



# Solar Imaging Radio Array (SIRA)

**Mechanical**

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“When we ask for advice, we are usually looking for an accomplice.”

Marquis de la Grange (1639-1692)

Competition Sensitive





# Requirements / Objectives

I n t e g r a t e d   M i s s i o n   D e s i g n   C e n t e r

- **Mission unique bus structure**
- **12-18 micro-satellites required**
  - Separation system required
- **Comm:**
  - 0.5m x 0.5m flat phased array, articulated (cost)
  - **Ø0.5m dish antenna, fixed (mass)**
- **Propulsion**
- **ACS:**
  - **3-axis stabilized**
  - Possible momentum wheels – Dynacon MicroWheel 200
- **Power:**
  - 0.8m<sup>2</sup> minimum array area, **articulated**
- **Launch Vehicle:**
  - Delta II 2925-10 with **bi-prop fourth stage**
- **Operational Scenario:**
  - **BASELINE: Point antenna at earth, articulate solar array, triangle bus, 3 stacks of 6**
  - OPTION #1: Off point s/c to download data, triangle bus, 3 stacks of 6
  - OPTION #2: Spin s/c, comm antenna fixed on earth, hexagonal bus, 4 stacks of 4

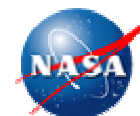




# Launch Vehicle

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<b>DELTA II</b>	<b>MASS (kg) TO ORBIT</b> (C3 ~ 0 km <sup>2</sup> /sec <sup>2</sup> )	<b>COST</b> <b>\$M FY02</b>
2920 - 10	625	67.0
2920H - 10	875	
2925-10	1240	
<b>2925H-10</b>	<b>1495</b>	<b>75.2</b>
2926-10	1085	
2926H-10	1315	





# Orbital Sciences MicroStar Bus (Former Proposals)

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## MicroStar™ Satellite Platform

### Technical Specifications

#### Core Bus Features

Bus Dry Mass.....	58.6 kg
Payload Mass Capability.....	68.0 kg
Redundancy.....	Single string
Orbit.....	700-1,000 km, all inclinations
Launch Vehicle Compatibility.....	Pegasus, Taurus, SELVIS I and II
Typical Mission Lifetime.....	3-5 years
Delivery.....	24 Months ARO

#### Structure

Bus Dimensions (Δ x H).....	104 x 16.5 cm
Payload Support Module Dimensions (Δ x H).....	104 x 33 cm
Construction.....	AlBeMet/Al Honeycomb
Shape.....	Dual-faced cylinder

#### Power Subsystem

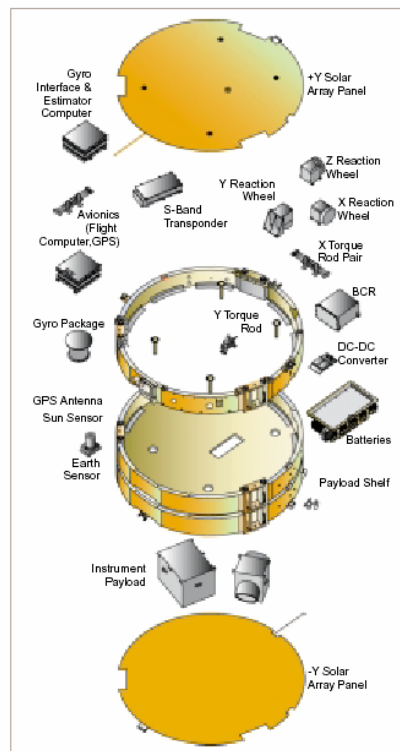
Payload Power.....	50 W orbit average
Bus Voltage.....	14 VDC unreg, 28 V reg
Solar Arrays.....	2 GaAs
Batteries.....	10 A*hr NiH <sub>2</sub> CPVs

#### Attitude Control Subsystem

Stability Mode.....	3-axis
Pointing Capabilities: Control.....	± 0.6°
Knowledge.....	< 1°
Rate/Stability.....	< 0.01°/sec

#### Command & Data Handling Subsystem

Flight Processor.....	68302
Rad Tolerant .....	15 K rad
Data Storage Capacity.....	3 MB
Interface Architecture.....	RS-422/RS-485
S-Band Uplink/Downlink Rates.....	2 Kbps/2 Mbps



### OPTIONS

- Custom structural ring configuration for flexible payload accommodations
- Increased power (up to 270W BOL) provided by second set of solar arrays for certain orbit/payload combinations
- 1553/1773 payload data interface to accommodate existing high-level interfaces
- Reduced pointing accuracy function (10° accuracy per axis) for missions requiring less precision
- Payload data storage enhancement (256 MB of storage)
- Propellant capacity of 26 kg hydrazine with 4 thrusters of 0.9 N each for orbit maintenance
- Mission operations and data delivery for two years



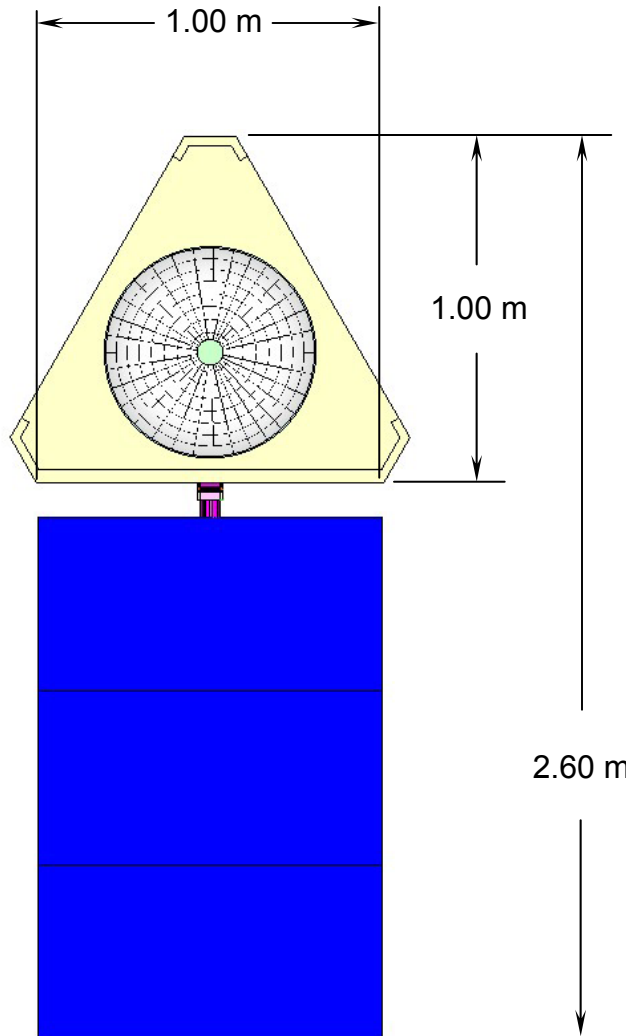
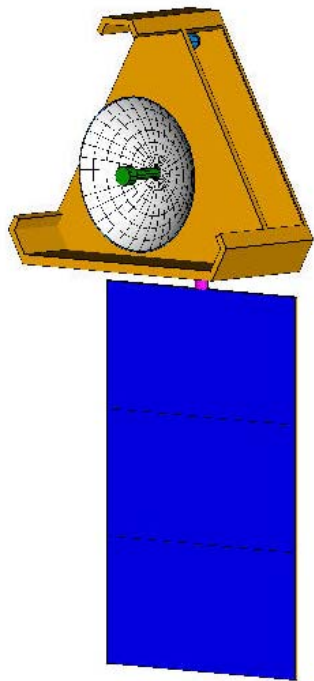


# S/C Configuration

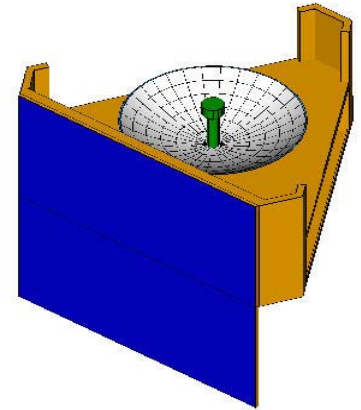
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## BASELINE

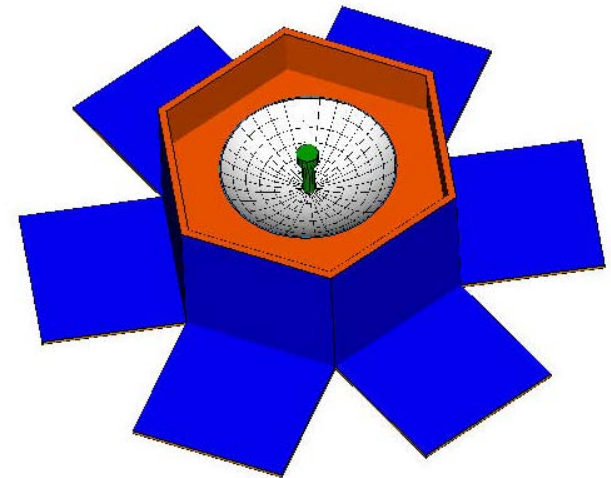
- Comm Antenna fixed on Earth
- Articulated Solar Array



## OPTION #1



## OPTION #2

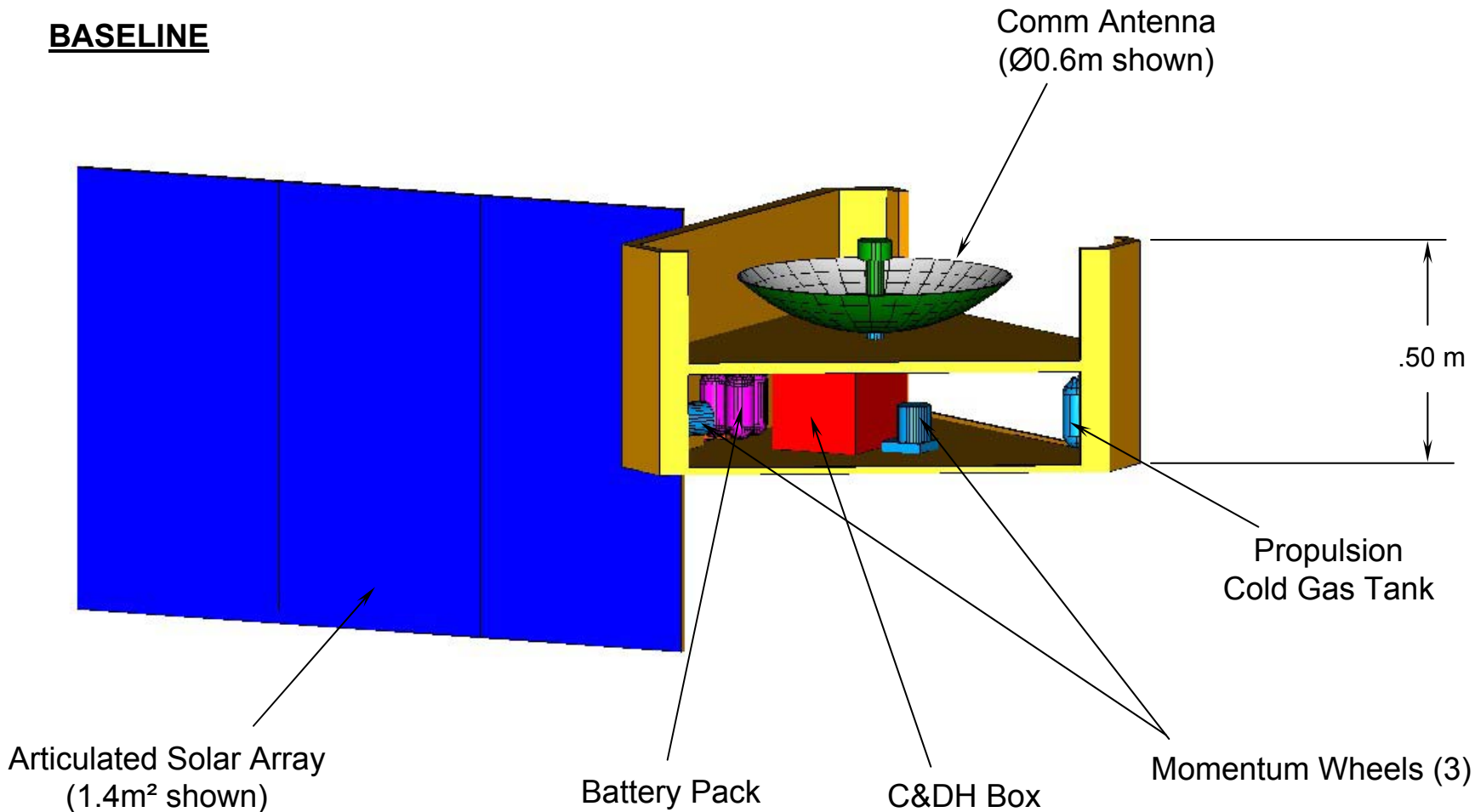




# S/C Component Layout

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## BASELINE

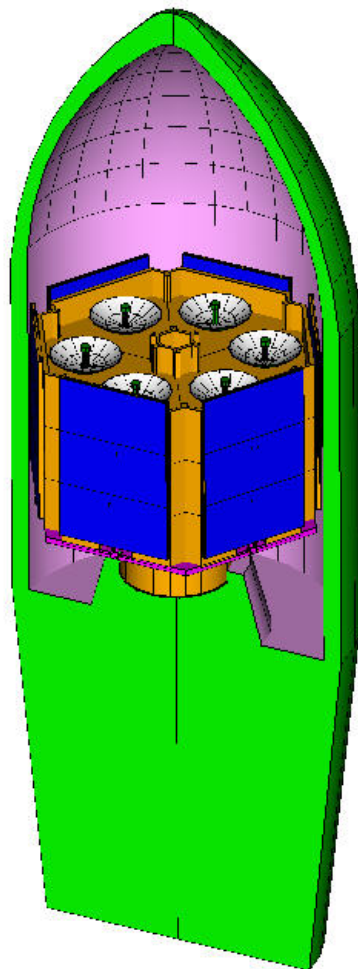
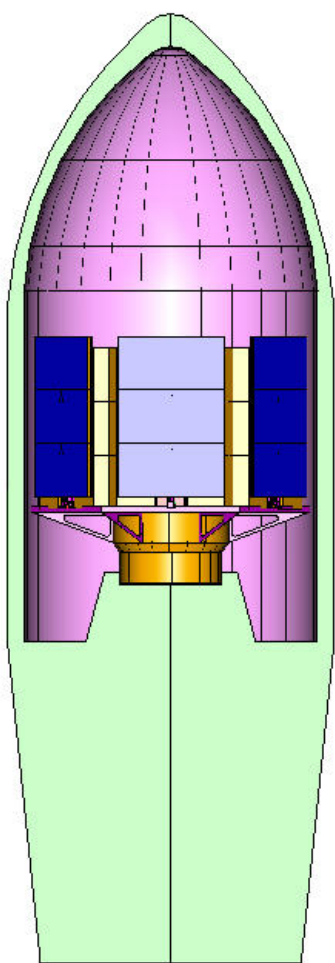




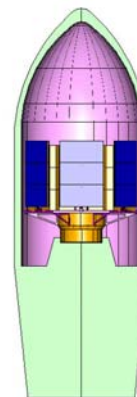
# Launch Configuration Delta II – 2925H-10

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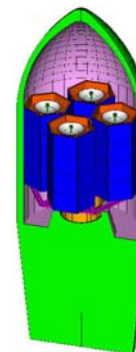
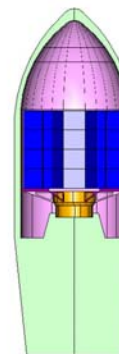
BASELINE



OPTION #1



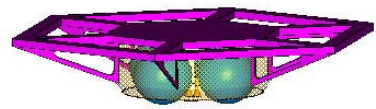
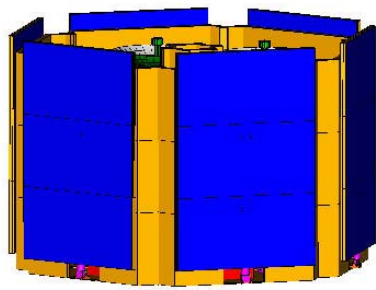
OPTION #2



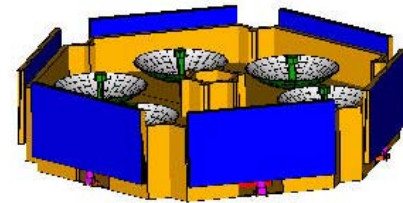
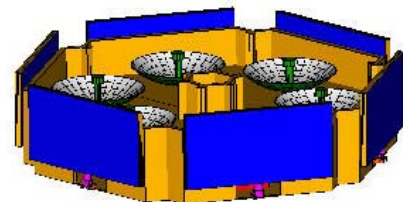
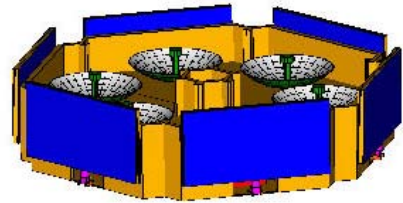


# Deploy Sequence

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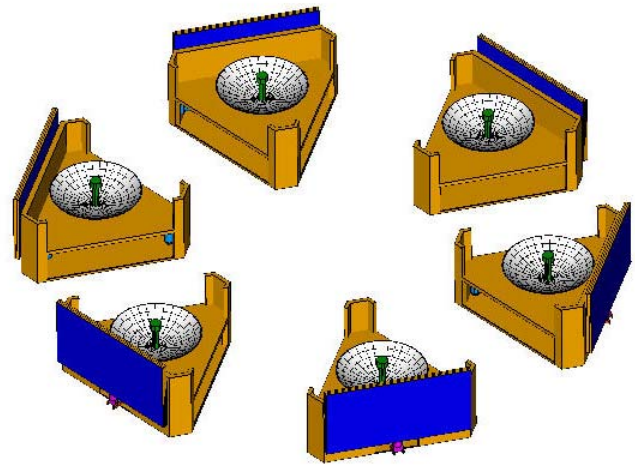
Separation of Fourth Stage



## Separation of Stacks

- Top layer forms top 1/3 of sphere
- Middle layer forms middle 1/3 of sphere
- Bottom layer forms bottom 1/3 of sphere

## Separation of MicroSats



Separation spring force adjusted to provide initial  $\Delta V$  to accomplish satellite placing on sphere







# Mass & Cost

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- **Propulsion Module**

- Mass – 87kg
- Cost – \$0.55M FY03

- **Spacecraft (structure, comm mounts, solar array)**

- Mass – 11.74kg
- Cost -
  - Copies 1-4 (ETU, Prototype, 2 flight units) - \$0.66M FY03
  - Copies 5-n – \$0.46M FY03

Option #2  
Most basic structure for  
mass and cost

- Delta

- Deployable solar array add (Option #3):

- 3.2kg
- Copies 1-4 (ETU, Prototype, 2 flight units) - \$0.04M FY03
- Copies 5-n – \$0.03M FY03

- **Deploy & articulate solar array add (BASELINE):**

- **12.6kg**
  - **The increase in mass is due to solar array deployment and articulation. The mass of the drive (9.3kg) is an average of several single axis drives. As the study refines a drive that will fit the mission requirements could be the MOOG type 2 or Ball EMS 221. These weigh-in at 3.0kg and 4.5kg respectively.**
- **Copies 1-4 (ETU, Prototype, 2 flight units) - \$0.70M FY03**
- **Copies 5-n – \$0.60M FY03**





# Risk

I n t e g r a t e d   M i s s i o n   D e s i g n   C e n t e r

## • Separation System

- Sep-systems have been utilized on spacecraft for many years. The likelihood of a sep-system failing is very small. However this risk is mentioned because of the number of separations required.
- Fall Back
  - Stack / Stack separation – try to re-initiate. Try separation of individual MicroSat.
  - MicroSat / MicroSat separation – try to re-initiate
- Consequence
  - Stack / Stack separation – loss of MicroSats in stack. Could be somewhat mitigated if the fall back plan is successful
  - MicroSat / MicroSat separation – loss of individual MicroSats

## • Solar Array

- Deployment of solar array. Again, solar array deployments are standard events. The likelihood of failure is very small. This risk is mentioned because of the number of deployments.
- Solar array drive failure. Again, solar array drives are standard mechanical systems on satellites. The likelihood of failure is very small. This risk is mentioned because of the number of drives.
- Consequence – partial to total loss of power to MicroSat.

