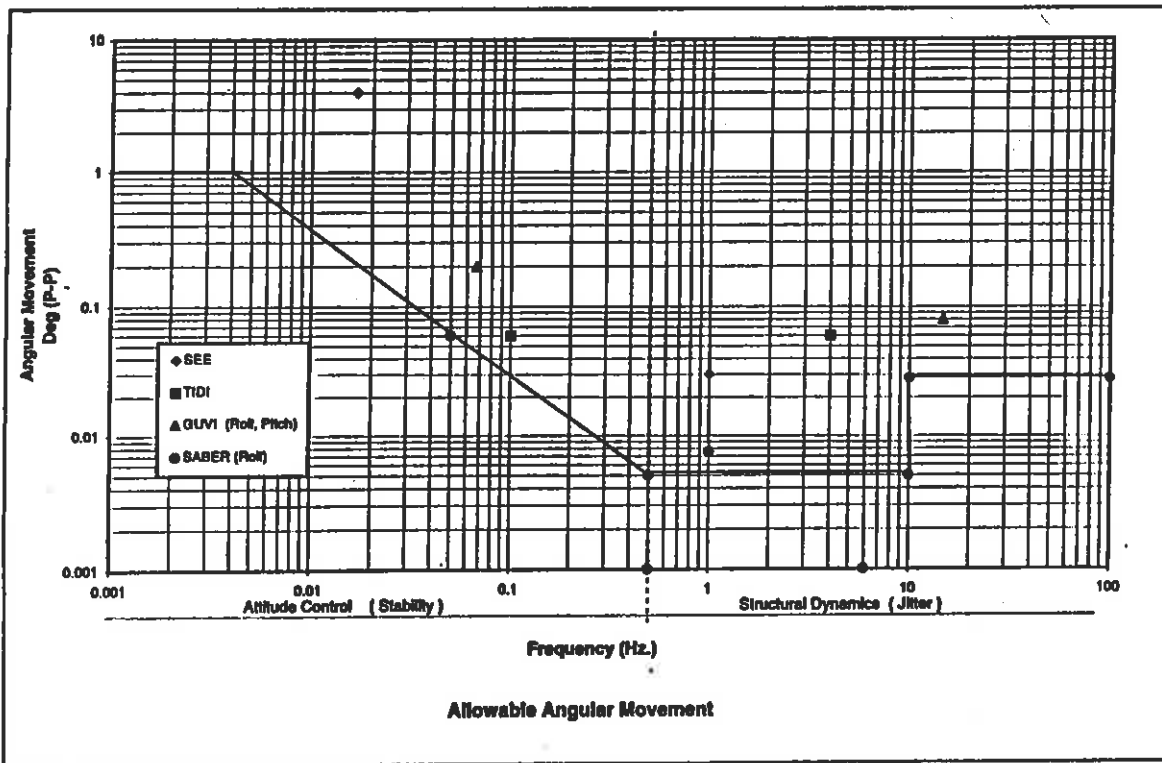
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Instrument Requirements

- Instrument Jitter and Stability



Jitter

Stability

GUVI:

0.04° / .068 sec. PR

0.1° / 15 sec.

SABER:

0.005° p-p / 0.5-10. Hz.

0.0075° p-p / sec.

0.028° p-p / 10-100. Hz.

0.025° p-p / sec.

SEE:

0.03° / sec.

2.0° / 60 sec.

TIDI:

0.03° / .25 sec.

.03° / 10 sec.



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Selected Materials

Spacecraft Structure

Primary Structure

Aft Deck

Corner Brackets

Adapter Ring

Side Panels

Corner Panels

Foreward Deck

Aft Deck

Machined Aluminum

6061-T651

Sandwich Panels

Face sheets: 2024 -T81

Core: 1/8 - 5056 - 3.1 lb./Ft³

Edge Members: Magnesium ZK60A-T5

Film Adhesive: FM 73 0.030 lb/ft²

Inserts: Magnesium ZK60A-T5

Secondary Structure

Instrument Bench

GPS Antenna Masts

Composite System

Resin: Cyanate Ester

Fiber: Ultra-high Modulus Pitch Fibers

Inserts: Titanium Ti-6Al-4V

Film Adhesive: A54 0.015 lb/ft²



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Selected Materials

Structural Attachments / Fasteners

Components < 5.0 lbs. Rivnuts
Subsystems < 30 lbs. Potted in inserts
Subsystems > 30 lbs. Spools

Fasteners:

Primary & Secondary Structure

Material Spec. AMS 4928N

Ti-6Al-4V

Tensile Strength 150000 psi

Socket head cap screws

Size 10-32



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Structural Design Criteria

Design and Test Factors of safety:

Protoflight Proof Test Factor of Safety 1.25

Design Factors of Safety:

Metallic Structures:	Yield design factor	1.4
	Ultimate design factor	1.8
Composite / Bonded Structures:	Ultimate design factor	1.8
	Joints:	Ultimate design factor
Buckling :	Knockdown factor	2.0

Margins of Safety :

$$\text{Margin of safety} = \frac{\text{allowable stress}}{\text{calculated stress} * \text{factor of safety}} - 1$$



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Structural Design Criteria

Fastener Design Allowables

- **Potted in inserts, for 10-32 fasteners**

Face-sheets: 2042 - T81 (t=.015) Core: 1/8 - 5056 - .0007

Insert: Shur-Lok SL 606-3C Potting Compound: SEL 3010

Tension (lbs.)	385.0
Compression (lbs.)	385.0
Shear (lbs.)	304.0
Torque (in - lbs.)	50.0

Face-sheets: 5HS _ XN-70A / 996 (t = .040) Core: 1/8 - 5056 - .0007

Insert: AEP 1035-3CPM565 Potting Compound: EPOCAST 1618-A/B

Tension (lbs.)	289.0
Compression (lbs.)	289.0
Shear (lbs.)	314.0
Torque (in - lbs.)	55.0



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Structural Design Criteria

- Composite Design Allowables**

A test program is currently underway to establish design allowables for the XN 70A Pitch based fibers with a cyanate ester resin system. The following mechanical properties are being evaluated:

Youngs Modulus	(msi)	E_{11} E_{22}
Shear Modulus	(msi)	G_{12}
Poisson Ratio		μ_{12}
Coefficient Thermal Expansaion	(μ in/in/ $^{\circ}$ F)	α_{11} α_{22}
Tensile Strength	(ksi)	σ_{11} σ_{22}
Compressive Strength	(ksi)	σ_{11} σ_{22}
Strain To Failure (Tensile)	(%)	ϵ_{11} ϵ_{22}
Strain To Failure (Compression)	(%)	ϵ_{11} ϵ_{22}
In-plane Shear	(ksi)	τ_{12}
Interlaminar Shear	(ksi)	τ_{13}

The design allowables will be established by taking 80% of the maen value of the sample tests.

- The use of a cyanate siloxane resin system is being investigated because of its advantages over the current cyanate ester systems.



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Spacecraft Structure - Launch Configuration

Frequency Constraints:

Thrust Axis > 35.0 Hz.

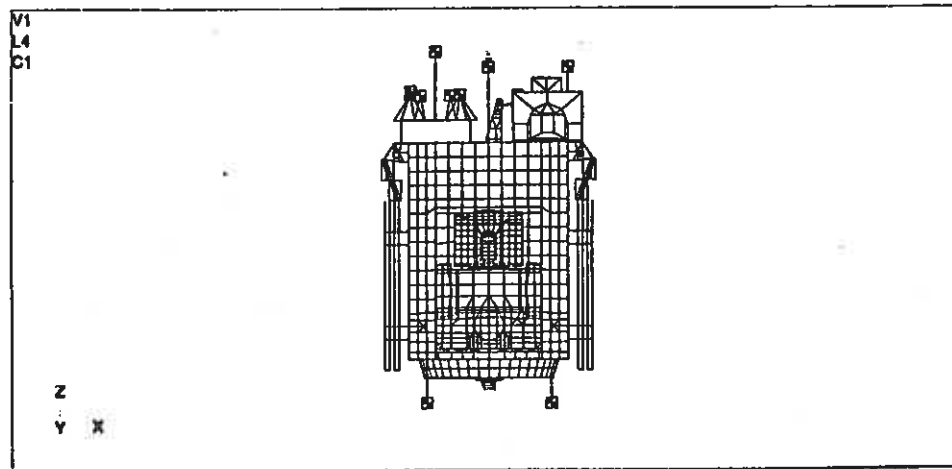
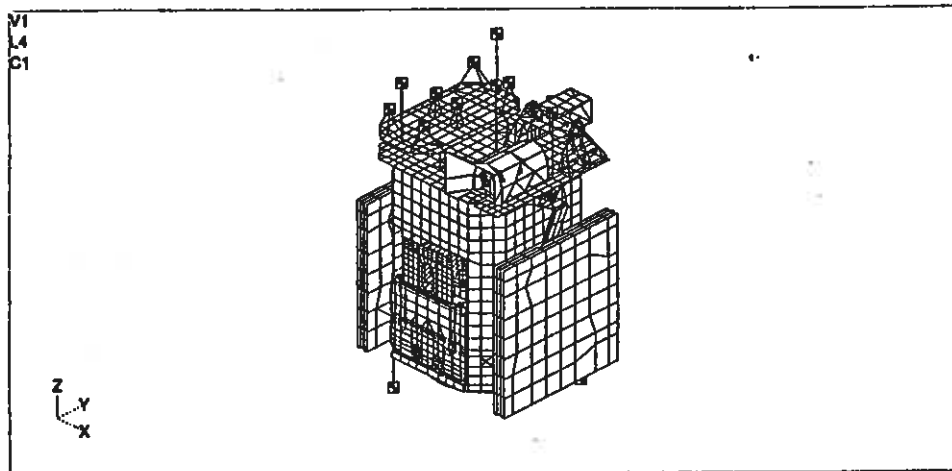
Lateral Axes >20.0 Hz.

Design Load Cases:

Ultimate Loads (g's)

(Transient plus Steady-State)

Load Cases;	Thrust	Lateral
1. Max. Thrust	10.0	0.5 (x)
2. Max. Thrust	10.0	0.5 (y)
3. Max. Lateral	3.5	3.75 (x)
4. Max. Lateral	3.5	3.75 (y)





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Margins of Safety

Structural Component	Load Condition	Failure Mode	Max. Stress (psi)	Margin of Safety Failure Index
Interface Adapter	3	Buckling	4019.	MS 1.7
Bottom Deck Alum.	3	Bending	5769.	MS 3.0
Corner Brackets	3	Bending	4224.	MS 4.5
Vertical Framing Members	2	Bending	8639.	MS 1.7
Bottom Deck Sandwich	2	Bending	4382.	FI 0.101 (1) BFI 0.008
Corner Panels	4	Bending	5416.	FI 0.125 (1) BFI 0.004
Side Panels	2	Bending	18056.	FI 0.453 (1) BFI 0.017
Top Deck	4	Bending	6170.	FI 0.104 (1) BFI 0.007

Notes: MS Margin of Safety FI Failure Index (first ply failure - max. strain criteria) BFI Bond Failure Index
 () denotes first ply failure



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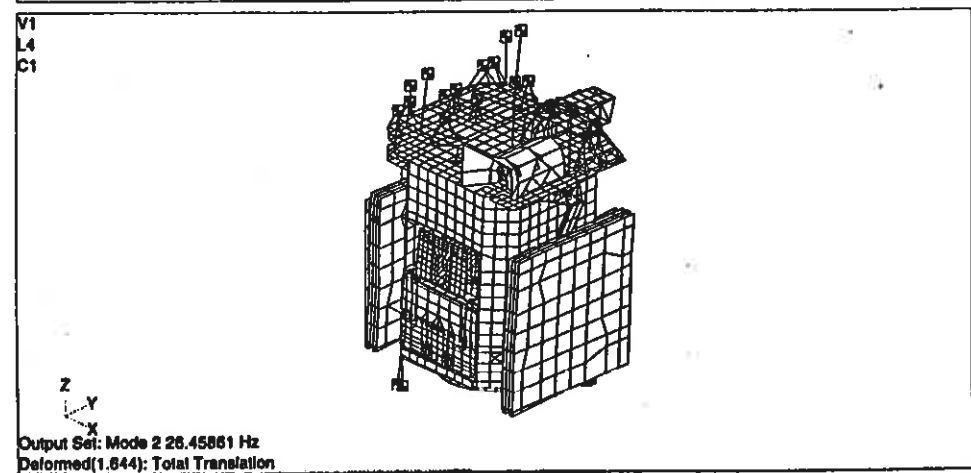
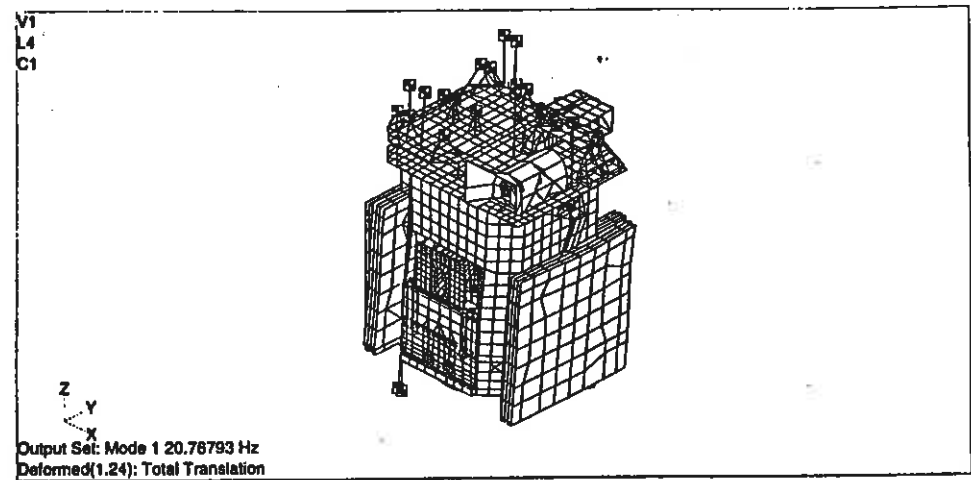


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Spacecraft Structure - Launch Configuration

Primary Modes:

Mode No.	Frequency	Mode Shapes
1	20.7 Hz	Lateral Bending (y) axis
2	26.4 Hz	Lateral Bending (x) axis
3	35.1 Hz	SABER Radiator
36	57.0 Hz	Torsion
40	62.3 Hz	Bottom Deck/ Thrust
54	72.2 Hz	Top Deck
79	83.9 Hz	GUVI SIS
91	94.4 Hz	Top Deck





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Spacecraft Structure - Launch Environment

Sinusoidal Vibration Test Level - based on the launch vehicle requirements. i.e. maximum flight level +3 dB

	Frequency (Hz.)	Acceleration (g's)
Thrust Axis	5.0 - 7.4	.5 in DA
	7.4 - 100	1.4
Lateral Axis	5.0 - 6.2	.5 in DA
	6.2 - 100	1.0

- Notes:
1. The acceleration levels shall be applied at the base of the payload attach fitting.
 2. The dynamic response of the spacecraft may be limited to the results of the coupled loads analysis.



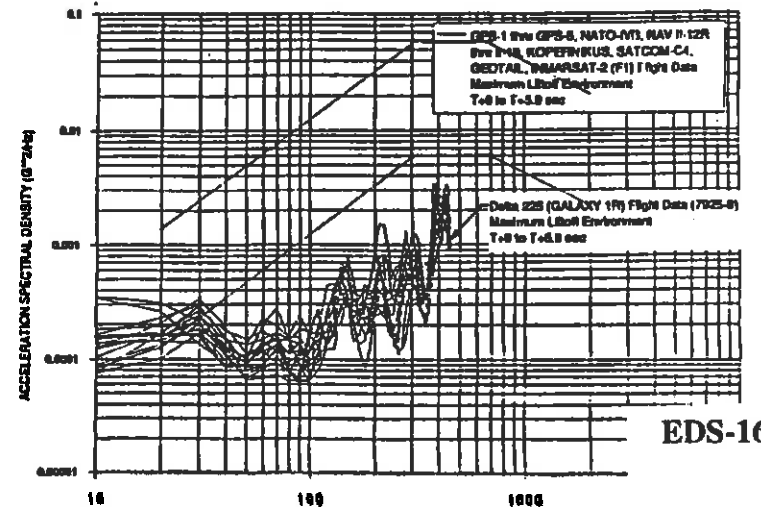
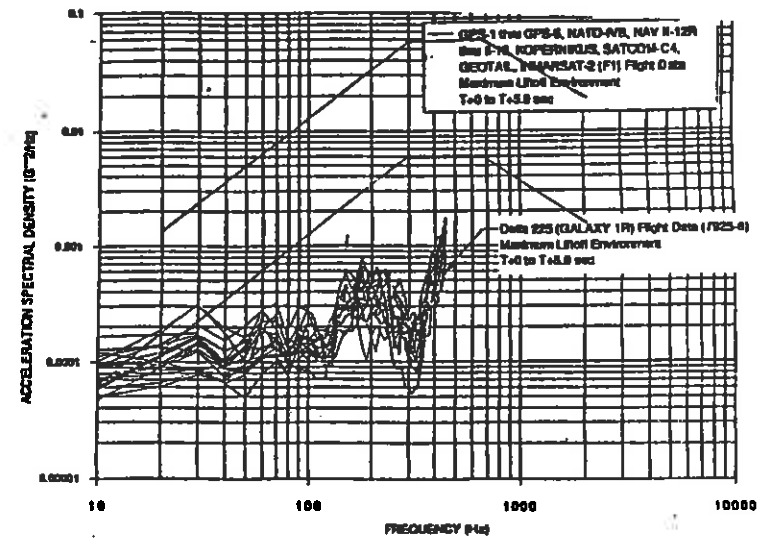
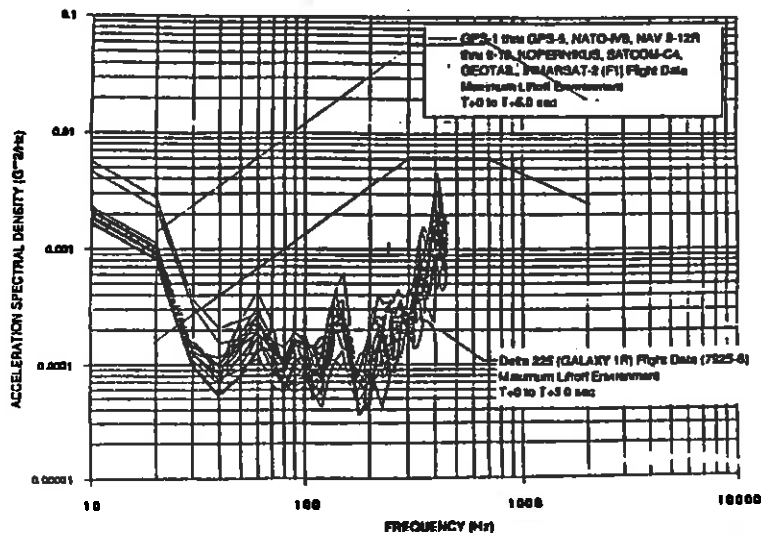
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Spacecraft Structure - Launch Environment

Estimate - Base Excited Random for Delta II
(Test data from Delta II guidance section compared with NASA GEVS recommendation)





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Spacecraft Structure - Launch Environment

Dynamic Response to Base Excited Inputs: Lateral Axis (X)

Instrument	Component	Sinusoidal		Random		Coupled Loads (g's) < 50 Hz.
		fn (Hz.)	Max. (g)	fn (Hz.)	Max. PSD	
SABER	Cooler mount	20.7	4.1	190.0	1.2	
	Chopper mount	20.7	5.2	36.5	0.1	
	Ctr. of Scan mirror	36.5	9.1	36.5	0.4	
	Mirror No. 1 & 2	36.5	7.5	36.5	0.3	
	Mirror No. 3	20.7	5.5	36.5	0.14	
	Mirror No. 4	20.7	5.2	36.5	0.8	
	Focal plane COM	20.7	5.0	210.0	0.5	
	Focal plane top	20.7	4.8	210.0	0.35	
	Scan mirror motor	36.5	9.2	36.5	0.4	
TIDI	Profiler (etalron)	20.7	16.0	20.7	0.4	
	Focal plane array	20.7	15.0	20.7	0.5	
	Telescope No.1	20.7	18.0	20.7	0.6	
	Telescope No.2	20.7	18.0	20.7	0.6	
	Telescope No.3	20.7	17.0	20.7	0.5	
	Telescope No.4	20.7	17.0	20.7	0.5	

Based on 4% C/C₀; except GUVI 2.5% C/C₀ * Denotes out of plane responses



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Spacecraft Structure - Launch Environment

Dynamic Response to Base Excited Inputs: lateral Axis (X)

Instrument	Component	Sinusoidal		Random		Coupled Loads (g's) < 50 Hz.
		f_n (Hz.)	Max. (g)	f_n (Hz.)	Max. PSD	
SEE	XUV photometer (XPS)	20.7	17.0	20.7	0.5	
	Grating spectrograph (EGS)	20.7	18.0	20.7	0.5	
	Microcontroller	20.7	17.0	20.7	0.5	
	Power control unit (PCU)	20.7	17.0	20.7	0.5	
	Motor support	20.7	17.0	20.7	0.5	
	Bearing support plate / bkt	20.7	17.0	*410.0	1.8	
GUVI	Focal plane No. 1	83.9	6.0	*460.0	3.5	
	Focal plane No. 2	83.9	5.8	340.0	4.0	
	Grating	*67.0	3.2	550.0	1.8	
	Pop- up mirror	*67.0	3.8	550.0	2.1	
	Slit mechanism	83.9	9.1	83.9	1.4	
	Motor	83.9	13.0	340.0	21.0	
	Mirror No.1	83.9	12.0	340.0	6.5	

Based on 4% C/C₀; except GUVI 2.5% C/C₀

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Spacecraft Structure - Launch Environment

Dynamic Response to Base Excited Inputs: Lateral Axis (Y)

Instrument	Component	Sinusoidal		Random		Coupled Loads (g's) < 50 Hz.
		f_n (Hz.)	Max. (g)	f_n (Hz.)	Max. PSD	
SABER	Cooler mount	26.4	3.0	*205.0	2.30	
	Chopper mount	26.4	6.0	26.4	0.13	
	Ctr. of Scan mirror	26.4	9.8	26.4	0.35	
	Mirror No. 1 & 2	26.4	9.5	*110.0	0.50	
	Mirror No. 3	26.4	6.8	26.4	0.16	
	Mirror No. 4	26.4	6.0	26.4	0.10	
	Focal plane COM	26.4	3.9	*205.0	0.30	
	Focal plane top	26.4	4.0	*205.0	0.25	
	Scan mirror motor	26.4	10.0	26.4	0.30	
TIDI	Profiler (etalron)	26.4	16.0	26.4	0.50	
	Focal plane array	26.4	14.0	220.0	3.5	
	Telescope No.1	26.4	18.5	26.4	1.0	
	Telescope No.2	26.4	18.5	26.4	1.0	
	Telescope No.3	26.4	19.0	26.4	1.0	
	Telescope No.4	26.4	19.0	26.4	1.0	

Based on 4% C/C₀; except GUVI 2.5% C/C₀

*Denotes out of plane responses



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Spacecraft Structure - Launch Environment

Dynamic Response to Base Excited Inputs: lateral Axis (Y)

Instrument	Component	Sinusoidal		Random		Coupled Loads (g's) < 50 Hz.
		f_n (Hz.)	Max. (g)	f_n (Hz.)	Max. PSD	
SEE	XUV photometer (XPS)	26.4	18.0	26.4	0.80	
	Grating spectrograph (EGS)	26.4	16.0	220.0	0.80	
	Microcontroller	26.4	16.0	26.4	0.55	
	Power control unit (PCU)	26.4	16.0	26.4	0.70	
	Motor support	26.4	16.0	26.4	0.70	
	Bearing support plate / bkt	26.4	16.0	*210.	2.10	
GUVI	Focal plane No. 1	98.2	12.0	98.2	3.0	
	Focal plane No. 2	98.2	12.0	98.2	3.0	
	Grating	98.2	12.0	98.2	3.2	
	Pop- up mirror	98.2	12.0	98.2	2.9	
	Slit mechanism	98.2	12.0	98.2	2.9	
	Motor	98.2	12.0	*205.0	8.1	
	Mirror No.1	98.2	12.0	98.2	2.9	

Based on 4% C/C₀; except GUVI 2.5% C/C₀

*Denotes out of plane responses



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Spacecraft Structure - Launch Environment

Dynamic Response to Base Excited Inputs: Thrust Axis (Z)

Instrument	Component	Sinusoidal		Random		Coupled Loads (g's) < 50 Hz.
		f_n (Hz.)	Max. (g)	f_n (Hz.)	Max. PSD	
SABER	Cooler mount	62.3	6.0	150.	1.0	
	Chopper mount	62.3	19.0	62.3	1.8	
	Ctr. of Scan mirror	62.3	19.0	62.3	2.0	
	Mirror No. 1 & 2	62.3	19.0	62.3	2.0	
	Mirror No. 3	62.3	19.0	62.3	1.8	
	Mirror No. 4	62.3	18.0	62.3	1.8	
	Focal plane COM	62.3	18.0	62.3	1.8	
	Focal plane top	62.3	18.0	62.3	1.8	
	Scan mirror motor	62.2	20.0	62.3	2.1	
TIDI	Profiler (etalon)	*89.2	8.0	*86.0	0.5	
	Focal plane array	95.7	5.7	*130.	1.3	
	Telescope No.1	90.2	9.0	90.2	0.5	
	Telescope No 2	90.2	7.0	90.2	0.5	
	Telescope No.3	93.6	11.0	90.2	1.2	
	Telescope No.4	93.6	10.0	90.2	1.2	

Based on 4% C/C₀; except GUVI 2.5% C/C₀

*Denotes out of plane responses



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Spacecraft Structure - Launch Environment

Dynamic Response to Base Excited Inputs: Thrust Axis (Z)

Instrument	Component	Sinusoidal		Random		Coupled Loads (g's) < 50 Hz.
		f_n (Hz.)	Max. (g)	f_n (Hz.)	Max. PSD	
SEE	XUV photometer (XPS)	*100.0	12.0	*99.2	1.7	
	Grating spectrograph (EGS)	*48.0	7.0	*150.0	2.0	
	Microcontroller	100.0	7.0	*150.0	1.4	
	Power control unit (PCU)	72.2	10.0	*99.2	0.7	
	Motor support	72.2	10.0	*99.2	0.7	
	Bearing support plate / bkt	*100.0	7.0	*110.0	0.7	
GUVI	Focal plane No. 1	*100.0	19.5	*98.9	4.9	
	Focal plane No. 2	*100.0	19.5	*98.9	4.8	
	Grating	*100.0	19.5	*98.9	4.9	
	Pop- up mirror	*100.0	19.5	*98.9	4.8	
	Slit mechanism	*100.0	19.5	*98.9	4.8	
	Motor	62.3	21.0	*98.9	5.0	
	Mirror No.1	*100.0	19.5	*98.9	4.7	

Based on 4% C/C₀; except GUVI 2.5% C/C₀

*Denotes out of plane responses



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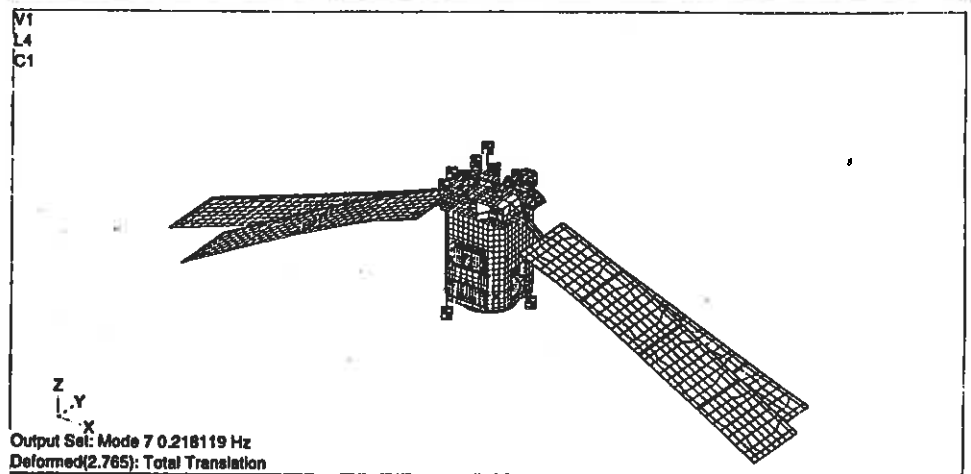
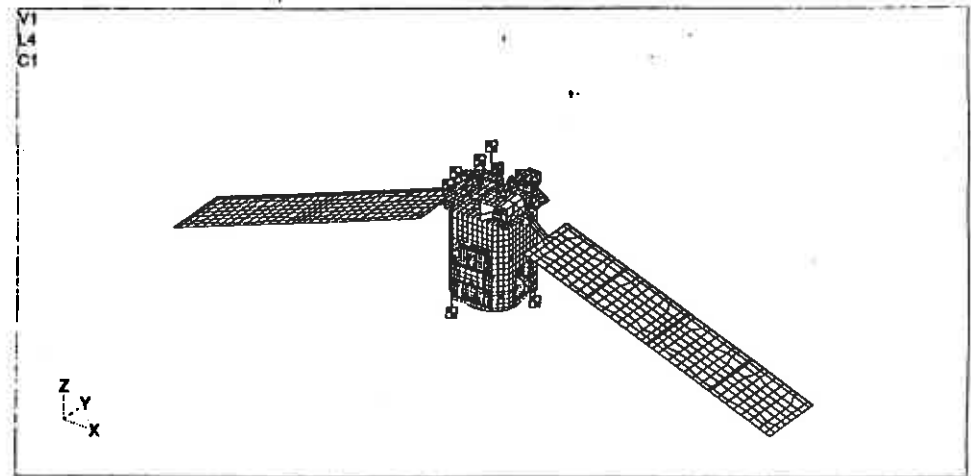


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Spacecraft Structure - Orbit Configuration

Primary Modes:

Mode	Frequency	Mode Shape
1	.23 Hz.	Flatwise Bending at Actuator
2	.40 Hz.	Axisymmetric Panel Bending
3	.73 Hz.	Torsion At Actuator
4	1.32 Hz.	First Mode Panel Bending





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Dynamic Disturbances - Instruments

- **Jitter** defined, herein, as the line-of-sight disturbance in the optical patch due to transient loads and the mechanical response of the structure.

- **Sources and Forcing Functions:**

Instrument	Jitter Source	Amplitude	Frequency	Axis	Duration
GUVI	Scan mirror (Retrace)	0.80 in - lb	200.0	Ry	2.0 seconds
	Pop-up mirror	0.008 in - lb	10.0	Rz	Infrequent
	Slit mechanism	0.0004 in - lb	10.0	Rz	Infrequent
SABER	Scan mirror	1.56 in - lb	0.5	Rx	141.4 seconds
	Cryo-cooler	0.02 lb	52.0,104	Ty	Continuous
	Chopper	0.002 lb	1000.0	Tx	-----
SEE	SSPP gimbal	0.7 in - lb	2.5,20	Rx	300 seconds
	Filter wheel	0.018 in - lb	2.0	Ry	4 times / cycle
TIDI	Telescope (4)	0.23 in - lb	12.5	Rxy	100 seconds
	Filter wheel	0.34 in - lb	10.0	Ry	4 times / cycle

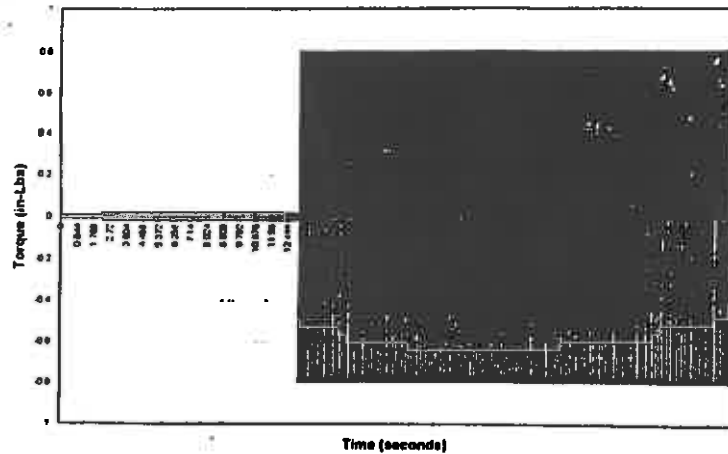


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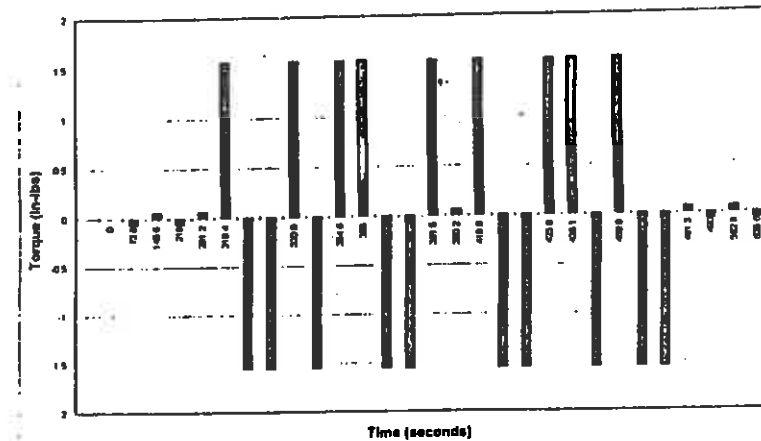


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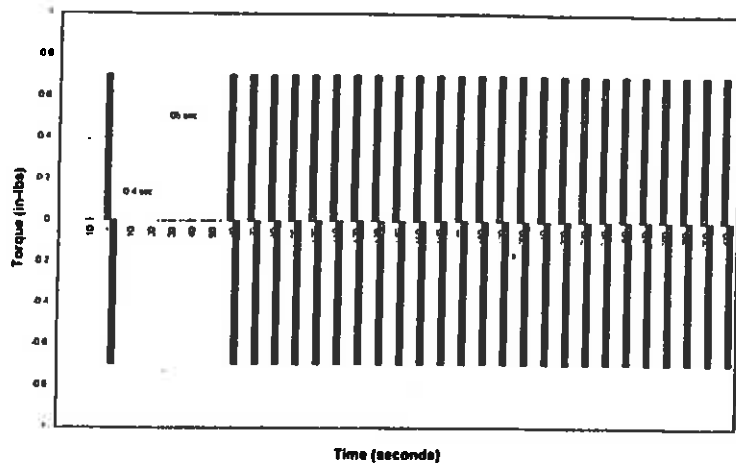
Instrument Disturbance Torques



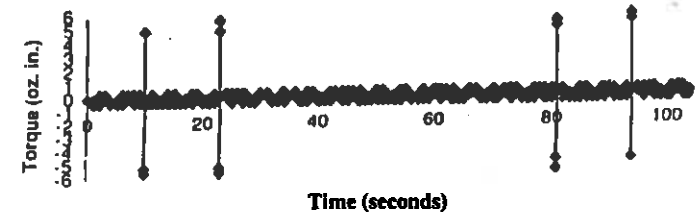
GUVI Torque Disturbances - Scan Mirror (pitch)



SABER Torque Disturbance - Scan Mirror (roll)



SEE Torque Disturbance - SEE Solar Pointing Platform (roll)



TIDI Torque Disturbance - Telescopes with Profiler



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Reaction Wheel Disturbances

- Reaction wheel disturbance is not broad band white noise, but sinusoidal, containing many harmonics and some sub-frequencies of the fundamental
- Each reaction wheel produces mechanical noise at specific harmonics of the wheel speed.
- The primary harmonics are as follows:

Harmonic Multiple	Harmonic Source
0.34	Ball bearing retainer
1.0	Rotor mass imbalance
1.39	Bearing race-to-race misalignment
2.0	Rotor mass imbalance
2.74	Defects in outer race
3.0	Rotor mass imbalance
5.26	Defects in the inner race
144.0	Motor torque ripple



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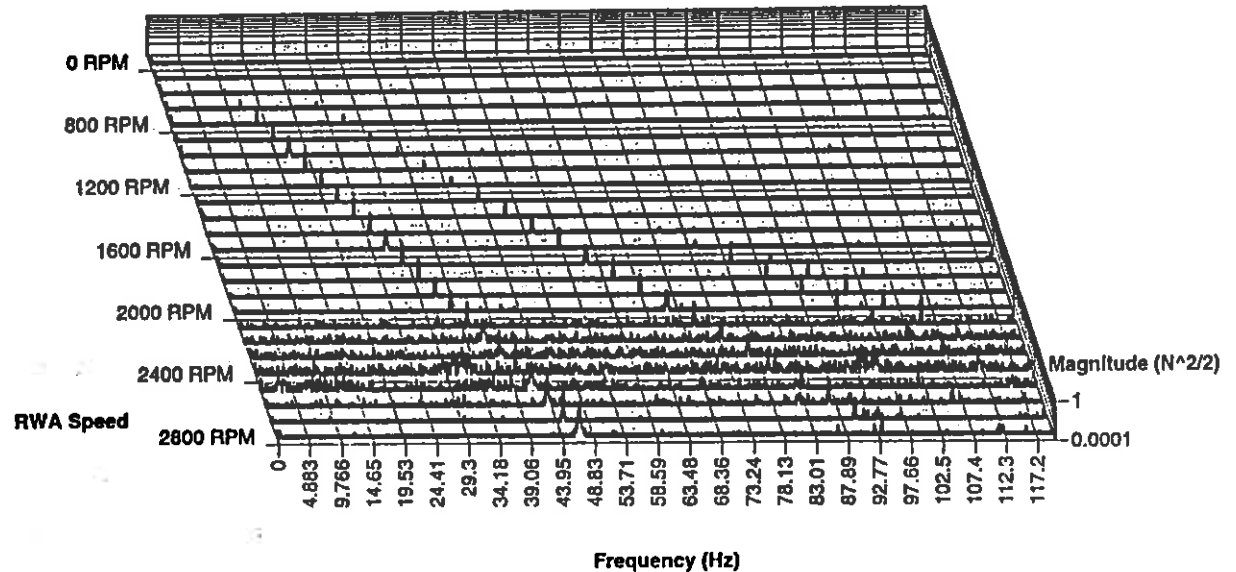
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Reaction Wheel Disturbances

RWA EDU Hard Mounted: X Force vs Fréquency:
RWA speed from 500-2800 RPM at 100 RPM Intervals (first line at 0 RPM!)

Critical Wheel Frequencies:

Mode	Critical Frequency (RPM)
Axial Translation	3900
Rocking	5100
Radial Translation	12000





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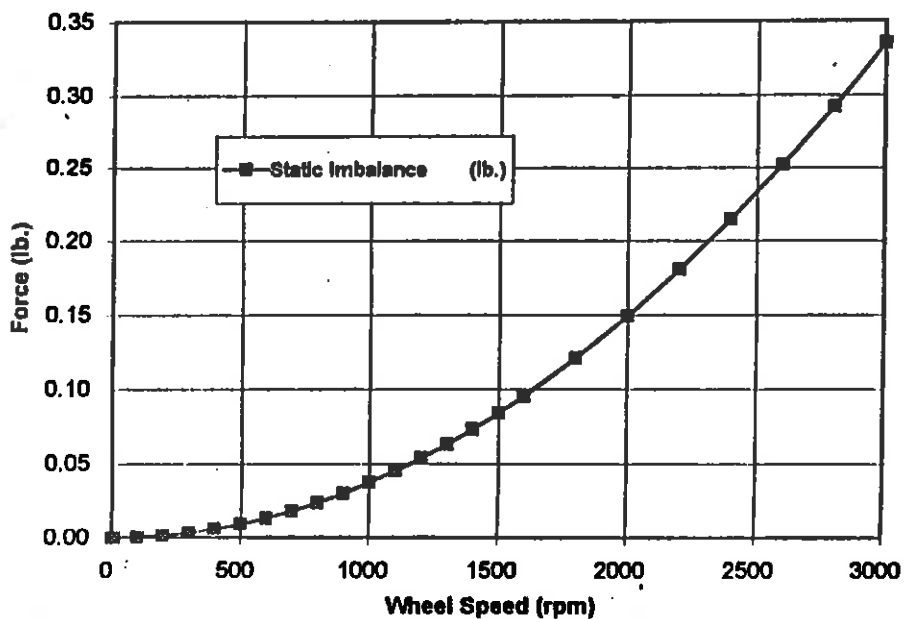


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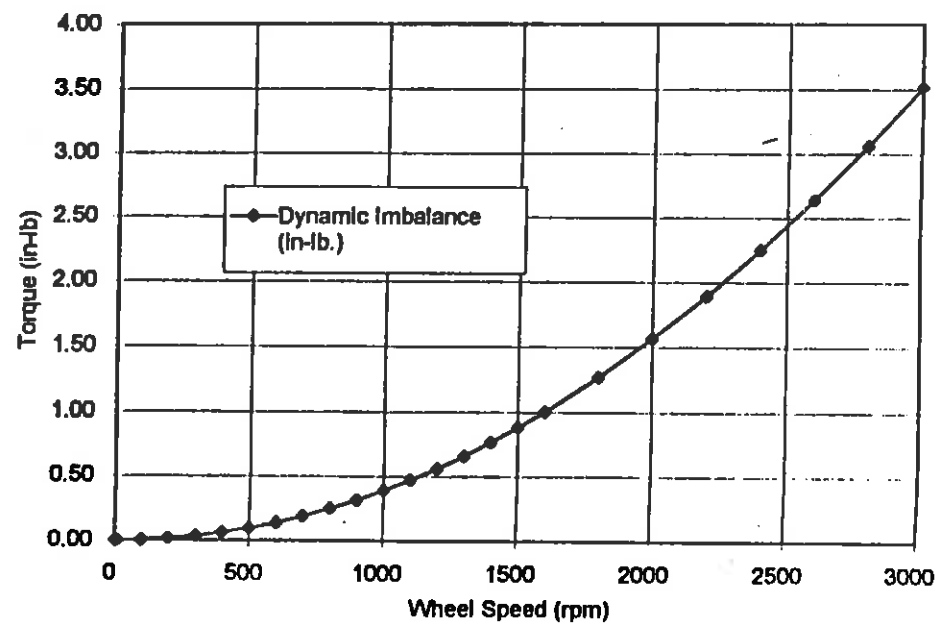
Reaction Wheel Disturbances

Static & Dynamic Imbalance (rss)

Typical Wheel Speeds 100 - 500 RPM



Static Imbalance



Dynamic Imbalance



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Jitter Analysis

Model Parameters:

- The jitter frequency range is defined herein as 0.50 to 50.0 Hz. (30 to 3000 rpm)
- With the exception of the reaction wheels, the disturbances are randomly phased to combine in a root-sum-square (rss) manner.
- Percent critical damping 0.5%

Dynamic Load Cases	1	2	3	4	5
Reaction Wheels	O	O	O	O	O
GUVI	R	R	O	O	O
SABER	R	O	R	O	O
SEE	R	O	O	R	O
TIDI	R	O	O	O	R

Note: (O) Equipment or Instrument Operating

(R) Response Measurement



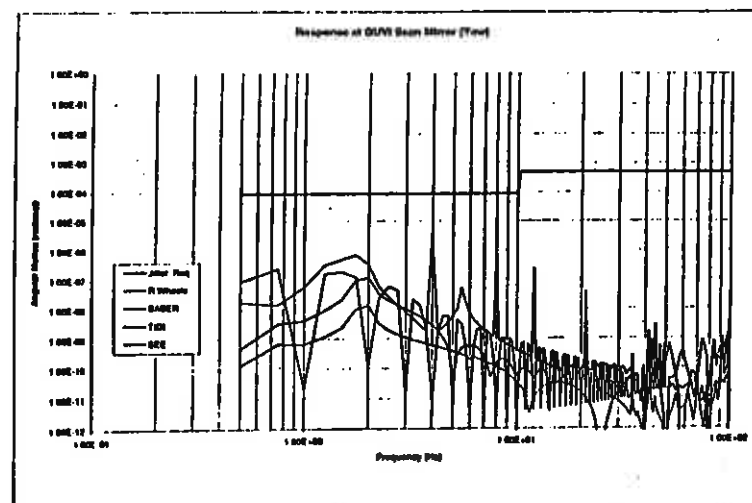
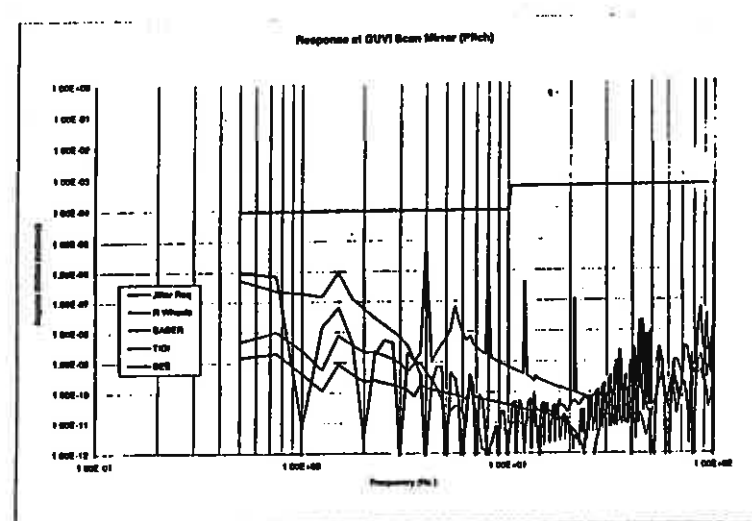
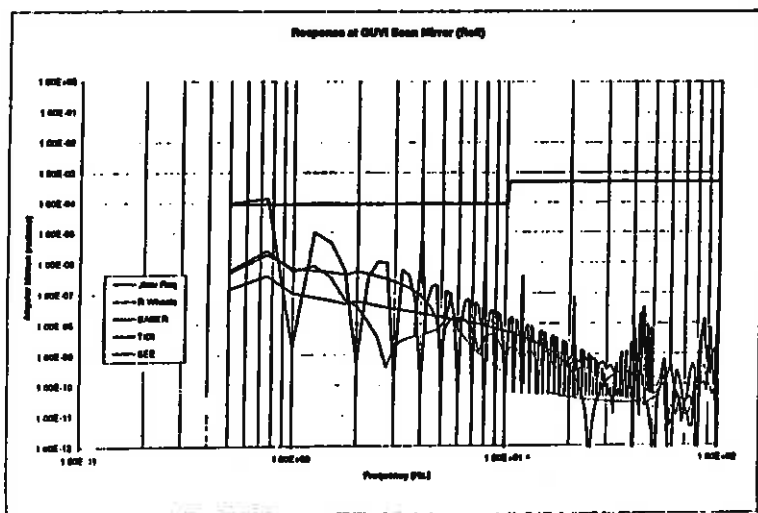
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Jitter Analysis

- **Operating Environment for GUVI**
Typical reaction wheel speed: 240 RPM
All other instruments operating
Response location : Scan mirror





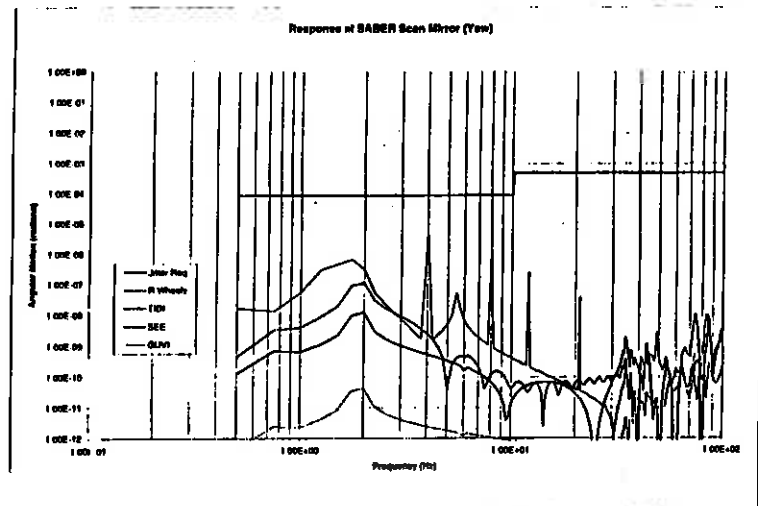
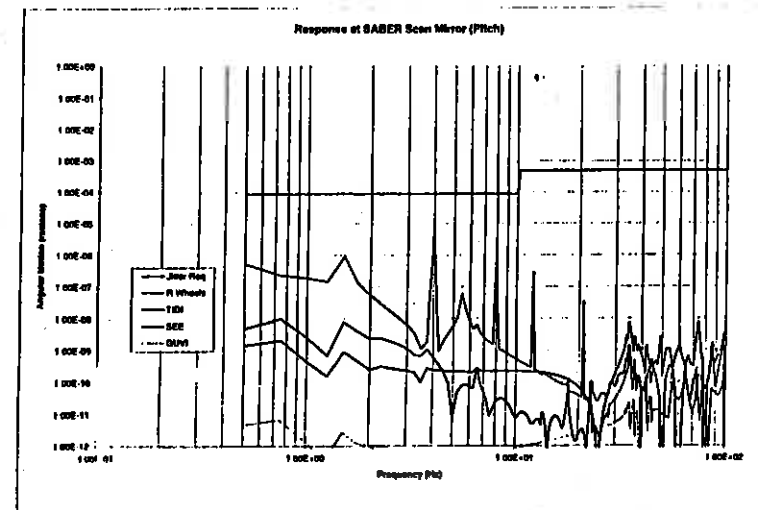
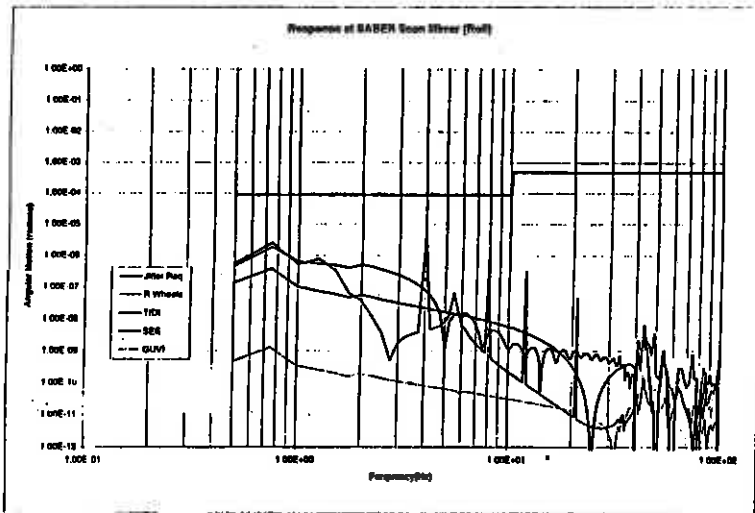
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Jitter Analysis

- **Operating Environment for SABER**
 Typical reaction wheel speed: 240 RPM
 All other instruments operating
 Response location : Scan mirror





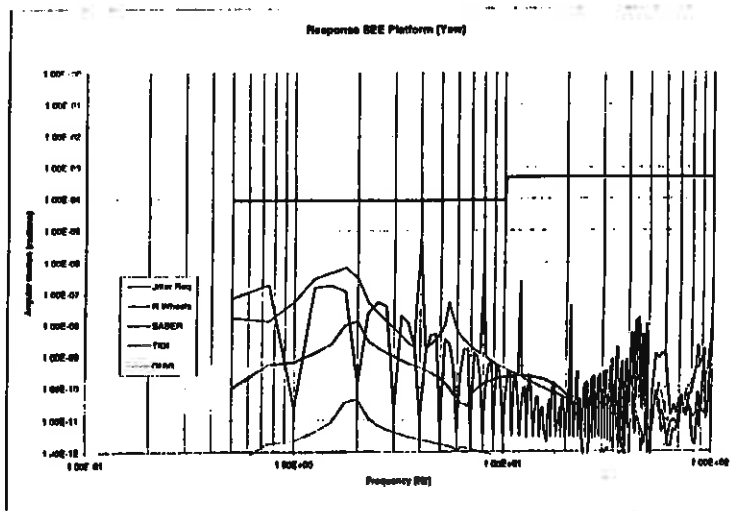
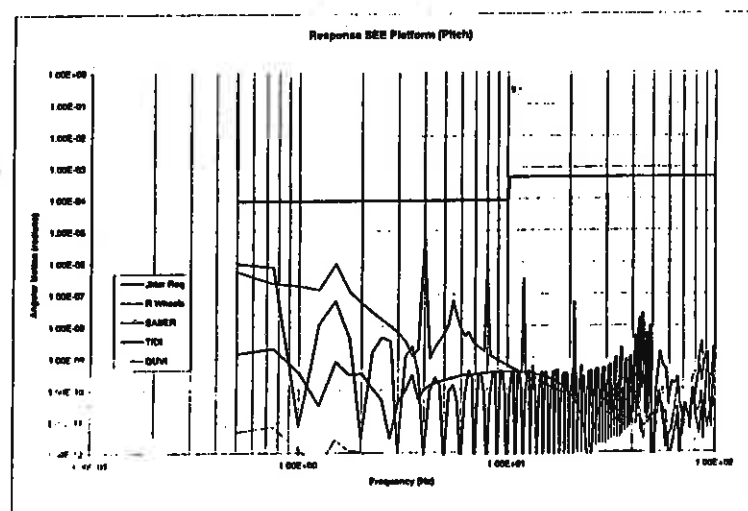
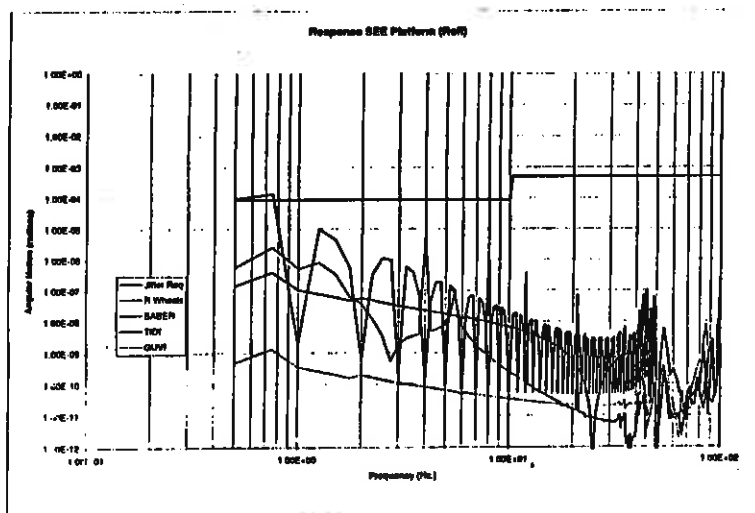
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Jitter Analysis

- **Operating Environment for SEE**
 Typical reaction wheel speed: 240 RPM
 All other instruments operating
 Response location : Solar Pointing Platform





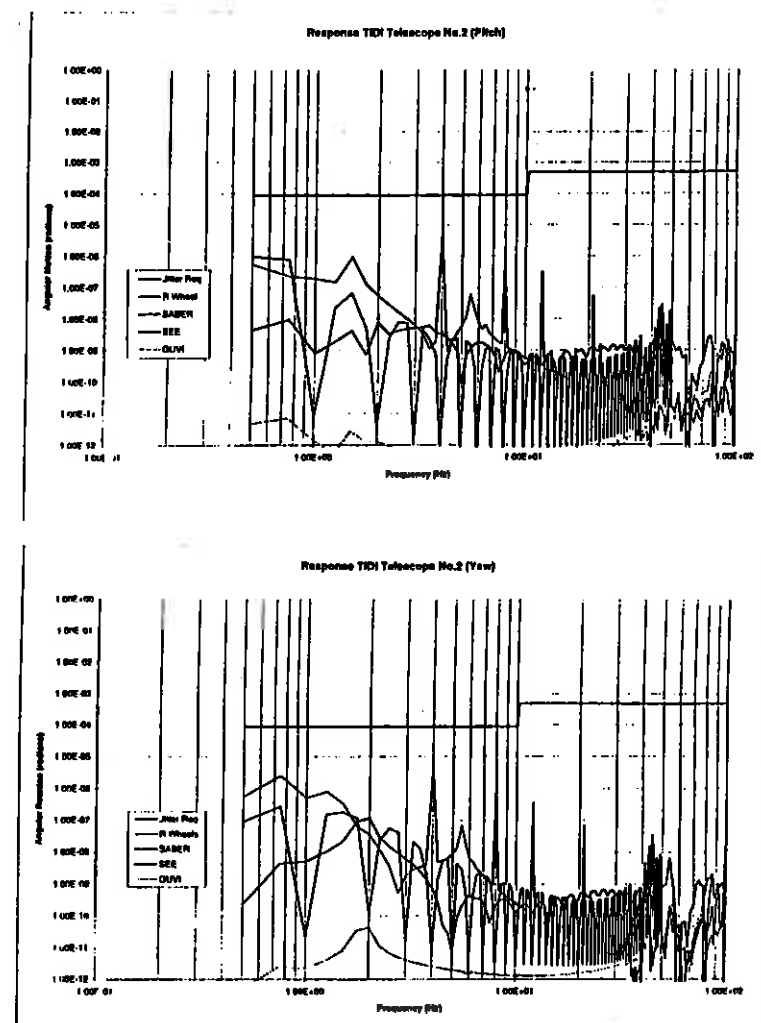
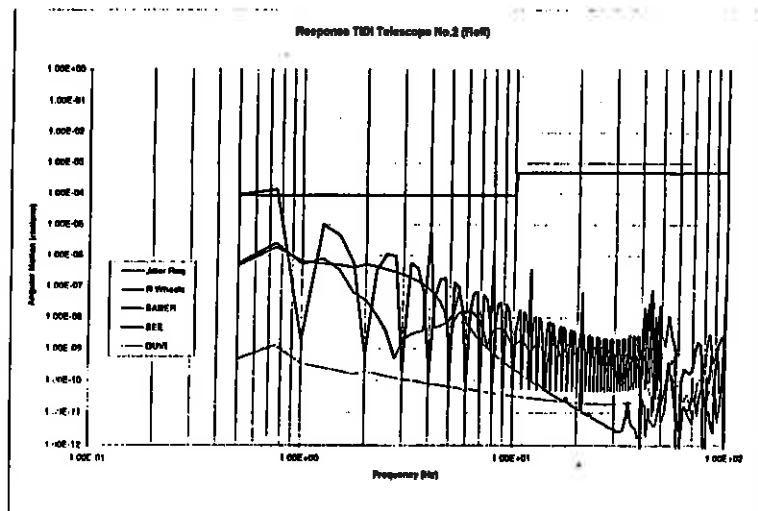
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Jitter Analysis

- Operating Environment for TIDI
Typical reaction wheel speed: 240 RPM
All other instruments operating
Response location : Telescope No. 1





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Instrument Bench Requirements / Criteria

- **Frequency Constraint:** Thrust > 50.0 Hz.
Lateral > 30.0 Hz.
- **Quasi-static Loading :** 30 g's Applied independently, each axes
- **Thermal, Max Operating:** (includes 10 deg. C margin) -15 to 35 deg. C
- **Distortion Angular:** Defined herein as the relative angular rotation between a point on the bench adjacent to the base of each TIDI telescope with respect to a point representing the bore sight axis of each star tracker.

Static Distortion: Due to the 1.0 g effect

Thermal, Operating: (β) angles 0 & 88 deg. Cold
(β) angles 0 & 88 deg. Hot



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Instrument Bench

Bench Structure

Composite System: Pitch Fibers / Cyanate Ester

Sandwich Panel: $t=1.83\text{in.}$

Face Sheets: 5HS XN-70A / EX-1515

Core: 1/8 - 5056 - 0.0007 - 3.1Lb/Ft³

Lay-up: $\{[(-45)(0)(45)(90)]_s / \text{core} / [(90)(45)(0)(-45)]_s\}$

Mounting System

Kinematic support system

Launch locks with (2) Pyro-release

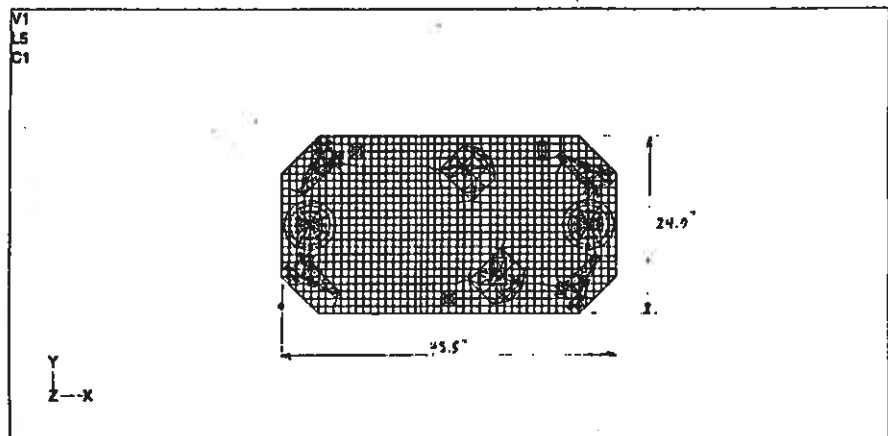
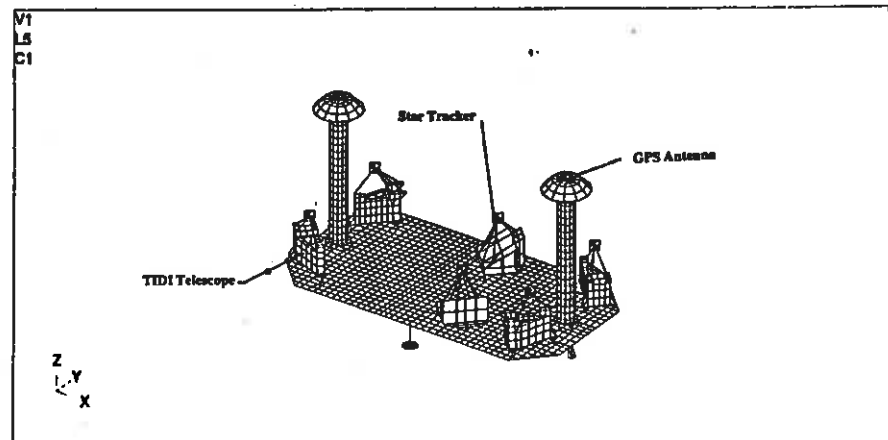
Weight Estimate

Bench Structure 4.7 kg.

Inserts 1.8 kg.

Mounting System 1.8 kg.

Total 8.3 kg.



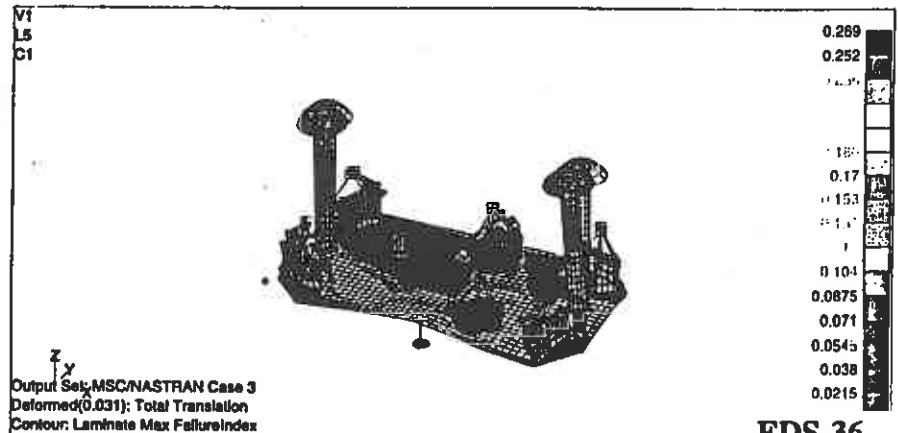
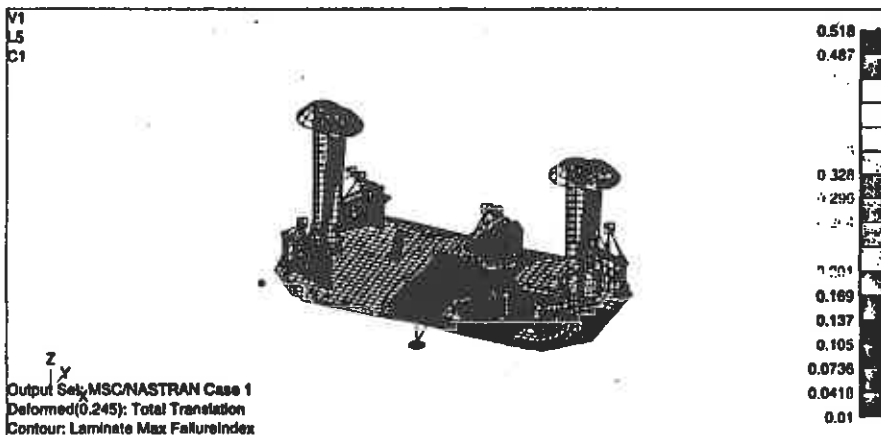
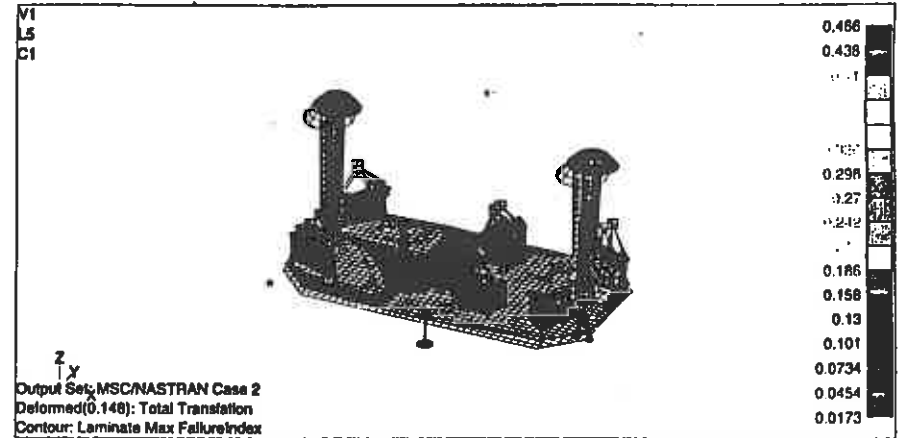
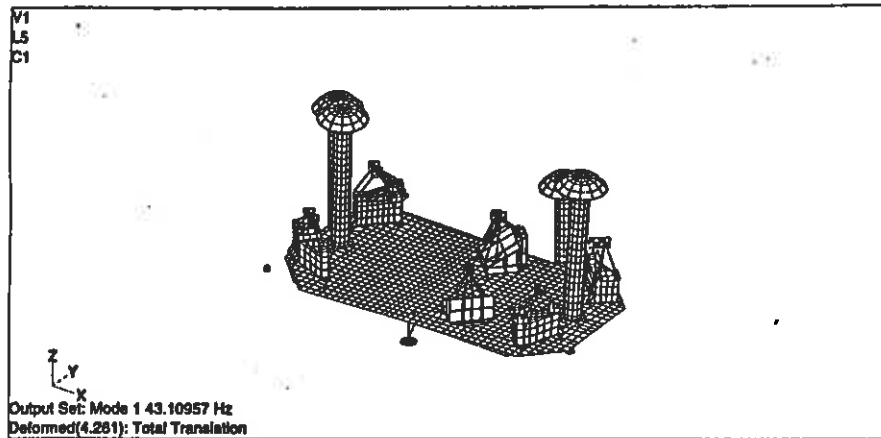


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Instrument Bench Launch Configuration





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GPS Antenna Mast

Mast Structure

Composite System

Prepreg: XN-70A / EX-1515

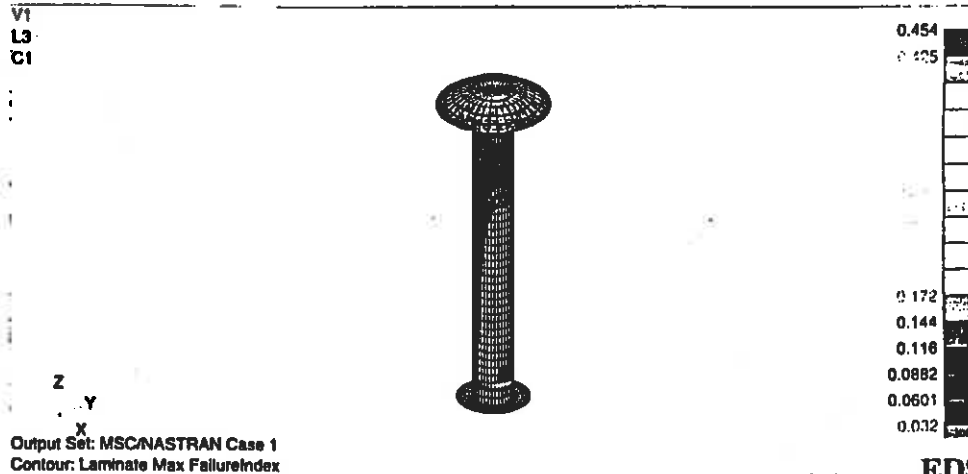
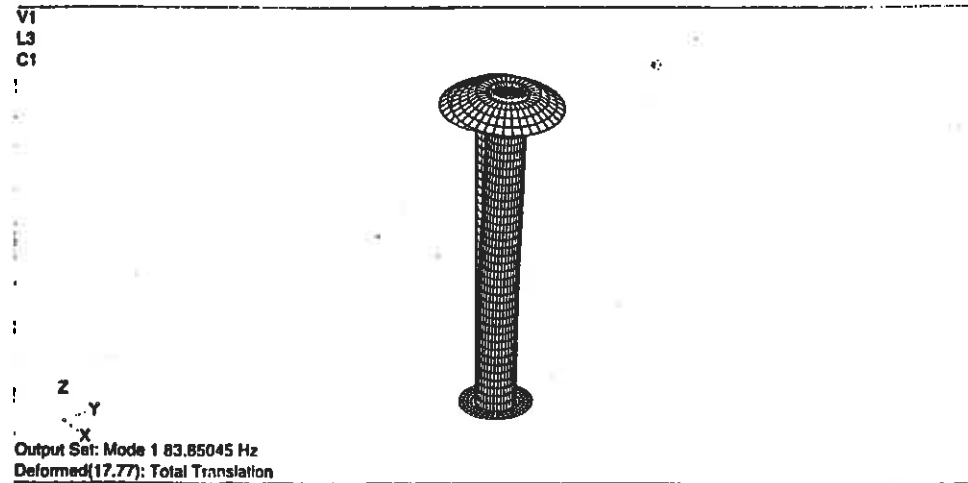
Layup: (0/60/0/-60)_s

Wall Thickness: 0.040 in.

Mast Height: 21.5 in.

Weight Estimate

Mast structure	.52 kg.
Ground plane & Antenna	.30 kg.
Coaxial cable	.27 kg.
ML insulation	.17 kg.
Total	1.26 kg.





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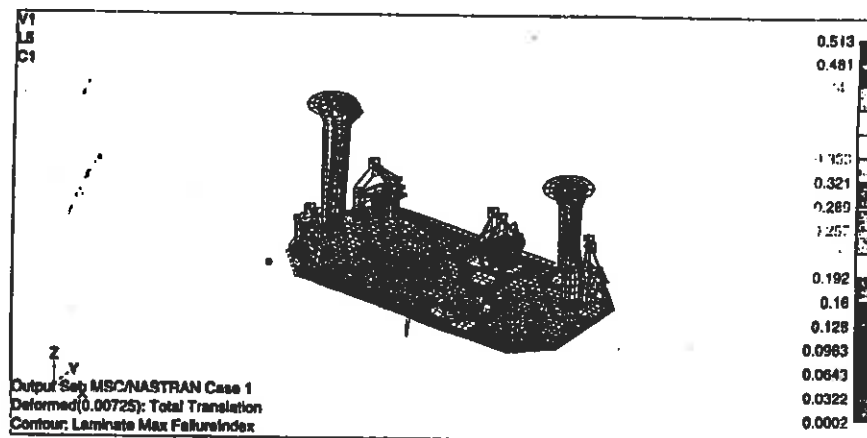
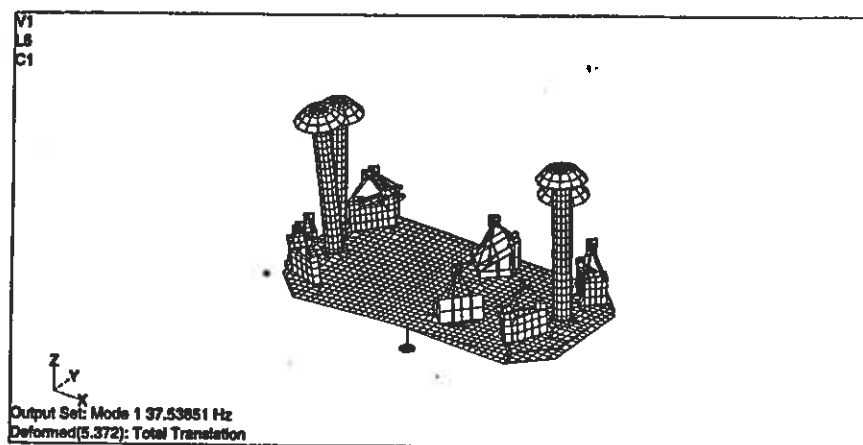


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Instrument Bench Orbit Configuration

Angular Distortion (arcseconds)

Error Type	Roll	Pitch	Yaw
1 g effect	27.4	25.6	2.2
Thermal			
Cold ($\beta = 88^\circ$)	34.3	39.2	4.7
Cold ($\beta = 0^\circ$)	34.6	38.6	5.2
Hot ($\beta = 88^\circ$)	35.9	36.7	7.3
Hot ($\beta = 0^\circ$)	36.1	36.3	7.8





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Structural Verification

Protoflight test program serves the purpose of both prototype and flight acceptance tests.

- **Structural Verification will be performed at the component, the assembly/ subsystem and at the system level. A bottoms up approach is used to screen out design flaws and infant mortality.**
- **Subsystem Level Tests**
 - Mechanical Functional
 - Sine Vibration
 - Random Vibration
 - Pyro-releases
 - Solar Panel Deployment
 - Static Load Test
- **Spacecraft Dynamic Tests**
 - Modal Survey
 - Sine Vibration
 - Acoustic
 - Pyro-shock clampband & release mechanisms



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Structural Verification - Spacecraft

- **Structural Verification** - A static load test will be performed on the primary structure. ·
(Draft of static load test procedure complete)
- **Modal Survey** - Experimental verification of the spacecraft's significant modes will be measured and correlated to the mathematical model
- **Vibration Test** - A sinusoidal test will be performed in accordance with the launch vehicle requirements
A test duration of 4.0 octaves per minute, with a tolerance of +/- 10% on the amplitude.
(No notching currently requested by spacecraft or instruments)
- **Acoustic Test** - Broad band reverberant field test, using the maximum expected flight level plus 3 dB.
The test duration is 60 seconds. A tolerance of +/-1.0 dB. on the overall sound pressure level, with +/- 3.0 dB. from 50 to 3000 Hz. Below 50 Hz and above 3000 Hz is based on capability of the test facility.
- **Pyrotechnic Shock** - Two live firings per device.



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Instrument / Subsystem Design Criteria

- **Load Factor:** Based on Instrument/Subsystem weight, the load will be applied individually along each of the three orthogonal axes of the subsystem at its center of gravity.

Subsystem Weight (lbs)	Load Factor
< 10	30
10 - 100	25
> 100	16

- **Frequency Constraints:**

	SABER	All other Instruments & Subsystems
Thrust axis	> 35 Hz	> 50 Hz.
Lateral axes	> 20 Hz.	> 30 Hz.

- **Pyro Shock: Requires Testing,**
 - Near field < 1.0 in, no pyro sensitive hardware should be mounted in this region
 - Mid field 1.0 to 6.0 in. requires two pyrotechnic firings

- **Min. Factors of Safety :** Same as spacecraft structure



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Instrument / Subsystem Dynamic Tests

Sinusoidal Vibration:

Test duration: 4.0 Octave / minutes

Test tolerance: +/- 10 % Amplitude, +/- 2% Frequency

	SABER		All other Instruments & Subsystems	
	f_n (Hz.)	Acceleration (g's)	f_n (Hz.)	Acceleration (g's)
Thrust Axis	5 - 9	0.50 in (DA)	5 - 24	.50 in (DA)
	9 - 100	2.0	24 - 80	15.5
			80 - 100	2.0
Lateral Axes	5 - 7.7	0.50 in (DA)	5 - 18	.50 in DA
	7.7 - 100	1.5	18 - 30	8.5
			30 - 100	1.4

* An alternative approach Sine Burst



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Instrument / Subsystem Dynamic Tests

Random Vibration:

Test duration : 1.0 min / axis

Test tolerance: +/- 3 dB. PSD, +/- 10% g_{rms} .

	Frequency (Hz.)	PSD Level ($G^2/Hz.$)
< 100 lbs.	20	.026
	50 - 800	.160
	2000	.026
	Overall Level 14.1 g_{rms}	
> 100 lbs.	20	.013
	50 - 800	.080
	2000	.013
	Overall Level 10.0 g_{rms}	

* An alternative approach force limiting



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Summary of Mass Properties

Item	Launch		On-Orbit	
	lb	kg		
Mass	1322.8	599.9		
Center of Gravity	in.	cm.	in.	cm.
CGx	.51	1.31	.51	1.31
CGy	1.95	4.95	1.95	4.95
CGz	39.4	100.2	38.4	97.4
Moment of Inertia	slug-ft²	kg-m²	slug-ft²	kg-m²
Ixx	225.9	306.3	243.9	330.7
Iyy	264.4	358.4	1155.3	1566.2
Izz	132.2	179.2	1011.4	1371.1
Product of Inertia	slug-ft²	kg-m²	slug-ft²	kg-m²
Pxy	1.28	1.74	1.28	1.74
Pxz	0.32	0.43	0.16	0.22
Pyz	1.07	1.45	0.47	0.63

*Properties about the spacecraft CG



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Weight Estimate (kg.)

	CoDR	PDR	CDR
Instruments	111.9	141.3	151.0
Power Subsystem	164.4	172.8	186.0
R F	8.2	4.3	4.2
Navigation	----	0.4	2.1
Attitude	36.3	55.6	60.4
IEM	24.0	26.8	27.7
Thermal	26.5	21.1	16.9
Harness	15.2	45.1	36.3
Primary Structure	154.7	84.4	88.9
Sec. Structure	--	29.8	26.7
Total	541.2	581.6	600.2
Margin %	21.9	13.4	10.0

10.3 ZENITH ANT. MAST #1	A-010	1.30	0.89	10	0.68	0.00	4.00	79.60	0.00	0.00	0.00	0.00	8.20	103.36	8237.13	8216.33
10.4 ZENITH ANT. MAST #2	A-011	1.30	0.89	10	0.68	25.00	4.00	79.60	0.00	0.00	0.00	32.60	6.20	103.36	8237.13	9028.63
10.5 NADIR ANT. MAST #1	A-008	1.80	0.68	16	0.78	-20.60	20.60	4.00	0.00	0.00	0.00	-30.78	30.78	6.00	654.38	654.38
10.6 NADIR ANT. MAST #2	A-009	1.80	0.68	16	0.78	20.60	-20.60	4.00	0.00	0.00	0.00	30.78	-30.78	6.00	654.38	654.38
10.7 UMBICAL CONN & BKT (2)	A-024	1.20	0.64	16	0.63	0.00	0.00	2.00	0.00	0.00	0.00	0.00	0.00	2.40	4.80	4.80
10.8 INSTRUMENT BENCH	A-015	16.30	8.30	10	9.13	-14.60	0.00	75.00	0.00	0.00	0.00	-265.35	0.00	1372.60	102937.60	106785.08
10.9 STAR CAMERA BKT. #1	A-017	1.30	0.89	10	0.65	-21.00	0.00	80.00	0.00	0.00	0.00	-27.30	0.00	104.00	8320.00	8893.30
10.10 STAR CAMERA BKT. #2	A-018	1.30	0.89	10	0.68	-7.60	0.00	80.00	0.00	0.00	0.00	-9.76	0.00	104.00	8320.00	8393.13
10.11 ARMING CONN.	A-022	1.15	0.62	16	0.60	-20.00	-18.60	59.00	0.00	0.00	0.00	-23.00	-21.28	67.85	4396.74	4463.16
10.12 TEST PT. CONN.	A-026	1.00	0.45	16	0.52	20.00	-19.00	57.50	0.00	0.00	0.00	20.00	-19.00	57.50	3647.26	3704.25
10.14 R W BKT #1	A-004	2.00	0.91	16	1.04	6.00	4.00	12.00	0.00	0.00	0.00	12.00	8.00	24.00	320.00	360.00
10.15 R W BKT #2	A-005	2.00	0.91	16	1.04	-6.00	4.00	12.00	0.00	0.00	0.00	-12.00	8.00	24.00	320.00	360.00
10.16 R W BKT #3	A-006	2.00	0.91	16	1.04	-6.00	16.60	12.00	0.00	0.00	0.00	-12.00	37.00	24.00	972.60	360.00
10.17 R W BKT #4	A-007	2.00	0.91	16	1.04	6.00	16.60	12.00	0.00	0.00	0.00	12.00	37.00	24.00	972.60	360.00
10.18 MISC. HARDWARE		8.00	2.27	16	2.41	0.00	0.00	36.00	0.00	0.00	0.00	0.00	0.00	190.00	7220.00	7220.00
10.19 SOLAR PNL. MOTOR BKT (->)	A-028	2.20	1.00	16	1.15	25.00	0.00	64.00	0.00	0.00	0.00	65.00	0.00	140.80	9011.20	10384.20
10.20 SOLAR PNL. MOTOR BKT (->)	A-029	2.20	1.00	16	1.16	-25.00	0.00	64.00	0.00	0.00	0.00	-65.00	0.00	140.80	9011.20	10384.20
10.21 SOLAR PNL. HOLD-DOWN BKTS (0)		3.00	1.36	10	1.60	25.00	0.00	28.00	0.00	0.00	0.00	75.00	0.00	84.00	2362.00	4227.00
10.22 SOLAR PNL. HOLD-DOWN BKTS (->)		3.00	1.36	10	1.60	-25.00	0.00	28.00	0.00	0.00	0.00	-75.00	0.00	84.00	2362.00	4227.00
10.23 PURGE SYSTEM		3.00	1.36	16	1.66	24.00	0.00	36.00	0.00	0.00	0.00	72.00	0.00	114.00	4332.00	6060.00
WT SUBTOTALS		1322.79	599.91		655.98							680.19	-2676.44	62180.11	3110140.99	3283520.03

TIMED MASS PROPERTIES (ABOUT S/C CG, WITHOUT CONTINGENCIES)

MAXIMUM LAUNCH WEIGHT 1466.0 (Lbs.) 660 (KG.)

CURRENT WEIGHT MARGIN = 10.02 %

WEIGHT (W/O CONTINGENCY) = 1322.79 LBS.

CGX =	0.61 in.	0.04 ft.	1.31 cm.
CGY =	-1.95 in.	-0.16 ft.	-4.96 cm.
CGZ =	39.45 in.	3.29 ft.	100.20 cm.
IXX =	1046776.49 lb-in**2	226.96 ft-lb	306.33 kg-m**2
IYY =	1224823.95 lb-in**2	264.40 ft-lb	358.43 kg-m**2
IZZ =	612207.43 lb-in**2	132.16 ft-lb	179.16 kg-m**2
PXY =	5929.46 lb-in**2	1.28 ft-lb	1.74 kg-m**2
PXZ =	-1475.74 lb-in**2	-0.32 ft-lb	-0.43 kg-m**2
PYZ =	4968.69 lb-in**2	1.07 ft-lb	1.45 kg-m**2